

1. We start with the distribution function f defined in 6-d space of coordinates + momenta

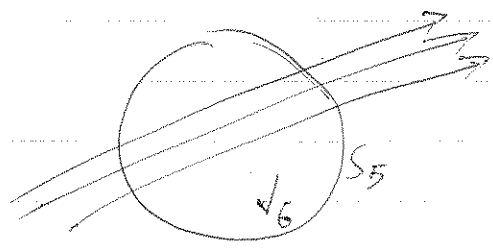
$$f(\vec{r}, \vec{p}, t) = f(r_i, p_i, t)$$

Full differential

$$df = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial r_i} dr_i + \frac{\partial f}{\partial p_i} dp_i, \text{ or}$$

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial r_i} \frac{dr_i}{dt} + \frac{\partial f}{\partial p_i} \frac{dp_i}{dt}$$

$$v_i = \frac{p_i}{m} \quad F_i = a_i \cdot m \quad ; \quad m - \text{particle mass}$$



V_6 - arbitrary volume bounded by S_5

We can write Gauss theorem $\left(\int_V (\vec{F} \cdot \vec{F}) dV = \int_S (\vec{F} \cdot \vec{n}) dS \right)$
 \vec{F} - cont. diff vector field

$$\frac{\partial}{\partial t} \int_{V_6} f dV_6 + \oint_{S_5} f v_i n_i dS_5 = 0 \quad - \text{conservation of particle number}$$

$$\frac{\partial}{\partial t} \int_{V_6} f dV_6 + \int_{V_6} \frac{\partial}{\partial x_i} (f v_i) dV_6 = 0$$

V_6 - arbitrary, in $\mathbb{R}^n, n=6$

so

$$\boxed{\frac{\partial f}{\partial t} + \frac{\partial}{\partial x_i} (f \cdot v_i)} = 0 \quad \text{①}$$

Splitting (1) in x and v components:

$$\frac{\partial}{\partial t} f + \frac{\partial}{\partial x_i} \left(f \cdot \frac{dx_i}{dt} \right) + \frac{\partial}{\partial p_i} \left(f \cdot \frac{dp_i}{dt} \right) = 0.$$

$$f \equiv f(x_i, p_i, t)$$

(Liouville equation)

Opening derivatives gives:

$$\frac{\partial}{\partial t} f + \frac{dx_i}{dt} \frac{\partial f}{\partial x_i} + \frac{dp_i}{dt} \frac{\partial f}{\partial p_i} + f \left[\frac{\partial}{\partial x_i} \frac{dx_i}{dt} + \frac{\partial}{\partial p_i} \frac{dp_i}{dt} \right] = 0$$

Proof that the last bracket is eq to 0:

Assume closed system, write Hamiltonian:

$$\dot{x}_i = \frac{\partial H}{\partial p_i}; \quad \dot{p}_i = - \frac{\partial H}{\partial x_i}$$

$$\frac{\partial}{\partial x_i} \frac{\partial H}{\partial p_i} - \frac{\partial}{\partial p_i} \frac{\partial H}{\partial x_i} \equiv 0;$$

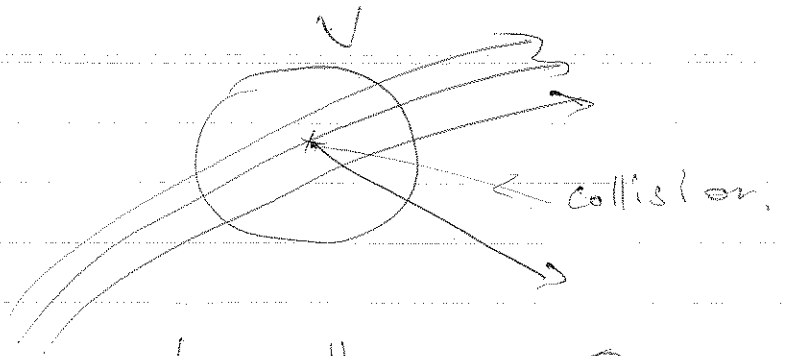
Interestingly, the bracket is GD-divergence of GD-flow in phase space.

Liouville equation now:

$$\frac{\partial f}{\partial t} + v_i \frac{\partial f}{\partial x_i} + F_i \frac{\partial f}{\partial p_i} = 0.$$

Collisions change i.

(3)



$$\frac{\partial f}{\partial t} + v_i \frac{\partial f}{\partial x_i} + F_i \frac{\partial f}{\partial p_i} = \left(\frac{\partial f}{\partial t} \right)_{\text{coll}} \quad \text{— formally.} \quad (*)$$

(Boltzmann equation)

WE WANT TO GET RID OF VELOCITY PART IN (*).
WE INTEGRATE (*) OVER AN ARBITRARY VOLUME
IN V-SPACE $d^3\vec{v}$.

WE ALSO MULTIPLY (*) BY SOME FUNCTION OF \vec{v} ,
 $\chi(\vec{v})$

$$\chi = \chi(\vec{v})$$

$$\frac{\partial f}{\partial t} + \vec{v} \cdot \nabla f + \vec{F} \cdot \nabla_p f = \left(\frac{\partial f}{\partial t} \right)_{\text{coll}}$$

⇓

$$\underbrace{\int \chi \frac{\partial f}{\partial t} d^3 \vec{v}}_{[1]} + \underbrace{\int \chi \vec{v} \cdot \nabla f d^3 \vec{v}}_{[2]} + \underbrace{\int \chi \vec{F} \cdot \nabla_p f d^3 \vec{v}}_{[3]} = \underbrace{\int \chi \left(\frac{\partial f}{\partial t} \right)_{\text{coll}} d^3 \vec{v}}_{[4]}$$

$$[1] \int \chi \frac{\partial f}{\partial t} d^3 v = \frac{\partial}{\partial t} \int \chi f d^3 v - \int \frac{\partial \chi}{\partial t} f d^3 v$$

$$\Rightarrow \left(\chi = \chi(\vec{v}) \Rightarrow \frac{\partial \chi}{\partial t} = 0 \right)$$

$$\boxed{\int \chi \frac{\partial f}{\partial t} d^3 v = \frac{\partial}{\partial t} \int \chi f d^3 v}$$

$$[2] \int \chi \vec{v} \cdot \nabla f d^3 \vec{v} = \nabla \cdot \int \chi v f d^3 \vec{v} - \int \chi v \cdot \nabla \chi d^3 \vec{v} - \int f v \cdot \nabla \chi d^3 \vec{v} = 0$$

$$\chi = \chi(\vec{v}) \Rightarrow \nabla \chi = 0$$

$$\vec{v} = \frac{\vec{p}}{m} \Rightarrow v \cdot \vec{v} = 0$$

$$\int \chi \vec{v} \cdot \nabla f d^3 \vec{v} = \nabla \cdot \int \chi v f d^3 \vec{v}$$

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$$\int \chi \vec{F} \cdot \nabla_p f d^3 \vec{v} =$$

$$= \underbrace{\int \nabla_p \cdot (\vec{F} \chi f) d^3 \vec{v}}_{\textcircled{1}} - \underbrace{\int \chi f (\nabla_p \cdot \vec{F}) d^3 \vec{v}}_{\textcircled{2}} - \underbrace{\int f (\vec{F} \cdot \nabla_p) \chi d^3 \vec{v}}_{\textcircled{3}}$$

① $\int \nabla_p \cdot (\vec{F} \chi f) d^3 v = F \chi f |_{v \rightarrow \infty}$
 exact differential

~~INTEGRATING VOLUME IS ARBITRARY~~

INTEGRATING VOLUME IS ARBITRARY, so $v \rightarrow \infty$

WITH $v \rightarrow \infty$ $f \rightarrow 0$ (no infinitely fast particles),
 so $\int = 0$.

② Need an assumption on force.

Say $F = m \vec{g}$, $\vec{g} = \vec{g}(\vec{x})$

$\nabla_p \vec{g} = 0$

$\int = 0$

$$\int \chi \vec{F} \cdot \nabla_p f d^3 v = - \int f (\vec{F} \cdot \nabla_p) \chi d^3 \vec{v}$$

4 Collision term:

$$\int \chi \left(\frac{\partial f}{\partial t} \right)_{\text{coll}} d\vec{v} = \frac{\partial}{\partial t} \int \chi f|_{\text{coll}} d\vec{v} - \int f \frac{\partial \chi}{\partial t} d\vec{v}$$

$\frac{\partial \chi}{\partial t} = 0$ as $\chi = \chi(\vec{v})$

$$\int \chi \left(\frac{\partial f}{\partial t} \right)_{\text{coll}} d\vec{v} = \frac{\partial}{\partial t} \int \chi f|_{\text{coll}} d\vec{v}$$

All together:

$$\frac{\partial}{\partial t} \int \chi f d^3\vec{v} + \nabla \cdot \int \chi \vec{v} f d^3\vec{v} - \int f (\mathbf{F} \cdot \nabla_p) \chi d^3\vec{v} = \frac{\partial}{\partial t} \int \chi f|_{\text{coll}} d\vec{v} \quad (A)$$

Define average value of χ , $\langle \chi \rangle$ as

$$\langle \chi \rangle = \frac{1}{n} \int \chi f d^3v, \text{ or}$$

$$n \langle \chi \rangle = \int \chi f d^3v$$

$$n \langle \chi v \rangle = \int \chi \vec{v} f d^3v$$

$$n \langle (\mathbf{F} \cdot \nabla_p) \chi \rangle = \int f (\mathbf{F} \cdot \nabla_p) \chi d^3v$$

Generalised Transport Equation:

$$\frac{\partial}{\partial t} (n \langle \chi \rangle) + \nabla \cdot (n \langle \chi v \rangle) - n \langle (\mathbf{F} \cdot \nabla_p) \chi \rangle = \frac{\partial}{\partial t} (n \langle \chi \rangle|_{\text{coll}})$$

We will need "Reynolds Decomposition"

Bulk Velocity $\vec{u} = \langle \vec{v} \rangle$, "macroscopic"

$\vec{v} = \vec{u} + \vec{c}$, where \vec{c} - fluctuation
"microscopic"

$$\langle \vec{c} \rangle = 0.$$

$$\langle \vec{v} \rangle = \langle \vec{u} + \vec{c} \rangle$$

$$\chi = m \quad \nabla_{\perp} \chi = 0$$

$$\frac{\partial}{\partial t} (nm) + \nabla \cdot (n \langle m \vec{v} \rangle) = \frac{\partial}{\partial t} (nm) \Big|_{\text{col.}}$$

$$\rho = n \cdot m$$

$$\frac{\partial}{\partial t} \rho + \nabla \cdot (\rho \vec{u}) = S$$

continuity equation

$$X = m\vec{v} \quad (X = f(\vec{v}))$$

$$\frac{\partial}{\partial t} (\rho \langle \vec{v} \rangle) + \nabla \cdot (\rho \langle \vec{v} \vec{v} \rangle) - \rho \langle (\vec{F} \cdot \nabla_p) \vec{v} \rangle = \frac{\partial}{\partial t} (\rho \langle \vec{v} \rangle) \Big|_{coll}$$

$$\frac{\partial}{\partial t} (\rho \langle \vec{v} \rangle) = \frac{\partial}{\partial t} (\rho \vec{u})$$

$$\begin{aligned} \nabla \cdot (\rho \langle \vec{v} \vec{v} \rangle) &= \nabla \cdot (\rho (\vec{u}\vec{u} + \cancel{\vec{u}\langle c \rangle} + \cancel{\langle c \rangle \vec{u}} + \langle c c \rangle)) = \\ &= \nabla \cdot (\rho \vec{u}\vec{u}) + \nabla \cdot (\rho \langle c c \rangle) \end{aligned}$$

$$- \rho \langle (\vec{F} \cdot \nabla_p) \vec{v} \rangle = (\text{assume constant})$$

$$\begin{aligned} &= - \rho \langle (F_x \hat{i} + F_y \hat{j} + F_z \hat{k}) \left(\frac{\partial}{\partial v_x} \hat{i} + \frac{\partial}{\partial v_y} \hat{j} + \frac{\partial}{\partial v_z} \hat{k} \right) \vec{v} \rangle / m = \\ &= - \frac{\rho}{m} \langle F_x \frac{\partial}{\partial v_x} + F_y \frac{\partial}{\partial v_y} + F_z \frac{\partial}{\partial v_z} \rangle \vec{v} = \\ &= - \frac{\rho}{m} \langle F_x \hat{i} + F_y \hat{j} + F_z \hat{k} \rangle = - \frac{\rho}{m} \langle \vec{F} \rangle \quad (F = m\vec{g}) \\ &= \rho \vec{g} \end{aligned}$$

Coll. term:

$$\frac{\partial}{\partial t} (\rho \langle \vec{v} \rangle) \Big|_{coll} = \frac{\partial}{\partial t} \rho u \Big|_{coll} = \vec{A} \quad \left(\begin{array}{l} \text{Zero actually.} \\ \text{momentum is} \\ \text{conserved in closed} \\ \text{system.} \end{array} \right)$$

So:

$$\frac{\partial}{\partial t} (\rho \vec{u}) + \nabla \cdot (\rho \vec{u}\vec{u}) + \nabla \cdot (\rho \langle c c \rangle) - \frac{\rho}{m} \langle F \rangle = \vec{A}$$

$\nabla \cdot (\rho \langle c c \rangle)$
Stress tensor. σ

$$\frac{\partial}{\partial t} (\rho \vec{u}) + \nabla \cdot (\rho \vec{u}\vec{u}) + \nabla \cdot \sigma - \frac{\rho}{m} \langle F \rangle = \vec{A}$$

Momentum equation

A few words on the stress tensor:

① coming from microscopic scales, affects macroscopic

Formally: $\underline{\underline{\sigma}} = \begin{pmatrix} \pi & 0 & 0 \\ 0 & \pi & 0 \\ 0 & 0 & \pi \end{pmatrix} + \begin{pmatrix} \sigma_{xx} - \pi & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & \sigma_{yy} - \pi & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_{zz} - \pi \end{pmatrix} =$

$= -\pi \mathbb{I} + \underline{\underline{\tau}}$

mechanical pressure (scalar) Stress tensor

$$\pi = \frac{1}{3}(\sigma_{xx} + \sigma_{yy} + \sigma_{zz})$$

③ Stress tensor is a very complex thing. Different "types" (or simplifications) of fluids exist.

Newtonian observation:
(viscous stress is linearly proportional to "shear")

$$\tau = \mu \frac{du}{dy} \text{ - by Newton}$$

$$\tau_{ij} = \mu \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$$

$$\sigma_{ij} = p \delta_{ij} - \mu \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$$

non-Newtonian

When this does not work. Even more complex behaviour.

Different - microscopic - physics.

CITE:

$$\frac{\partial}{\partial t} (n \langle X \rangle) + \nabla \cdot (n \langle X \vec{v} \rangle) - n \langle (\mathbf{F} \cdot \nabla_p) X \rangle = \frac{\partial}{\partial t} (n \langle X \rangle)_{\text{coll}}$$

$$X = \frac{1}{2} m (\vec{v} \cdot \vec{v}) = \frac{1}{2} m v^2$$

$$\begin{aligned} \nabla_p X &= \frac{1}{m} \nabla_p X = \frac{1}{m} \left(m \nabla (\vec{v} \cdot \vec{v}) \frac{1}{2} \right) = \\ &= \frac{1}{2} 2 (\vec{v} \cdot \nabla_p) \vec{v} = \vec{v} \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial t} \left(\frac{1}{2} \rho \langle v^2 \rangle \right) + \nabla \cdot \left(\frac{1}{2} \rho \langle v^2 \vec{v} \rangle \right) - n_a \langle (\mathbf{F} \cdot \nabla_p) \left(\frac{1}{2} m v^2 \right) \rangle &= \\ &= \frac{\partial}{\partial t} \left(\frac{1}{2} \rho \langle v^2 \rangle \right)_{\text{coll}} = M_{\text{E}} \\ &\rightarrow 0 \text{ (energy conservation)} \end{aligned}$$

$$\nabla \cdot \left(\frac{1}{2} \rho \langle (v \cdot v) \vec{v} \rangle \right) = \quad (v = u + c)$$

$$= \nabla \cdot \left(\frac{1}{2} \rho \langle (\vec{u}^2 + 2\vec{u}\vec{c} + \vec{c}^2) (\vec{u} + \vec{c}) \rangle =$$

$$= \nabla \cdot \left(\frac{1}{2} \rho \left(\langle u^2 \vec{u} \rangle + \langle u^2 \vec{c} \rangle + \langle 2u \vec{c} \vec{u} \rangle + \langle 2u \vec{c} \vec{c} \rangle + \langle c^2 \vec{u} \rangle + \langle c^2 \vec{c} \rangle \right) =$$

$$= \nabla \cdot \left(\underbrace{\frac{1}{2} \rho \langle u^2 \vec{u} \rangle}_{\text{kinetic energy}} + \underbrace{\frac{1}{2} \rho \langle c^2 \vec{u} \rangle + \rho \langle \vec{c} \vec{c} \rangle \cdot \vec{u}}_{\text{mechanical pressure } \pi \text{ (diagonal of } \sigma)} + \underbrace{\frac{\rho}{2} \langle c^2 \vec{c} \rangle}_{\text{Heat flux } q = \frac{1}{2} \rho \langle c^2 \vec{c} \rangle} \right)$$

(Thermodynamical $\gamma = \frac{d+2}{d}$, where $d=3$ - dimensionality of space.)

$$\frac{1}{\gamma-1} \pi + \frac{1}{2} \rho u^2 = \epsilon \quad \text{- Energy density,}$$

$$n \langle X \rangle = \frac{1}{2} \rho \langle c^2 \rangle + \frac{1}{2} \rho u^2 = \frac{1}{\gamma-1} \pi + \frac{1}{2} \rho u^2, \quad \left[\frac{\partial n \langle X \rangle}{\partial t} = \frac{\partial \epsilon}{\partial t} \right]$$

$$\frac{\partial \epsilon}{\partial t} + \nabla \cdot (\epsilon \vec{u}) + \nabla \cdot (\sigma \cdot \vec{u}) + \vec{q} = n \langle (\vec{F} \cdot \nabla_p) X \rangle = |_{coll.}$$

$$n \langle \vec{F} \cdot \vec{v} \rangle$$

$$n \langle \vec{F} \cdot \vec{v} \rangle = n \langle \vec{F} \cdot (\vec{u} + \vec{c}) \rangle = n [\langle \vec{F} \rangle \cdot \vec{u} + \langle \vec{F} \cdot \vec{c} \rangle]$$

If \vec{F} is velocity-independent: $\langle \vec{F} \cdot \vec{c} \rangle = \vec{F} \cdot \langle \vec{c} \rangle = 0$.

$$\vec{F} = m \vec{g}$$

$$n \langle \vec{F} \cdot \vec{v} \rangle = n m \vec{g} \cdot \vec{u} = p \vec{g} \cdot \vec{u}$$

Energy equation:

$$\frac{\partial \epsilon}{\partial t} + \nabla \cdot (\epsilon \vec{u} + \sigma \cdot \vec{u}) + \vec{q} - p \vec{g} \cdot \vec{u} = 0 \text{ (coll.)}$$

finally, equations:

(continuity) $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0$

(momentum) $\frac{\partial (\rho \vec{u})}{\partial t} + \nabla \cdot (\rho \vec{u} \vec{u}) + \nabla \cdot \sigma - \rho \vec{g} = 0$

(energy) $\frac{\partial \epsilon}{\partial t} + \nabla \cdot (\epsilon \vec{u} + \sigma \cdot \vec{u}) + \vec{q} - p \vec{g} \cdot \vec{u} = 0$

(Equation of state) $\epsilon = \frac{\pi}{\gamma - 1} + \frac{\rho u^2}{2}$ (connects int. ϵ and mechanical pressure)

(Stress tensor generally) $\sigma = \pi I + \tau$