

# Multi-step methods, Adams-Bashforth

Note; they have to be started: not self starting as RK.

Advantage - they use previously calculated time steps. So, for one time step, only one calculation is needed, compared to  $N(4-5)-6...$  in R-K methods.

Disadvantage - they are less stable.

We derive explicit (Adams-Bashforth), but there are also implicit ones (Adams-Moulton).

IVP:  $\frac{dy}{dt} = f(y(t))$

~~Equation~~  $y(t_{n+1}) = y(t_n) + \int_{t_n}^{t_{n+1}} f(y(t)) dt$

The idea behind Adams methods is to approximate RHS integral using polynomial interpolation of  $f$  at the points  $t_{n+1-s}, t_{n+2-s} \dots t_n$  (explicit).

The interpolation polynomial is on  $s$  points, and of  $s-1$  order.

We will use Lagrange polynomials - natural choice for this kind of problems, when pairs  $(x_0, y_0), (x_1, y_1) \dots (x_k, y_k)$  are given.

# Lagrange\* polynomials:

\*(first discovered by Edward Waring)

Set of points  $(x_0, y_0), (x_1, y_1) \dots (x_k, y_k)$  (grid defined)

(1\*)  $L(x) = \sum_{j=0}^k y_j l_j(x)$  —  $L$ , interpolation polynomial

Where

$l_j$  —  $L$ . basis polynomials.

$l_j(x) = \prod_{\substack{0 \leq m \leq k \\ m \neq j}} \frac{x - x_m}{x_j - x_m}$  k factors, so  $l$  are k-order polynomials.

Property:

$l_{j \neq i}(x_i) = \prod_{\substack{0 \leq m \leq k \\ m \neq j}} \frac{x_i - x_m}{x_j - x_m} = 0$  (  $m=i$  gives  $x_i - x_i = 0$  )

$l_i(x_i) = \prod_{\substack{0 \leq m \leq k \\ m \neq i}} \frac{x_i - x_m}{x_i - x_m} = 1;$   
 $y_i l_i(x_i) = y_i$

Therefore, the sum (1\*) exactly interpolates the function defined by the set of the points.

Use it now.

2-step A-B method: IVP  $\frac{dy}{dt} = f(t, y(t))$

$$f(t_n, y(t_n)) = f_n$$

Given at  $(t_{n-1}, f_{n-1}), (t_n, f_n)$

find  $(t_{n+1}, f_{n+1}), y_{n+1}$ .

Assume  $t_{n+1} - t_n = t_n - t_{n-1} = \Delta t$

1st ~~order~~ order L.- interpolation polynomial

$$P(t) = f_n \frac{t - t_{n-1}}{t_n - t_{n-1}} + f_{n-1} \frac{t - t_n}{t_{n-1} - t_n}$$

Extrapolate onto  $n+1$ -th step:

$$\int_{t_n}^{t_{n+1}} f(y(t)) dt = \int_{t_n}^{t_{n+1}} P(t) dt$$

Substitute:

$$\int_{t_n}^{t_{n+1}} \left[ f_n \frac{t - t_{n-1}}{t_n - t_{n-1}} + f_{n-1} \frac{t - t_n}{t_{n-1} - t_n} \right] dt =$$

$$= \int_{t_n}^{t_{n+1}} \left[ f_n \frac{t - t_{n-1}}{\Delta t} - f_{n-1} \frac{t - t_n}{\Delta t} \right] dt =$$

$$\frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} [f_n t - f_{n-1} t - f_n t_{n-1} + f_{n-1} t_n] dt =$$

(4)

$$\begin{aligned}
&= \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} t (f_n - f_{n-1}) dt + \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} (f_{n-1} t_n - f_n t_{n-1}) dt = \\
&= \frac{1}{\Delta t} \frac{t_{n+1}^2 - t_n^2}{2} (f_n - f_{n-1}) + \frac{1}{\Delta t} (f_{n-1} t_n - f_n t_{n-1}) \underbrace{(t_{n+1} - t_n)}_{\Delta t} = \\
&= \frac{(t_{n+1} + t_n)(f_n - f_{n-1})}{2} + (f_{n-1} t_n - f_n t_{n-1}) =
\end{aligned}$$

$$= \frac{1}{2} t_{n+1} f_n + \frac{1}{2} t_n f_n - \frac{1}{2} t_{n+1} f_{n-1} - \frac{1}{2} t_n f_{n-1} + \underbrace{f_{n-1} t_n - f_n t_{n-1}} =$$

$$= f_n \left( \frac{1}{2} t_{n+1} + \frac{1}{2} t_n - t_{n-1} \right) - f_{n-1} \left( \frac{1}{2} t_{n+1} + \frac{1}{2} t_n - t_n \right) =$$

$$= \frac{1}{2} f_n \left( \underbrace{t_{n+1} + t_n - t_{n-1} - t_{n-1}}_{\Delta t} \right) - \frac{1}{2} f_{n-1} (t_{n+1} - t_n) =$$

$$= \frac{3}{2} f_n \Delta t - \frac{1}{2} f_{n-1} \Delta t = \frac{\Delta t}{2} (3 f_n - f_{n-1})$$

$$\text{So, } y_{n+1} = y_n + \frac{\Delta t}{2} (3 f_n - f_{n-1}) \quad \boxed{AB2}$$

Higher orders are derived in the same fashion, but the integrals are longer.

AB3

$$y_{n+1} = y_n + \frac{\Delta t}{12} (23f_n - 16f_{n-1} + 5f_{n-2})$$

AB4

$$y_{n+1} = y_n + \left( \frac{55}{24} f_n - \frac{59}{24} f_{n-1} + \frac{37}{24} f_{n-2} - \frac{3}{8} f_{n-3} \right)$$

AB5

$$y_{n+1} = y_n + \left( \frac{1901}{720} f_n - \frac{1387}{360} f_{n-1} + \frac{109}{30} f_{n-2} - \frac{637}{360} f_{n-3} + \frac{251}{720} f_{n-4} \right)$$

- AB is linear, as a linear combination of the previous steps is used.
- Bashforth has nothing to do with numerics, he was HD-mathematician. Adams developed both explicit & implicit methods.
- Non-linear multistep methods exist.
- AB has to be started with the same-order selfstarting method.

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Generally, multistep methods are good for stiff equations (see homework)

Stiffness has no "exact" definition, but it is when there are terms in equations ~~that~~ which can lead to rapid variation of the solution. HD eq-s are stiff.