

Consistency

a numerical method $A^h V^h = F^h$ is consistent with PDE $Lu = f$

$$\text{if } \lim_{h \rightarrow 0} T^h = 0 ;$$

order of consistency q if $T = O(h^q)$

Relation between T^h & E^h :

$$T^h = A^h U^h - F^h$$

subtract: $A^h V^h = F^h$; $0 = A^h V^h - F^h$

$$T^h = A^h (U^h - V^h) ; U^h - V^h = E^h$$

$$T^h = A^h E^h$$

$$\left\| (A^h)^{-1} \left[A^h E^h = T^h \right] \right\|_p =$$

$$= \|E^h\|_p = \|(A^h)^{-1}\|_p \|T^h\|_p$$

p -norm:
 $\|x\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p}$
 $p=1$ "Taxicab"
 $p=2$ Euclidean

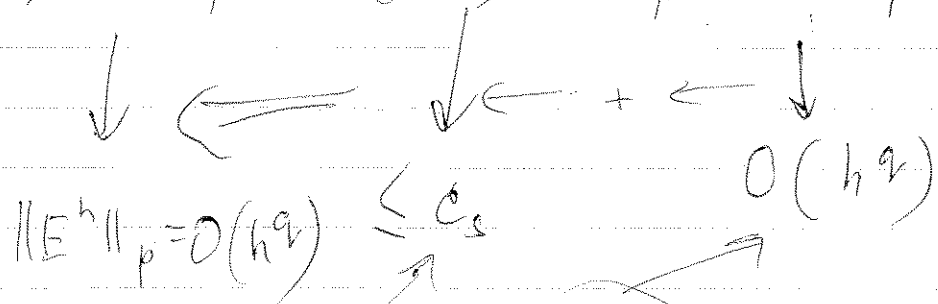
If we know that a numerical method is consistent, i.e. $T^h = O(h)$ at least, then

if exists c so that $\|(A^h)^{-1}\|_p \leq c$ ($c \neq c(h)$)

$A^h V^h = F^h$ is stable

Lax convergence theorem:

$$\|E^h\|_p = \|(A^h)^{-1}\|_p \|T^h\|_p$$



If the method is consistent with order q in the p -norm and stable in the p -norm, then the method is convergent with the order q .

(Fundamental theorem of finite difference methods)

Note: E^h converges with the same order as T^h . T^h can be used to obtain order of convergence.

Example:

$$T_i^h = \frac{1}{12} h^2 \frac{\partial^4 u}{\partial x^4} + O(h^3) = O(h^2)$$

can be shown!
 $T_i = \frac{1}{12} h^2 u^{(4)}(x_i)$

①

consistent with the order 2 with our problem.

Assume $C_T = \max_{x \in [0,1]} |u^{(4)}(x)|$

$$T_i \leq \frac{1}{12} h^2 C_T$$

2-norm

$$\begin{aligned} \|T^h\|_2 &= \sqrt{h} \sqrt{\sum_{i=1}^m (T_i)^2} \leq \sqrt{h} \sqrt{m \left(\frac{1}{12} h^2 C_T\right)^2} \leq \\ &\leq \sqrt{h} \sqrt{(m+1) \left(\frac{1}{12} h^2 C_T\right)^2} \end{aligned}$$

$$h = \frac{1}{m+1} \text{ (from BVP definition)}$$

∴

$$\|T^h\|_2 \leq \frac{1}{12} h^2 C_T$$

∴

$$\|T^h\|_2 = O(h^2)$$

/ consistent

②. Stability:

1) A^h is symmetric $\Rightarrow (A^h)^{-1}$ is symmetric too:

$$A^h = (A^h)^T \Rightarrow (A^h)^{-1} = ((A^h)^{-1})^T$$

Spectral radius of A , $\rho(A) = \max_{1 \leq i \leq m} |\lambda_i|$,

where λ_i - eigenvalues of A given by $\det(A - \lambda I) = 0$

$$(A - \lambda I) \vec{v} = 0$$

It can be shown that if $A = A^T$, $\|A\|_2 = \rho_A$

$$\left(\text{2-norm } \|A\|_2 = \sqrt{\rho(AA^T)} = \sqrt{\rho(A^T A)} \right)$$

$$\text{So, } \|(A^h)^{-1}\|_2 = \rho((A^h)^{-1})$$

2) If A^h is invertible and has eigenvalues $\lambda_1, \dots, \lambda_m$,

$(A^h)^{-1}$ has eigenvalues $\frac{1}{\lambda_1}, \dots, \frac{1}{\lambda_m}$

$$A \vec{v} = \lambda \vec{v} \quad | \text{ mult. by } \frac{A^{-1}}{\lambda} \Rightarrow \frac{1}{\lambda} \vec{v} = A^{-1} \vec{v}$$

which implies that $\frac{1}{\lambda}$ are eigenvalues.

Using 1) and 2),

$$\|(A^h)^{-1}\|_2 = \rho((A^h)^{-1}) = \max_{1 \leq i \leq m} \left| \frac{1}{\lambda_i} \right| = \left(\min_{1 \leq i \leq m} |\lambda_i| \right)^{-1}$$

Need eigenvalues for A .

Sturm-Liouville problem.
(discrete)

* Note: solution is a sum of eigenfunctions; solution depends on how they behave

Need eigenvalues for A .

$$A^\lambda = \frac{1}{h^2} \begin{pmatrix} -2 & 1 & 0 & \dots & 0 \\ 1 & -2 & 1 & \dots & 0 \\ \vdots & & & & \\ 0 & & & -1 & -2 \end{pmatrix}$$

$$Au = \lambda u$$

one of the equations $u_{j-1} - 2u_j + u_{j+1} = \lambda u_j$

It can be shown that for A_h^λ eigenvalues are

$$\lambda_k = \frac{2}{h^2} (\cos(k\pi h) - 1), \quad k = 1, \dots, m$$

$$h = \frac{1}{m+1}$$

λ_1 's smallest when $k=1$ (argument of \cos is smallest, $\cos \rightarrow 1$)

Expand $\cos(k\pi h)$ around $k=1$

$$\cos(\pi h) = 1 - \frac{1}{2} \pi^2 h^2 + \frac{1}{24} \pi^4 h^4 \cos(\pi \xi)$$

where $\xi \in [0, h]$

Substitute $\cos(\pi h)$ in λ_k :

$$\begin{aligned} \lambda_1 &\approx \frac{2}{h^2} \left(-\frac{1}{2} \pi^2 h^2 + \frac{1}{24} \pi^4 h^4 \cos(\pi \xi) \right) = \\ &= -\pi^2 + \frac{1}{12} \pi^4 h^2 \cos(\pi \xi) \end{aligned}$$

$|\lambda_1| \approx \pi^2$ independent on h for sufficiently small h .

①

So

$$\frac{1}{\pi^2} \approx \|(A^h)^{-1}\|_2 = \frac{1}{|\lambda_1|}$$

So the method is stable.

Therefore ~~the~~ by Lax convergence, the method A is convergent with order 2 in the 2-norm:

$$\|E^h\|_2 = O(h^2)$$

⊗ Note, higher-order methods can be developed.

Few notes:

① Sometimes, solving $Lu = f$, where L is elliptic is complicated.

There are relaxation methods:

$$Lu - f = 0 \implies \frac{\partial u}{\partial t} = Lu - f$$

u relaxes to equilibrium solution with $t \rightarrow \infty$.

② Wave equation:

$$\frac{\partial^2 u}{\partial t^2} = v^2 \frac{\partial^2 u}{\partial x^2}$$

can be discretised directly.

But

$$\frac{\partial^2 u}{\partial t^2} - v^2 \frac{\partial^2 u}{\partial x^2} = 0 \text{ is } L_1 L_2 u = 0,$$

$$\text{and } L_1 = \frac{\partial}{\partial t} + v \frac{\partial}{\partial x}; L_2 = \frac{\partial}{\partial t} - v \frac{\partial}{\partial x}$$

$$w = L_2 u \implies$$

$$L_2 u = w$$

$$L_1 w = 0.$$

Or, in matrix form

$$\frac{\partial}{\partial t} \begin{bmatrix} u \\ w \end{bmatrix} + \begin{bmatrix} -v & 0 \\ 0 & v \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} u \\ w \end{bmatrix} = \begin{bmatrix} w \\ 0 \end{bmatrix}$$

Which gives a "flux-conservative" equation

$$\frac{\partial \vec{u}}{\partial t} - \frac{\partial \vec{F}(\vec{u})}{\partial x} = 0 \text{ or } \vec{\nabla} \cdot \vec{F}(\vec{u}) = 0$$

(Here, all 1D-equations are!)

Prototype:

$$\frac{\partial u}{\partial t} + v \frac{\partial u}{\partial x} = 0.$$

Note, linear!

Let's look at temporal discretisation!

explicit

computes $n+1$ state from $n, n-1, n-2, \dots$

cheaps, but unstable

implicit

computes $n+1$ state from $n+1, n, n-1, n-2, \dots$

leads to system of eqs => expensive more stable (largest)
