POLYNOMIAL BOUNDS FOR SURFACES IN CUSPED 3-MANIFOLDS

JESSICA S. PURCELL AND ANASTASIIA TSVIETKOVA

ABSTRACT. We find polynomial upper bounds on the number of isotopy classes of connected essential surfaces embedded in many cusped 3-manifolds and their Dehn fillings. Our bounds are universal, in the sense that we obtain the same explicit formula for all 3-manifolds that we consider, with the formula dependent on the Euler characteristic of the surface and similar numerical quantities encoding topology of the ambient 3-manifold. Universal and polynomial bounds have been obtained previously for classical alternating links in the 3-sphere and their Dehn fillings, but only for surfaces that are closed or spanning. Here, we consider much broader classes of 3-manifolds and all topological types of surfaces. The 3-manifolds are called weakly generalized alternating links; they include, for example, many links that are not classically alternating and/or do not lie in the 3-sphere, many virtual links and toroidally alternating links.

1. INTRODUCTION

For decades, the study of essential surfaces in 3-manifolds has led to important topological and geometric consequences. For example, the existence or nonexistence of low genus essential surfaces gives crucial insight into the geometrization of the 3-manifold, due to work of Thurston [38]. Every 3-manifold is now known to have a finite cover containing an embedded essential surface, by significant mathematical achievements involving work of Kahn and Markovic [23], Haglund and Wise [12], and Agol [3], among others.

For fixed Euler characteristic, it is natural to ask how many embedded essential surfaces lie in a given 3-manifold (up to ambient isotopy). For certain 3-manifolds, the number is infinite; for example there are infinitely many nonisotopic Seifert surfaces in a connect sum of knots, as shown in work of Eisner [8]. However, for 3-manifolds with no essential embedded spheres or tori, the number of embedded surfaces with fixed topological type is finite; see for example Jaco and Oertel [21].

Analogues of the question of how many essential surfaces embed in a given 3manifold have been addressed by others. For example, Masters [26] and then Kahn and Markovic [22] found exponential bounds on the number of immersed essential surfaces. Recently, Dunfield, Garoufalidis, and Rubinstein found quasi-polynomial bounds depending on the 3-manifold, with some restrictions [7]. Restricting to important families of 3-manifolds allows even stronger results. For example, Hass, Thompson and Tsvietkova found polynomial bounds on essential surfaces in the complement of alternating links in the 3-sphere [15, 16]. One dimension lower, a similar question was addressed by Mirzakhani for curves on surfaces [32].

This paper finds polynomial upper bounds on the number of embedded essential surfaces for broad classes of 3-manifolds with torus boundary, and many of their Dehn fillings. These results are novel on several levels. For example, our work immediately applies to the complement of alternating knots in the 3-sphere, and addresses cases not included in work of Hass, Thompson, and Tsvietkova. In particular, the previous work in [15, 16] bounds the number of closed orientable surfaces and spanning surfaces, meaning the boundary is required to be a longitude. Here, we give bounds on any embedded surface, with or without boundary, with no restrictions on boundary slope. Our results also apply to orientable and non-orientable surfaces. This completes the picture for all surfaces within classical alternating knot and link complements.

This paper can also be seen as the next step forward in the same direction as the work of Kahn and Markovic [22] and the work of Dunfield, Garoufalidis, and Rubinstein [7]. The previous step was showing that in addition to exponential bounds for immersed connected surfaces in all hyperbolic 3-manifolds [22], quasipolynomial bounds for embedded connected surfaces are possible in broad classes of 3-manifolds [7]. (More precisely, the latter work [7] gives an algorithm producing quasi-polynomial count for disconnected surfaces in a fixed 3-manifold, and that count serves as an upper bound for connected surfaces in the given 3-manifold.) Both [22, 7] provide remarkable results, but neither of them explains how the upper bound depends on the 3-manifold; instead, the bounds utilize genus or Euler characteristic of the surface. Hence, once a 3-manifold changes, the expression of the bound changes mysteriously, while the order of dependence on the genus or Euler characteristic of surfaces stays the same. The work [7] conjectures that the dependence on a 3-manifold can be captured through two parameters of the space of measured laminations without boundary in a 3-manifold.

Here, we provide a polynomial upper bound for a broad class for 3-manifolds, which is the natural next step from exponential and quasi-polynomial bounds. More importantly, we achieve the polynomial order because we now know how the bound depends on a 3-manifold. With this, our bound is universal and explicit, i.e. stated as the same straightforward formula for all 3-manifolds that we consider. It depends both on genus or Euler characteristic (exponentially) of surfaces and on two parameters that belong to a 3-manifold (polynomially). This makes our work complementary to what was established in [22, 7]. Note that our two parameters are not relevant to the lamination space, as in the forementioned conjecture: instead, they are related to torus boundary and minimal triangulations of 3-manifold. This is because both our bound and our methods are very different in nature from [22, 7].

Our methods allow us a high level of generality: for example, this is the first paper where the bound applies not only to closed surfaces (as in [7, 15]) or surfaces with one longitudal boundary component, i.e. spanning surfaces (as in [16]), but to all surfaces, with or without boundary, and with any number and type of boundary components. While the bounds for surfaces with several meridianal boundary components are a corollary of bounds for closed surfaces, no work gave bounds for surfaces with multiple boundary components, all with different slopes, before this paper. Our bound also includes not only orientable surfaces (as in [7]), but non-orientable ones as well.

1.1. Main results. We bound the count of essential surfaces for a broad family of cusped 3-manifolds called weakly generalized alternating link complements, as well as for many closed 3-manifolds that are their Dehn fillings. These first appeared in the work of Howie [18] and Howie and Purcell [19]. They include classes of 3-manifolds that have been considered over several decades, including complements of

all classical alternating links and many non-alternating links in the 3-sphere, virtual alternaing links, and others; see below.

Informally, they are complements of links in 3-manifolds such that the link has an alternating diagram on some embedded surface, with mild restrictions. In this paper, we show that for many families of weakly generalized alternating links, if the alternating link diagram has n crossings, then the number of essential surfaces of fixed Euler characteristic χ is bounded above by an explicit universal polynomial in n, of degree at most $-800\chi^3 + 80\chi^2$.

The most general statement is:

Theorem 7.4. Let L be a weakly generalized alternating link in a 3-manifold Y, with alternating diagram $\pi(L)$ on a projection surface Π , satisfying Assumptions 2.1, 2.9. Suppose that $\pi(L)$ has n crossings, and suppose that for each 3-manifold component Σ of $Y - N(\Pi)$, there is a universal bound X on the number of isotopy classes of incompressible surfaces properly embedded in Σ with fixed genus and fixed boundary curves on $\partial N(\Pi) \cap \partial \Sigma$. Fix a topological surface Z, either orientable or non-orientable, possibly with boundary, with fixed orientable or non-orientable genus g and Euler characteristic χ . Then up to isotopy, the number of ways such a surface can be properly embedded in Y - N(L) as an essential surface is at most:

$$(2X(g+1))^{-4\chi+2} \cdot (6n)^{-800\chi^3+80\chi^2}$$

The factor X is explicitly known for a number of families of cusped 3-manifolds. With this, our work gives simple polynomial bounds depending only on χ, g, n for:

(1) Alternating links in the 3-sphere. For L a nonsplit prime alternating link, our result extends work of Hass, Thompson, and Tsvietkova, who bound the number of closed surfaces and meridianal surfaces [15], and spanning surfaces with slope a longitude of the knot [16]. Our work gives bounds on arbitrary (connected) essential surfaces with any boundary slope, including both orientable and nonorientable surfaces; see Theorems 6.1 and 6.3. If Z is meridianally incompressible, the number of embeddings is at most $(6n)^{80\chi(Z)^2}$; otherwise there is an additional factor in terms of $\chi(Z)$.

(2) Alternating links in a thickened surface Y (i.e. virtual alternating links). Such 3manifolds were recently investigated by Adams *et al* [1] and Champanekar, Kofman, and Purcell [6]. Here, we obtain a bound on the number of essential embedded surfaces in Corollary 8.6 below.

(3) Weakly generalized alternating links with a projection surface Π that is a Heegaard torus in a lens space, or in a thickened torus, or in a solid torus. The bound is Corollary 8.4. These classes of 3-manifolds appear frequently in low-dimensional topology. For example, alternating knots on Heegaard tori have been studied by Adams [2]. Alternating knots on more general Heegaard surfaces have been studied by Hayashi [17].

As a corollary, we obtain bounds on the number of essential surfaces of fixed Euler characteristic χ in most closed manifolds obtained by Dehn filling on weakly generalized alternating links, including classical alternating knots; see Theorem 9.1 and Corollary 9.3.

1.2. Comparison to previous work. As noted above, the work presented here is novel on several levels: It gives polynomial bounds in addition to the existing quasipolynomial and exponential bounds, applies to closed surfaces as well as those with boundary, applies to both orientable and nonorientable surfaces, and is naturally tailored to working with connected surfaces, which is often more subtle than working with disconnected ones. More importantly, the bound is universal, meaning it is the same formula for all 3-manifolds that we consider, capturing explicit dependence on numerical parameters of surfaces (genus and Euler characteristics) and numerical parameters of 3-manifolds (number of tetrahedra in a minimal triangulation of a chunk, number of crossings in a projection of cusp boundary). Note universal and explicit bounds were also obtained in [15, 16], but not in [22, 7].

Similar to other work, our upper bounds for connected surfaces are not sharp. Indeed, due to various shortcuts we took to simplify our bounds, and in the combinatorial part of the proof, the final upper bound is likely quite far from sharp. We have not analysed how far from sharp it might be; this would be interesting follow up work.

Finally, the methods we develop here are also new: they have not been used in any of the previous bounds. Some of our techniques can be seen broadly as generalizations of normal surface theory. However the direct application of classical normal surface theory to this problem can only produce universal bounds that are exponential. For example, using triangulations of 3-manifolds and normal surface theory, one can bound the number of isotopy classes of fundamental normal surfaces; see Matveev [27], Jaco and Oertel [21], and Hass, Lagarias, and Pippenger [13]. This can be used to give bounds on the number of all essential surfaces in certain settings, but the bounds are a tower of exponentials in terms of genus. Normal surfaces are also used in the recent work of Dunfield, Garoufalidis, and Rubinstein [7], but, as explained above, the set up is different: instead of a universal bound, normal surfaces allow an algorithm that will count disconnected closed orientable surfaces once a 3-manifold is fixed.

Note that a related, but much simpler problem is bounding the number of incompressible surfaces that can be simultaneously disjointly embedded in a 3-manifold. This problem was originally studied by Kneser, who obtained bounds in 1929 [24]. Here, we bound all essential embeddings, not just disjoint collections.

1.3. **Organisation.** In Section 2, we recall the definition of a weakly generalized alternating link, and the decomposition of its complement into *chunks* introduced by Howie and Purcell [19]. We also review certain techniques for essential surfaces in these link complements: normal form with respect to a chunk decomposition, combinatorial area, and results from Purcell and Tsvietkova [36] giving restrictions on how such surfaces meet chunks. We begin the count of surfaces in Section 4, by bounding the number of subsurfaces making up an essential surface, and the number of labels on the boundaries of such subsurfaces. In Section 5, we restrict the possible number of boundary curves of subsurfaces.

At this point, we are ready for our first application: the count of essential surfaces for classical alternating links in S^3 whose boundary follows a longitude more than one time. We do this in Section 6.

We then return to the more general case of links in any compact orientable 3-manifold, giving a general bound depending on the chunks in Section 7, and giving applications to certain families of weakly generalized alternating links in Section 8: bounds for weakly generalized alternating links in thickened tori and in lens spaces, and bounds for virtual alternating knots that have a diagram that is cellular, meaning all regions are disks. Finally, we give applications to Dehn fillings in Section 9.

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2. Preliminaries

In recent work of Hass, Thompson, and Tsvietkova [15, 16], surfaces are put into a standard form, extending work of Menasco [28, 29] and Menasco–Thistlethwaite [31]. Here, we combine standard form techniques with related work of Lackenby [25], Futer–Guéritaud [11], and Howie–Purcell [19], who put surfaces into normal form with respect to a decomposition of the knot complement. The combination of these two ideas extends beyond usual alternating links projected onto S^2 lying in the 3-sphere. Howie and Purcell extend such tools to apply to a class of knots with alternating diagram projected onto any closed orientable surface II embedded in any irreducible, boundary irreducible, compact orientable 3-manifold Y [19]. These are called weakly generalized alternating links. They include alternating links in 3-sphere, which we refer to as classical alternating links. They also include many virtual alternating knots, many alternating knots on Heegaard surfaces in closed irreducible 3-manifolds, and other broad families of 3-manifolds.

In this section, we recall the definition of weakly generalized alternating links, the decomposition of their complement into chunks, and normal surfaces within them. Most of this originally appeared in Howie–Purcell [19] and in Purcell–Tsvietkova [36].

2.1. Weakly generalized alternating links.

Assumption 2.1. Throughout, we work with PL manifolds. We let Y be a compact, orientable, irreducible 3-manifold, possibly with boundary. Embedded in Y is a closed, orientable surface Π . If Y has boundary, we require ∂Y to be incompressible in $Y - N(\Pi)$, where $N(\cdot)$ denotes an open regular neighborhood. Further, we require $Y - \Pi$ to be irreducible.

A generalized diagram is the projection $\pi: L \to N(\Pi)$ of a link L onto the surface Π in general position. That is, L can be isotoped through Y to lie in $N(\Pi)$. The image of the projection $\pi(L)$ consists of crossings and arcs between them on Π .

Observe that the requirement that $Y - \Pi$ be irreducible means that if Π is the 2-sphere, then $Y = S^3$ and the generalized diagram is actually the standard diagram of a knot in the 3-sphere.

A generalized diagram is *alternating* if, for each region of $\Pi \setminus \pi(L)$, each boundary component of the region is alternating. That is, it can be oriented such that crossings run from under to over in the direction of orientation. An alternating generalized diagram is *checkerboard colored* if each region of $\Pi \setminus \pi(L)$ is oriented so that the induced orientation on the boundary is alternating. See [36, Figure 1] for examples and nonexamples.

To ensure that the diagram $\pi(L)$ is sufficiently reduced, we introduce a notion of prime. A generalized diagram is *weakly prime* if whenever a disk D embedded in Π has boundary ∂D meeting $\pi(L)$ transversely exactly twice, either the disk contains no crossings in its interior, or Π is the 2-sphere and there is a single embedded arc with no crossings in the complementary disk $\Pi - D$. Note that by this definition, a classical alternating link on S^2 in S^3 that is prime is also weakly prime.

Finally, the representativity of a generalized diagram is defined as follows. Because Π is orientable, $Y - N(\Pi)$ has two boundary components for each component Π_i of Π , call them Π_i^+ and Π_i^- . Let $r^+(\pi(L), \Pi_i)$ denote the minimum number of intersections between $\pi(L)$ and the boundary of any essential compressing disk in $Y - N(\Pi)$ whose boundary lies on Π_i^+ ; if there are no such essential compressing disks, we definite this to be ∞ . Define $r^-(\pi(L), \Pi_i)$ similarly. The *representativity* $r(\pi(L), \Pi)$ is the minimum of all values $r^+(\pi(L), \Pi_i)$ and $r^-(\pi(L), \Pi)$ over all *i*. Thus it measures the minimum number of times the boundary of any essential compressing disk for $Y - N(\Pi)$ meets $\pi(L)$.

The hat-representativity $\hat{r}(\pi(L), \Pi)$ is defined to be the minimum of

$$\bigcup_{i} \max\{r^{+}(\pi(L), \Pi_{i}), r^{-}(\pi(L), \Pi_{i})\}.$$

Thus it measures the minimal number of intersections of the boundary of any essential compressing disk on one side of Π . See [36, Example 2.2] for examples.

Note that in the case Π is the 2-sphere inside $Y = S^3$, there are no essential compressing disks for the balls $S^3 - N(\Pi)$. Hence the representativity and hat-representativity in the classical alternating setting are both infinite.

A generalized diagram $\pi(L)$ on Π is defined in [19] to be *weakly generalized* alternating if

- (1) $\pi(L)$ is alternating on Π ,
- (2) $\pi(L)$ is weakly prime,
- (3) $\pi(L)$ meets each component of the projection surface Π ,
- (4) each component of $\pi(L)$ projects to at least one crossing in $\pi(L)$,
- (5) $\pi(L)$ is checkerboard colorable, and
- (6) the representativity $r(\pi(L), \Pi) \geq 4$.

From now on, every link we consider will have such a diagram, i.e. it will be a weakly generalized alternating link. Note that a classical reduced, prime, alternating diagram of a link L on $\Pi = S^2$ in S^3 is an example of a weakly generalized alternating link. As noted in the introduction, there are many more examples, including alternating links on Heegaard tori in S^3 and in lens spaces. When the diagram is *cellular*, meaning all regions of $\Pi - \pi(L)$ are disks, these are examples of toroidally alternating knots studied by Adams [2]. Note that weakly generalized alternating knots do not necessarily need to have cellular diagrams. However, the representativity condition means that not every toroidally alternating knot is also weakly generalized alternating. Virtual alternating knots are further examples of weakly generalized alternating knots; these are alternating knots in a thickened surface $\Sigma \times (-1, 1)$, projected onto $\Pi = \Sigma \times \{0\}$. They have also received attention recently, for example by Adams [1] and Champanerkar, Kofman, and Purcell [6]. 2.2. Chunk decomposition. Classical alternating knot and link complements have a well-known decomposition into topological polyhedra. This was suggested by W. Thurston and described by Menasco [30]; see also Lackenby [25] and Purcell [35, Chapters 1 and 11]. A more general decomposition of arborescent knots into angled blocks was defined by Futer and Guéritaud [11], and this was generalized further by Howie and Purcell to weakly generalized alternating links [19]. We briefly review the salient points here; see also [36, Section 3] for further discussion and examples.

A checkerboard colored diagram has two checkerboard colored surfaces. The white surface comes from regions of $\Pi - \pi(L)$ that are colored white, and connected by twisted bands at each crossing; a similar construction holds for the shaded surface. Note the two surfaces intersect at a crossing in a *crossing arc*, which runs from the overstrand to the understrand. The decomposition of the weakly generalized alternating link complement is obtained by cutting along the two checkerboard surfaces. This cuts Y - N(L) into components with interiors homeomorphic to $Y - N(\Pi)$. These are called *chunks*. Crossing arcs become ideal edges on the chunk boundary; strands of the knot become ideal vertices, and we contract strands so that ideal vertices lie at a crossing of the diagram, and edges follow the diagram graph of $\pi(L)$. Thus each chunk is a connected component of $Y - N(\Pi)$ with Π^+ and Π^- decorated by the following:

- (1) Edges of $\pi(L)$, corresponding to ideal edges. We call these *interior edges*. Four interior edges, two on each side of Π^{\pm} , are glued to form a crossing arc in Y - L.
- (2) Ideal vertices at the crossings of $\pi(L)$. These are all 4-valent.
- (3) Regions of $\pi(L)$ bounded by interior edges. These are called *faces* of the chunk. Observe that they are not necessarily simply connected, but they are checkerboard colored.

We further truncate ideal vertices. Because vertices are 4-valent, the resulting truncation turns each ideal vertex into a quad, called a *truncation face*, bounded by *truncation edges* (called boundary faces and boundary edges in [19]). Howie and Purcell prove that a weakly generalized alternating link complement admits such a decomposition [19, Propositions 3.1 and 3.3].

The key point is that the combinatorics of the chunk decomposition exactly matches the combinatorics of the link diagram; this comes from the fact that the diagram is alternating. Then the fact that the diagram is weakly prime and has bounded representativity restricts the way that surfaces can lie inside the chunk.

2.3. Normal surfaces. We now consider $(Z, \partial Z)$ to be an essential surface embedded in $(Y - N(L), \partial N(L))$, where the boundary of the surface Z is possibly empty. We will generally allow Z to be orientable or nonorientable, unless otherwise stated. Recall that a surface is *essential* if it is incompressible, boundary incompressible, and is not boundary parallel.

Assumption 2.2. Throughout, we use the topological definition of incompressible surfaces: a surface Z that is neither a disk nor a 2-sphere is incompressible in a 3-manifold M if any disk D with interior embedded in M - N(Z), with boundary on Z, satisfies ∂D bounds a disk in Z. A surface that is not incompressible admits an essential compression disk, namely a disk D with interior embedded in M - N(Z)with ∂D an essential curve on Z.



FIGURE 1. Left: a surface with meridianal boundary can be isotoped to meet N(L) transversely away from crossings. Right: in the chunk decomposition, ∂Z cuts off exactly two corners of truncation faces.

A 2-sphere is incompressible if and only if it does not bound a 3-ball. By convention, disks will be neither incompressible nor compressible.

We will count essential surfaces later in the paper in weakly generalized alternating links and their Dehn fillings. To do so, we put them into *normal form* with respect to the chunk decomposition. Normal form in this setting was introduced in Howie–Purcell [19, Definition 3.7]; it generalizes the definition of *standard position* for surfaces in classical alternating knots used by Menasco [28] and Menasco–Thistlethwaite [31], as well as *normal form* for surfaces in Lackenby [25] and Futer–Guéritaud [11]. We will not need the full definition of normal form here, only the consequences of that definition from Howie–Purcell [19] and from Purcell– Tsvietkova [36]. Therefore we refer to these references for definitions and examples, but we review the necessary results here.

First, it was shown in Howie–Purcell [19, Theorem 3.8] that any essential surface in a 3-manifold with a chunk decomposition can be put into normal form with respect to the chunk decomposition. When Z is isotoped into normal form, it is cut into components Z_i , which are connected subsurfaces of Z in normal form within a chunk. These may be closed or with boundary, and might have multiple boundary components. We will write $Z = \bigcup Z_i$.

Both for classical alternating links in S^3 [28, Theorem 2] and for weakly generalised alternating links under certain conditions [19, Lemma 4.9], a closed surface Z' admits meridianal compressions. After meridianal compressions the resulting surface Z can be arranged to meet the diagram in meridians.

It was shown by Purcell–Tsvietkova [36, Theorem 6.2] that an isotopy into normal form can be done such that boundary curves ∂Z that are meridians remain in *meridianal form* after the isotopy, meaning that ∂Z cuts off exactly two corners of quads corresponding to truncation faces, one on Π^+ and one on Π^- . See Figure 1, which is from [36]. Moreover, such an isotopy does not increase weight, where the weight is the pair (s(Z), t(Z)), ordered lexicographically, where s(Z) counts the number of intersections of Z with interior edges, and t(Z) counts the number of intersections with truncation edges.

Assumption 2.3. From now on, when we put an essential surface in normal form, we always make two assumptions:

(1) the surface is in meridianal form, and

(2) out of all ways to isotope the surface into normal, meridianal form, we choose one with least weight.

This allows a labeling of curves of Z_i that lie on chunk boundary, described in [36, Section 5], which we now review.

For normal components Z_j of the surface Z, each boundary component of ∂Z_j runs over truncation edges and interior edges of the respective chunks. Each intersection of ∂Z_j with an interior edge is labeled with an S, for "saddle", corresponding to an analogous labeling by Menasco [28]; see also [15, 16]. If a component of ∂Z_i is in meridianal form, then there will be some Z_i and Z_j such that ∂Z_i and ∂Z_j each cut off exactly one corner of a truncation quad, in meridianal form. We label these intersections with truncation faces by P. Finally, more generally some ∂Z_k may run through truncation faces that may or may not be in meridianal form. In this case, it runs through one truncation edge on the way in, and one truncation edge on the way out; label each intersection with a truncation edge with a B. The labeling of components of ∂Z_i by letters S, B, or P associates a cyclic word to ∂Z_i .

For classical alternating links, each Z_i can be taken to be a disk lying in one of the topological 3-balls either above or below the link. The boundary curves ∂Z_i are determined by the associated words in S, P, and B and by the position of each letter on the link diagram. Thus bounding the number of possible boundary words gives a bound on the number of surfaces; this is used in the work of Hass, Thompson, and Tsvietkova [15, 16]. For weakly generalized alternating links, the subsurfaces Z_i might have positive genus and multiple boundary components. Moreover, the subsurfaces are not in topological 3-balls anymore, but in chunks which might have complicated topology themselves. Thus we need more tools to restrict and control possible subsurfaces that arise. One such tool is the combinatorial area.

2.4. Combinatorial area. Label each interior edge of a chunk with angle $\pi/2$, and label each truncation edge with angle $\pi/2$.

Write $Z = \bigcup_{j=1}^{j} Z_j$ where each Z_j is a connected normal surface embedded in a

chunk. Each curve ∂Z_j will meet some number of interior edges, each labeled by S; denote the number by (#S). It will also meet truncation edges, with each either labeled by B or with a pair in meridianal form labeled by a single P. Denote the number of instances of B by (#B) and the number of instances of P by (#P). On a single component of N(L), all intersections of ∂Z_j with corresponding truncation edges will either all be labeled B or all labeled P.

For this surface, the *combinatorial area* of Z_j is defined to be

(2.4)
$$a(Z_j) = \frac{\pi}{2}(\#S) + \frac{\pi}{2}(\#B) + \pi(\#P) - 2\pi\chi(Z_j).$$

The *combinatorial area* of Z then is

(2.5)
$$a(Z) = \sum_{i=1}^{n} a(Z_i)$$

This construction satisfies a Gauss–Bonnet formula [19, Proposition 3.12]:

Furthermore, in [36, Lemma 8.5], it was shown that combinatorial area satisfies the following lemma.

Lemma 2.7 (Lemma 8.5 of [36]). Let Z_i be normal and connected with respect to a chunk. The combinatorial area of Z_i satisfies the following.

- (1) If $\chi(Z_i) < 0$ then $a(Z_i) \ge 2\pi$.
- (2) If $\chi(Z_i) \ge 0$ then either $a(Z_i) \ge \pi/2$ or $a(Z_i) = 0$.
- (3) Additionally, in the case that $a(Z_i) = 0$, Z_i is either:
 - (a) an essential torus or Klein bottle embedded in a chunk, hence $Z = Z_i$ is a torus or Klein bottle,
 - (b) an annulus or a Möbius band with boundary meeting no edges, or
 - (c) a disk with ∂Z_i meeting exactly four edges of the chunk decomposition.

Later, we will use combinatorial area to control the number of pieces Z_i for a surface of a given genus. But this type of argument does not work for normal components of the surface that have zero area, and so we need to consider them separately. If we assume that Π is chosen so that $Y - \Pi$ admits no essential embedded tori or Klein bottles, then there will be no zero area tori or Klein bottles in the chunk decomposition. If we require all regions of $\pi(L)$ on Π to be disks, that is, the diagram is *cellular*, then there will be no zero area annuli or Möbius bands. We therefore focus on disks with zero area.

The only possible disks with zero area are enumerated in [36, Lemma 8.6]; they have boundaries labeled one of PP, PSS, SSSS, BBBB, BBSS, or in the case of links, PBB. We will always relabel the instance of P in the final case with two instances of B; this allows us to identify such disks as BBBB disks and use the tools in that setting to control such disks.

The zero area disks are considered in [36]. By Theorem 9.1 in that paper, SSSS disks only appear as an essential compression disk for Π , with boundary meeting the diagram $\pi(L)$ in exactly four interior edges. They will not occur if the representativity satisfies $r(\pi(L), \Pi) > 4$. By [36, Theorem 10.1], there are no *PP* disks (nor *PS* nor *SS* disks). By [36, Theorem 10.2], there are no *PSS* disks.

If Z_i comes from a spanning surface or more general surface with boundary and meets truncation edges, then there will be letters B. We cannot rule these out, but in [36, Section 11] it is shown that if such disks arise, they form larger disks together. In particular, the following appears in that paper.

Theorem 2.8 (Theorem 11.4 of [36]). Assume that the hat-representativity satisfies $\hat{r}(\pi(L), \Pi) > 4$, and $\pi(L)$ is not a string of bigons on Π . Let Z be an essential surface in normal form with respect to the chunk decomposition. Then all subsurfaces Z_i that are neither BBBB disks nor BBSS disks, together with the link L, determine the surface Z up to isotopy.

Assumption 2.9. To rule out surfaces with zero area that are not disks, from now on we will assume that the diagram $\pi(L)$ is *cellular*, i.e. all regions of $\Pi - \pi(L)$ are disks. Assume also that $Y - N(\Pi)$ admits no embedded essential tori or Klein bottles. To rule out *SSSS* disks, we further assume $r(\pi(L), \Pi) > 4$; note this implies that $\hat{r}(\pi(L), \Pi) > 4$, so Theorem 2.8 also applies.

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3. Meridianal compressions

Let Z be a surface properly embedded in Y - N(L). We say Z is meridianally compressible if there is an essential meridianal annulus A with one component $\partial_1 A$ of ∂A on Z, and the other component $\partial_2 A$ of ∂A forming a meridian on $\partial N(L)$. The requirement that A be essential means that there is no embedded annulus A' in Z such that a component of $\partial A'$ agrees with $\partial_1 A$, the other component of $\partial A'$ lies on ∂Z , forming a meridianal boundary component on N(L), and A is ambient isotopic to A' in Y - N(L) rel $\partial_1 A$. If there is no essential meridianal annulus for Z, we say it is meridianally incompressible. For a meridianally compressible surface, performing surgery along A yields a new surface with boundary forming a meridian of N(L); this is called a meridianal compression of Z.

As in [15], we will count surfaces after first performing a maximal number of meridianal compressions. However, unlike [15], we now allow surfaces with additional boundary components and nonorientable surfaces. The next lemmas give bounds on the total number of meridianal compressions we must make. These are in terms of the Euler characteristic of the surface, which combines genus and boundary components. Recall that the genus of the surface is the maximum number of disjoint simple closed curves that can be drawn on the surface without disconnecting it. For orientable surfaces, we will denote the genus by g_0 . For a nonorientable surface, the genus is equal to the number of cross-caps attached to a sphere, and is often called a nonorientable genus. Denote it by g_N . Then for a closed orientable surface Z, $\chi(Z) = 2 - 2g_0$, and for a closed nonorientable one, $\chi(Z) = 2 - g_N$. Despite this difference, we will often just use g for genus, meaning both orientable and nonorientable, where this does not affect the calculation. For surfaces with b boundary components, the Euler characteristic is then $\chi(Z) = 2 - 2g_0 - b$ or $\chi(Z) = 2 - g_N - b$, for the orientable and nonorientable case respectively.

All cases are summarised in the following.

Lemma 3.1. Suppose Z' is an essential surface with negative Euler characteristic, with or without boundary, orientable or nonorientable, that is properly embedded in Y - N(L). Let Z be obtained from Z' by performing a maximal sequence of meridianal compressions. Then the Euler characteristic of Z is $\chi(Z) = \chi(Z')$, and the meridianal compressions have added at most $-4\chi(Z) + 2$ boundary components. These are tubed in pairs to obtain Z' from Z.

Note we could prove a better upper bound of $-2\chi(Z)$ when the surface is closed and orientable, by repeating an argument of [15]. However, since we only need a bound, and not a sharp bound, we state the most general bound to avoid dealing with multiple cases later in the paper.

Proof. A meridianal compression will be performed along a simple closed curve on the surface. We consider orientable and nonorientable surfaces, and for a nonorientable surface, such curve can be either one-sided or two-sided.

First, consider one-sided curves. Note that if an annulus A has boundary $\partial_1 A$ on a one-sided curve, then A must wrap twice around the curve, and gluing A to itself along $\partial_1 A$ forms a Möbius band with meridianal boundary. However, [19, Theorem 4.6] implies that there is no embedded Möbius band with meridianal boundary in a weakly generalised alternating link. Thus we may rule out one-sided curves for meridianal compressions.

Now consider two-sided curves, on orientable and nonorientable surfaces. The topological effect of a meridianal compression is to remove an open neighborhood of a (2-sided) curve $\partial_1 A$ on Z'. This is an annulus, and the Euler characteristic of the surface before and after removing the interior of an annulus is unchanged.

Note meridianal compression adds two boundary components to the surface. Thus to bound the number of added boundary components obtained by a maximal sequence of meridianal compressions, we must bound the number of such compressions.

If Z' is a closed orientable surface with negative Euler characteristic, then it contains at most 3g-3 disjoint nonparallel curves; these cut Z' into pairs of pants. More generally, if Z' is orientable with genus g and b boundary components, then it contains 3g-3+b disjoint nonparallel curves that are not parallel to boundary components. The total number of boundary components after removing the interior of a regular neighborhood of each of these curves is $6g-6+2b \leq -3(2-2g-b) =$ $-3\chi(Z') < -4\chi(Z') + 2$. This is an upper bound for the number of boundary components produced by meridianal compression in this case.

If Z' is a nonorientable surface with b boundary components, then it can be cut along g disjoint nonparallel two-sided curves to cut it into planar surfaces and Möbius bands. An additional g + b - 3 curves cut the planar surfaces into pairs of pants. This gives 2g - 3 + b disjoint nonparallel two-sided curves. The total number of boundary curves after removing regular neighborhoods of these curves is at most $4g - 6 + 2b < 4g + 4b - 8 + 2 = -4\chi(Z) + 2$.

We also include one result from [36] that allows us to rule out meridianal compressions for many surfaces with boundary on a link.

Lemma 3.2. [36, Proposition 7.1 (1)] There is no meridianal compression of Z to a component L_i of $\partial N(L)$ for which $\partial Z \cap L_i$ is nonempty and non-meridianal.

Assumption 3.3. From now on, assume Z is essential and properly embedded in Y - N(L). The surface Z is not necessarily orientable, and possibly has boundary components, meridianal or nonmeridianal, that are always on $\partial N(L)$.

4. Counting subsurfaces and their boundary curves

In this section, we begin our count of surfaces by bounding the total number of subsurfaces in a chunk making up a normal surface Z, and the total number of words associated with their boundary components.

Lemma 4.1. Suppose Z is meridianally incompressible. Let $Z = \bigcup_{i=1}^{m} Z_i$, where the Z_i are normal subsurfaces in chunks. Then the number of subsurfaces Z_i that are not disks with boundary BBBB or BBSS is at most $-4\chi(Z)$.

Remark 4.2. Recall that when we have a link with mixed boundary components, both meridianal and non-meridianal, we relabel all instances of P with two instances of B. Thus in Lemma 4.1, we view PBB disks as BBBB disks.

Proof of Lemma 4.1. Let n_1 be the number of the Z_i that have Euler characteristic 0 or 1, and are not disks with boundary *BBBB* or *BBSS*. Let n_2 be the number with Euler characteristic at most -1. Then the total number of subsurfaces Z_i considered in the lemma is $m = n_1 + n_2$. By the Gauss-Bonnet theorem (2.6), by

equation (2.5), and by Lemma 2.7 (1),

$$-2\pi\chi(Z) = a(Z) = \sum_{i=1}^{m} a(Z_i) \ge \sum_{\chi(Z_i)=0,1}^{m} a(Z_i) + n_2 2\pi.$$

For the subsurfaces with $\chi(Z_i) = 1$ or 0, we need to determine which have $a(Z_i) = 0$. By Lemma 2.7 (3), these can be tori, Klein bottles, annuli or Möbius bands meeting no edges, or disks meeting four edges. Assumption 2.9, that all regions of $\pi(L)$ on Π are disks, rules out annuli and Möbius bands meeting no edges: the boundary curve would lie in one of the cellular faces, and hence bound a disk there, which is not allowed for surfaces in normal form. Assumption 2.9 also requires that $Y - N(\Pi)$ admits no essential tori and Klein bottles, which rules out these surfaces. Thus if $a(Z_i) = 0$ then Z_i is a normal disk meeting four edges.

If Z has only meridianal boundary components and $a(Z_i) = 0$, then it is a disk with boundary of the form *PSS*, *PP*, or *SSSS*. But these are ruled out by [36, Theorem 10.1], [36, Theorem 10.2], and [36, Theorem 9.1], respectively, using the hypothesis that $r(\pi(L), \Pi) > 4$ for the *SSSS* case. If Z has a non-meridianal boundary component, then we consider all intersections with truncation edges as labeled B. The only remaining normal disks with $a(Z_i) = 0$ are *BBBB* or *BBSS* disks, ruled out by hypothesis.

Then Lemma 2.7(2) implies

$$\sum_{\chi(Z_i)=0,1} a(Z_i) \ge n_1 \frac{\pi}{2},$$

and hence

$$-2\pi\chi(Z) \ge n_1 \frac{\pi}{2} + n_2 2\pi \ge \frac{\pi}{2} m.$$

So $m \leq -4\chi(Z)$. Therefore, there are at most $-4\chi(Z)$ subsurfaces Z_i that are not disks labeled *BBBB* or *BBSS*.

Lemma 4.3. Let Z be meridianally incompressible, properly embedded in Y - N(L) in normal form. Suppose further that Z satisfies one of the following cases.

- (1) The surface Z has only meridianal boundary.
- (2) The surface Z has at least one non-meridianal boundary component on L.

Then there are at most $-10\chi(Z)$ boundary components on any Z_i that are not associated to BBBB or BBSS disks. Moreover, the number of intersections of such a boundary component with chunk edges is at most $-20\chi(Z)$.

Proof. Recall that $Z = \bigcup_{i=1}^{m} Z_i$. By (2.5), and by Gauss–Bonnet (2.6), the combinatorial area a(Z) satisfies:

$$-2\pi\chi(Z) = a(Z) = \sum_{i=1}^{m} a(Z_i).$$

Moreover, each time a boundary component of Z meets an interior or truncation edge of the chunk decomposition, there is a contribution of $\pi/2$ to the area. More precisely, if w_i is the total number of intersections of all the boundary components of Z_i with chunk edges, then

(4.4)
$$a(Z_i) = w_i \frac{\pi}{2} - 2\pi \chi(Z_i).$$

Let w be the number of intersections with chunk edges for all boundary components of Z that are not associated to BBBB or BBSS disks.

In case (1), when the surface has meridianal boundary, all words are in letters P and S, so $w = \sum w_i$. In case (2), when Z_i is a *BBBB* or *BBSS* disk, we know its combinatorial area is 0. Moreover, we know that $2\pi\chi(Z_i) \leq 0$ unless Z_i is a disk. Thus from equation (4.4), in both cases we have

$$a(Z) \ge w\frac{\pi}{2} - 2\pi \cdot |\{Z_i : Z_i \text{ is a disk, but not a } BBBB \text{ or } BBSS \text{ disk}\}|.$$

The number of Z_i that are disks but not *BBBB* or *BBSS* disks is at most the total number of such subsurfaces Z_i , which is at most $-4\chi(Z)$ by Lemma 4.1. Thus

$$-2\pi\chi(Z) \ge w\frac{\pi}{2} + 2\pi(4\chi(Z)),$$

and so $-20\chi(Z) \ge w$.

Any curve of ∂Z_i that does not come from a *BBBB* or *BBSS* disk can contain at most w intersections with chunk edges, so the total number of intersections is at most $w \leq -20\chi(Z)$. Any curve must have at least two intersections, since all regions of the chunks are disks and thus any closed curve ∂Z_i must enter and exit each region. Hence any Z_i has at most $-10\chi(Z)$ boundary components. \Box

5. Placing curves on the chunk boundary

We now proceed with counting options for potential curves of intersection of Z_i with the chunk boundary. Recall that for a fixed component Π_j of the projection surface Π , there are two associated boundary components Π_j^+ or Π_j^- for the chunk decomposition. However, Π^- is glued to Π^+ , so once the curves are determined in each Π_j^+ , they uniquely determine those on the Π_j^- . Thus we need only count the curves on Π^+ .

We will count the curves by counting how they intersect the edges of the chunk decomposition: truncation edges and interior edges.

Definition 5.1. An ordered subset of chunk edges on Π_j^+ , up to cyclic order, is called a *combination*.

Lemma 5.2. A boundary component of Z_i is determined up to isotopy on the chunk boundary by the respective combination.

Proof. Any two consecutive intersections in a combination will be connected by an arc of ∂Z_i in a face of a chunk. Because each face of a chunk is a disk, such an arc is unique up to isotopy. The only way the boundary component might not be unique is if multiple arcs with intersections on the same edges interleave in a face in different ways. But for a fixed combination, there will be a unique way to connect such arcs into a closed curve.

Therefore, a combination determines a closed curve on the chunk boundary. If we have two identical combinations, they will determine parallel curves on the chunk boundary. These are isotopic on the chunk boundary, as required. \Box

Lemma 5.3. Once all combinations that correspond to normal subsurfaces Z_i are fixed, then the slopes of boundary components of Z on $\partial N(L)$ are uniquely determined. In particular, this is true even if we do not distinguish between P and B.

Proof. By Lemma 5.2, the boundary components of the subsurfaces Z_i are determined up to isotopy by the fixed combinations. The subsurfaces will be identified across arcs in interior faces to form Z. This identification is via the homeomorphism that comes with the chunk decomposition of the link complement. The arcs of Z_i on truncation faces become boundary components of Z. These glue uniquely at their endpoints, which lie on the boundary of interior faces, to give closed curves on $\partial N(L)$.

Observe that combinations only include information on intersections with edges, and are independent of the letters P and B, which we assign separately. Thus the slope is also determined independent of the assignment of P or B.

Counting combinations gives us the following lemma, which is similar to part of the argument of Hass, Thompson, and Tsvietkova [15, 16], despite the fact that here the 3-manifold is more general, and the normal subsurfaces Z_i are general surfaces with boundary, while in [15, 16] analogous surfaces are disks. Also, unlike in [16], a surface Z with non-meridianal boundary is not necessarily a spanning surface for a link, i.e. its boundary curve does not have to have intersection number 1 with a meridian.

Lemma 5.4. Suppose Z has boundary, either meridianal or non-meridianal on $\partial N(L)$, and $\chi(Z) < 0$, and Z is meridianally incompressible. Let n be the number of crossings of the diagram $\pi(L)$. Then the number of curves on the boundary of the chunk that could be a boundary component of some subsurface Z_i on Π^+ is at most $C(n, \chi(Z))$, where:

$$C(n, \chi(Z)) = (6n)^{-20\chi(Z)}$$

Proof. Let γ be a boundary component of ∂Z_i . By Lemma 5.2, such a curve is determined by its associated combination.

On Π_j^+ , there are $2n_j$ interior edges of Π_j^+ for each potential intersection with γ , where n_j is the number of crossings on Π_j . Similarly, there are $4n_j$ truncation edges for each potential intersection. Thus for ∂Z_i on Π_j^+ , there are at most $2n_j + 4n_j \leq$ $6n_j$ choices for an intersection. Summing over all possibilities for all j, there are at most 6n choices for an intersection on $\Pi^+ = \bigcup \Pi_j^+$.

By Lemma 4.3, there are at most $-20\chi(Z)$ intersections with chunk edges for γ , as long as γ is not the boundary of a *BBBB* or *BBSS* disk. But even if it is the boundary of a *BBBB* or *BBSS* disk, there are only $4 < -20\chi(Z)$ intersections. Thus there are at most $(6n)^{-20\chi(Z)}$ combinations of length $-20\chi(Z)$ on Π^+ . However, we wish to count curves with at most $-20\chi(Z)$ intersections, meaning we need to count ones with $-20\chi(Z)$ intersections, with $-20\chi(Z) - 1$ intersections, etc., down to length 2. For this, we make use of the observation that our count of the combinations is already an overcount: For a combination with $s < -20\chi(Z)$ intersection). Define a combination of length $-20\chi(Z)$ associated to the shorter combination by requiring the combination to hit the same last edge consecutively over and over. Such a combination does not correspond to a curve of ∂Z_i , but is counted in the bound $(6n)^{-20\chi(Z)}$. Therefore, $(6n)^{-20\chi(Z)}$ is an upper bound for the number of curves on Π^+ .

Remark 5.5. The upper bound in Lemma 5.4 is not sharp. Indeed, the number of possible combinations includes combinations that do not result in closed curves at all, and ones that result in curves that cannot correspond to boundary components of any Z_i in normal position. However this bound will later allow us to obtain an upper bound on the number of surfaces that is polynomial in n. Observe that if Z has many boundary components, or high genus, or even boundary components that intersect a meridian many times, then $\chi(Z)$ will be large as a consequence of the Gauss–Bonnet formula, equation (2.6). Thus the upper bound will naturally be higher for such surfaces.

6. Surfaces in classical alternating link complements

In prior sections, we worked with a link L projected onto a surface Π in a general 3-manifold Y satisfying a few mild hypotheses, and developed machinery for weakly generalised alternating links in Y. In this section, we temporarily restrict our attention to $Y = S^3$ and classical alternating links on S^2 .

As noted in Section 2 above, a classical alternating link on S^2 in S^3 that is prime is also weakly prime, and has infinite representativity and hat-representativity. It is also checkerboard colored. Hence classical reduced, prime, alternating links are weakly generalized alternating links. Moreover, all the complementary regions in $S^2 - \pi(L)$ are disks in this case, and hence the diagram is cellular. Thus it satisfies Assumptions 2.1 and 2.9, hence satisfies all the hypotheses of the lemmas we have encountered so far.

A bound for the number of closed essential surfaces in classical alternating link complements was given in [15]; the same work gives the number of surfaces with meridianal boundary. The number of surfaces with non-meridianal boundary that are Seifert (spanning, orientable) was given in [16]; this generalizes to nonorientable spanning surfaces. However the bound for the number of non-spanning surfaces with non-meridianal boundary was unknown. These surfaces have some boundary component that follows the knot along its longitude q times, where q > 1. We give the bound for the number of such surfaces in this section.

Theorem 6.1. Let $\pi(L)$ be a prime alternating projection of a link L onto S^2 in $Y = S^3$, with n crossings. Let Z be a fixed connected topological surface with Euler characteristic χ . Then the number of ways, up to isotopy, that Z can be properly embedded in $S^3 - N(L)$ as an essential, meridianally incompressible surface is at most

$$(6n)^{80\chi(Z)^2}$$

Proof. For a standard alternating projection of a link onto S^2 in S^3 , there are exactly two chunks in its chunk decomposition, and these are both homeomorphic to balls. Each normal subsurface of Z must be a disk, else it would be compressible within the ball, contradicting the fact that Z is incompressible.

Suppose Z_i , i = 1, ..., k, are all normal subsurfaces of an essential surface Z in chunks that are not *BBBB* or *BBSS* disks. By Lemma 5.4, at most $C(n, \chi(Z)) = (6n)^{-20\chi(Z)}$ curves on the boundary of the chunk could be a boundary component of Z_i . Because each Z_i is a disk, $C(n, \chi(Z))$ therefore gives a bound on the number of possibilities for the disks Z_i . Set aside all Z_i that are *BBBB* and *BBSS* disks. The number of options for all remaining ∂Z_i to be placed on the boundaries of the chunks is at most $C(n, \chi(Z))$. By Theorem 2.8, these surfaces uniquely determine the surface Z. By Lemma 4.1, there are at most $-4\chi(Z)$ such surfaces.

Therefore, $C(n, \chi(Z))^{-4\chi(Z)} = (6n)^{80\chi(Z)^2}$ is an upper bound for the number of such surfaces.

Corollary 6.2. With the same hypotheses on L and $\pi(L)$, the bound in Theorem 6.1 holds if one considers the number of isotopy classes of all properly embedded connected essential and meridianally incompressible surfaces of fixed Euler characteristic χ instead of just one such fixed topological surface.

Proof. This follows directly from the proof of Theorem 6.1. Note that we count all subsurfaces that might compose any surface with Euler characteristic χ in the proof. Since all such surfaces are made up of these subsurfaces, we obtain not just the number of embeddings of one topological surface, but rather the sum of the number of embeddings of all topological surfaces of Euler characteristic χ .

Using similar techniques as in [15], we may almost immediately extend this to a count of essential surfaces, with or without boundary, that are not necessarily meridianally incompressible. The closed orientable surfaces counted in [15] fall into this category, but so do many other surfaces not considered in [15] or [16]. For example, we also consider non-spanning surfaces with a certain non-trivial slope, surfaces in link complements without a component of ∂Z on some of link components (such surfaces may meridianally compress), or surfaces with meridianal boundary on some but not all link components.

Theorem 6.3. Let $\pi(L)$ be a prime alternating projection of a link L onto S^2 in $Y = S^3$ with n crossings. Let Z be a connected topological surface with Euler characteristic $\chi(Z)$, with all boundary components (if any) on N(L). The number of ways, up to isotopy, that Z can be properly embedded in $S^3 - N(L)$ as an essential surface is at most

$$(6n)^{80\chi(Z)^2} 2^{-4\chi(Z)+2}$$

Proof. Perform a maximal number of meridianal compressions on Z. By Lemma 3.1 this yields a surface Z' with the same Euler characteristic as Z and with at most $-4\chi(Z) + 2$ additional boundary components. The number of such surfaces Z' is governed by Theorem 6.1: there are at most $(6n)^{80\chi(Z)^2}$ of these.

To obtain the original Z, we need to tube back together all boundary components created by meridianal compressions. Hence we need to multiply the upper bound by the number of ways to do these tubings. Mossessian studied ways to tube together surfaces in [33]. Although that paper is concerned with closed Heegaard surfaces, the argument in [33, Lemma 3.7] applies in more generality to construct tubed surfaces. It shows that a tubed surface is determined by any $-2\chi(Z) + 1$ element subset of the $-4\chi(Z) + 2$ boundary components of Z' to be tubed. Thus there are at most $\binom{-4\chi(Z)+2}{-2\chi(Z)+1}$ such tubings. The final bound follows from the fact that $\binom{n}{k} \leq 2^n$ for $k \leq n$.

Corollary 6.4. With the same hypotheses on L and $\pi(L)$, the bound in Theorem 6.1 holds if one considers the number of isotopy classes of all properly embedded connected essential surfaces of fixed Euler characteristic χ , instead of just one such fixed topological surface.

Proof. Again this follows directly from the proof of Theorem 6.3 and Corollary 6.2. \Box

7. The number of surfaces in arbitrary 3-manifolds

In Theorem 6.1, each subsurface Z_i is a disk in a chunk that is a ball, and therefore Z_i is uniquely determined by its boundary. More generally, we will have subsurfaces Z_i that can have varying genera. To count the total number of embedded nonisotopic surfaces in such cases, we need a bound on the number of incompressible surfaces embedded in the chunk C with fixed boundary curves and with a fixed genus, both orientable and nonorientable. This will be denoted by X. Assuming we have such a bound, we obtain a bound on the number surfaces embedded in a weakly generalized alternating link exterior, as follows.

Theorem 7.1. Let L be a weakly generalized alternating link in Y, with projection $\pi(L)$ with n crossings on Π , where Y, Π and L satisfy Assumptions 2.1 and 2.9. Suppose that for each 3-manifold component Σ of $Y - N(\Pi)$ there is a universal bound X on the number of isotopy classes of incompressible surfaces properly embedded in Σ with fixed genus and fixed boundary curves on $\partial N(\Pi) \cap \partial \Sigma$.

Fix a topological surface Z, with genus g, Euler characteristic χ , that is either orientable or non-orientable. Then the number of ways $(Z, \partial Z)$ can be properly embedded in $(Y - N(L), \partial N(L))$ as an essential, meridianally incompressible surface, up to isotopy, is at most:

$$(X(q+1))^{-4\chi} \cdot (6n)^{-800\chi^3+80\chi^2}$$

Remark 7.2. Note that g in Theorem 7.1 may refer to orientable or non-orientable genus, which have different relations with Euler characteristic χ as recalled in the beginning of Section 3. Once genus, Euler characteristic, and orientability type are fixed, as in Theorem 7.1, the expression for Euler characteristic in terms of g is determined, as is the number of boundary components of the surface.

Remark 7.3. We do not include a result equivalent to Corollaries 6.2 and 6.4 in this section. The proofs of theorems in this section still construct (and therefore count) any surface of given genus, Euler characteristic and orientability type. But due to the classification of surfaces, once the genus, Euler characteristic and orientability type is fixed, the surface is unique topologically. We are only obtaining embeddings of this surface up to isotopy. We could have reformulated the above theorem as giving the number of non-isotopic embedded surfaces of fixed genus, Euler characteristic and orientability type.

Proof of Theorem 7.1. Recall that an embedded, meridianally incompressible essential surface Z consists of subsurfaces Z_i in chunks. As in Theorem 6.1, each Z_i that is not a *BBBB* or *BBSS* disk can have from 0 to $-10\chi(Z)$ boundary components by Lemma 4.3. Each Z_i can also have genus or nonorientable genus from 0 to g. Moreover, for a fixed collection of boundary components and fixed g, Z_i may be one of at most X subsurfaces by assumption. Suppose first the boundary of Z_i consists of w curves already placed on the boundary of chunks. We then have at most X options for Z_i of genus g' inside its chunk. Since the genus of Z_i may be from 0 to g, we have

$$G = \sum_{i=0}^{g} X = (g+1)X$$

options for a subsurface Z_i with previously fixed boundary.

Now recall the options for ∂Z_i to be placed on faces of the chunks. For Z_i with 0 boundary components, we have one option, namely $Z_i = Z$. For Z_i with one boundary component, we have at most $C = C(n, \chi(Z))$ options by Lemma 5.4. By Lemma 5.2, an option determines ∂Z_i , and by Lemma 5.3, all options determine ∂Z . For Z_i with two boundary components, we have at most C^2 options by the same lemmas, etc. Hence the total number of options for the boundary of Z_i is at most

$$G \cdot 1 + G \cdot C + G \cdot C^{2} + \dots + G \cdot C^{-10\chi(Z)}$$

$$\leq G \cdot C^{-10\chi(Z)+1} \leq (g+1)X \cdot C^{-10\chi(Z)+1} = E$$

By Theorem 2.8, the surface Z is determined by the subsurfaces Z_i that are not *BBBB* and *BBSS* disks. By Lemma 4.1, there are at most $-4\chi(Z)$ such subsurfaces Z_i . Therefore the number of options for Z is at most $E^{-4\chi(Z)}$.

If we expand out E and C, and denote $\chi(Z)$ by χ , we obtain:

$$(X(g+1))^{-4\chi} \cdot (6n)^{-800\chi^3 + 80\chi^2} \qquad \Box$$

Theorem 7.4. With all the hypotheses of Theorem 7.1, consider embedded essential surfaces that are no longer required to be meridianally incompressible. Then the number of such surfaces is at most:

$$(2X(g+1))^{-4\chi+2} \cdot (6n)^{-800\chi^3+80\chi^2}$$

Proof. For every surface Z, we first perform the maximal possible number of meridianal compressions. By Lemma 3.1, we obtain a new surface Z' from Z with $\chi(Z') = \chi(Z)$, and with at most $-4\chi(Z) + 2$ new boundary components. The genus g' of the new surface Z' may have any value from $0, 1, 2, \ldots, g$. Applying Theorem 7.1, we obtain the upper bound for the number of meridianally incompressible surfaces Z' of genus g': $V(g') = (X(g'+1))^{-4\chi} \cdot (6n)^{-800\chi^3+80\chi^2}$.

Since g' may vary, we add options for different genera of meridianally incompressible surfaces, to obtain an upper bound for all of them:

$$V(0) + V(1) + V(2) + \dots + V(g) \le (g+1)V(g).$$

To obtain the original closed surface Z from Z', we need to tube together the punctures introduced by meridian compression. Hence we need to multiply the upper bound for the number of meridianally incompressible surfaces by the number of ways to tube its meridianal punctures. As in the proof of Theorem 6.3, by work of Mossessian [33, Lemma 3.7], the number of tubings producing non-isotopic embedded surfaces is:

$$\begin{pmatrix} -4\chi(Z)+2\\ -2\chi(Z)+1 \end{pmatrix}$$

Hence the bound is:

8. Bounds for isotopy classes of subsurfaces

To apply Theorem 7.1, we need to know bounds on X, the number of isotopy classes of incompressible surfaces properly embedded in a chunk with fixed genus and fixed boundary. Recall that chunks are submanifolds of Y - N(L), bounded by connected components of the projection surface Π . For classical alternating links in S^3 , there are just two chunks, above and below the projection plane, and topologically each one is a 3-ball. The only surfaces in a 3-ball are disks, each uniquely determined up to isotopy by its boundary, i.e. here X = 1. This leads to the results in Section 6 for classical alternating links.

Surprisingly, there is not much in the literature giving such bounds in more general cases. When the surface is incompressible and also boundary incompressible, one can bound the number of isotopy classes of essential surfaces in compact 3manifolds with boundary that are irreducible, boundary irreducible, anannular and atoroidal using techniques from classical normal surface theory; see for example Matveev [27], Jaco and Oertel [21], and Hass, Lagarias and Pippenger [13]. However, for our surfaces in a chunk, we cannot assume boundary incompressibility.

When we consider simultaneously embedded surfaces, i.e. the number of disjoint non-parallel incompressible surfaces properly embedded in a 3-manifold, results are known even in the case that the surface is not boundary incompressible. B. Freedman and M. Freedman gave a bound on the number of simultaneously embedded surfaces with bounded Euler characteristic [9]. However again this is not sufficient for our purposes; we need to count more than just the surfaces that can be simultaneously embedded. Such a count seems only to be known for a few classes of compact 3-manifolds with boundary besides balls. We treat two cases here.

8.1. Surfaces in thickened tori and solid tori. The following is stated by Przytycki [34, Theorem 2.3 and Corollary 2.5].

Theorem 8.1. Let F be a properly embedded incompressible surface in $T^2 \times I$ that is not a boundary parallel disk. Then either

- (1) F is isotopic to an annulus of type $(\gamma) \times I$ for a nontrivial simple closed curve γ in T^2 , or
- (2) F is an annulus or torus parallel to the boundary, or
- (3) *F* is isotopic to a nonorientable surface uniquely determined by two different slopes, one on $T^2 \times \{0\}$ and one on $T^2 \times \{1\}$.

Remark 8.2. It is stated in [34] that these results follow from work of Bredon and Wood [5] and Rubinstein [37] on surfaces in lens spaces. While indeed similar proof techniques can be used, Theorem 8.1 is not stated in that form in those papers.

Similarly, more recent unpublished work of Bartolini [4] gives an alternative proof of uniqueness of the surfaces in Theorem 8.1 (3). However again the fact we need, that all such surfaces in these 3-manifolds have this form, is not stated in that paper. Thus we outline the proof in the Appendix (Section 10) for completeness.

Corollary 8.3. Each incompressible surface that is not parallel to the boundary in a solid torus $S^1 \times D^2$ is determined up to isotopy by a simple closed curve on the boundary torus.

Proof. We may isotope the surface F so that it meets the core of the solid torus transversely in a finite number of points; equivalently, F meets a regular neighbourhood V of the core in a finite number of meridian disks. Then $G = F \cap (S^1 \times D^2 - V)$ is an incompressible surface, possibly with multiple components, in a thickened torus. By Theorem 8.1, each component of G has one of three forms unless it is a boundary parallel disk.

Because F meets V in meridian disks, no component of G will be a boundary parallel disk with boundary on ∂V . If there is a component G_i of G that is an annulus parallel to the boundary ∂V , then isotoping the surface G_i along a boundary compressing disk into V joins two disks of $F \cap V$ with a strip, creating a boundary parallel disk in V that can be isotoped outside of V, reducing the number of components of $V \cap F$. Repeating a finite number of times, we may assume that one of three things holds: (a) G is a vertical annulus with the form of (1) in Theorem 8.1; (b) $F \cap V$ is empty, in which case F is boundary parallel in the solid torus (and also in $T^2 \times I$); (c) G has the form of (3) in Theorem 8.1, hence $F \cap V$ is a single meridian disk. In case (a), F is a compressing disk for $S^1 \times D^2$. In case (c), Theorem 8.1 implies that $F \cap (S^1 \times D^2 - V)$ is nonorientable, and this surface is uniquely determined by its boundary components on $F \cap \partial V$ and on $F \cap (S^1 \times S^1)$. Since the boundary component on $F \cap \partial V$ is a meridian, the surface is determined by $F \cap (S^1 \times S^1)$.

The following result is more concrete than Theorems 7.4 and 7.1, since it does not depend on X. Remark 7.3 still applies here, i.e. the following corollary gives the bound on the number of embedded non-isotopic surfaces with fixed genus (orientable or non-orientable), Euler characteristic and orientability type. Topologically they are all embeddings of the same surface.

Corollary 8.4. Suppose that Π is a torus in the 3-manifold Y having one of the following forms:

- (a) Π is the Heegaard torus in a lens space Y, or
- (b) Π is the torus $T^2 \times \{0\}$ in the thickened torus $Y = T^2 \times [-1, 1]$, or
- (c) Π is a boundary parallel torus within a solid torus Y.

Let L be a weakly generalized alternating link in Y with projection $\pi(L)$ on Π , with a cellular diagram and in cases (a) and (c), representativity $r(\pi(L), \Pi) > 4$. Let n be the number of crossings in the diagram $\pi(L)$. Let Z be a fixed connected topological surface with Euler characteristic χ . Then up to isotopy, the number of ways that $(Z, \partial Z)$ can be properly embedded as an essential, meridianally incompressible surface in $(Y - N(L), \partial N(L))$ is at most:

$$(2(g+1))^{-4\chi} \cdot (6n)^{-800\chi^3 + 80\chi^2}$$

The number of ways to embed it as an essential surface with no restriction on meridianal compressibility is at most:

$$(4(g+1))^{-4\chi+2} \cdot (6n)^{-800\chi^3+80\chi^2}$$

Proof. Observe that Y, Π , and L above satisfy Assumptions 2.1 and 2.9, so Theorem 7.1 and Theorem 7.4 apply.

In all cases, the chunks consist of solid tori or thickened tori. When we isotope a properly embedded essential surface homeomorphic to Z into normal form, it will have boundary only on the torus corresponding to $\partial N(\Pi)$. Hence Theorem 8.1 (in cases (b) and (c)) and Corollary 8.3 (in case (a) and (c)) apply. Therefore genus and boundary curves on $\partial N(\Pi)$ uniquely determine the surface up to isotopy if Z is nonorientable. Theorem 8.1 also allows Z to be a boundary parallel annulus, i.e. Z is then parallel to the torus Π . There are at most two different boundary parallel annuli with the same boundary components. Thus for all these manifolds $X \leq 2$, and we may set X = 2 in Theorem 7.1 and Theorem 7.4.

8.2. Orientable surfaces in thickened surfaces. When we restrict to orientable surfaces, more results are known. For example, the following theorem appears in a paper of Waldhausen from 1968 [39, Corollary 3.2].

Theorem 8.5 (Waldhausen). Suppose G is a properly embedded orientable incompressible surface in the 3-manifold $F \times I$, for F an orientable surface that is not the 2-sphere, and suppose ∂G is contained in $F \times \{1\}$. Then every component of G is boundary parallel, parallel to a surface in $F \times \{1\}$.

Corollary 8.6. Let $\pi(L)$ be a weakly generalised alternating projection of a link L onto a projection surface $\Pi = F \times \{0\} \subset Y = F \times [-1, 1]$, such that $\pi(L)$ is cellular, and has n crossings. Fix a connected, orientable topological surface Z with Euler characteristic χ . Then up to isotopy, the number of ways to properly embed $(Z, \partial Z)$ as an essential, meridianally incompressible surface in $(Y - N(L), \partial N(L))$ is at most:

$$(2(g+1))^{-4\chi} \cdot (6n)^{-800\chi^3 + 80\chi^2}$$

If we do not require meridianal incompressibility, the number of ways is at most:

$$(4(q+1))^{-4\chi(Z)+2}(6n)^{-800\chi^3+80\chi^2}$$

Proof. Note first that Y, Π , and L satisfy Assumptions 2.1 and 2.9. Thus Theorem 7.1 and Theorem 7.4 will apply, once we determine a value for X. The chunk decomposition consists of two chunks of the form $F \times I$. Any embedded essential surface in Y - N(L) with boundary on N(L), when isotoped into normal form, will have boundary on only one side of the chunk, namely the boundary component of $F \times I$ that meets the diagram $\pi(L)$. Then Theorem 8.5 implies that such a surface is boundary parallel when orientable, hence uniquely determined by its boundary curves, with the surface lying on at most two sides of a component of the boundary curve. For these manifolds, we may set X = 2.

Question 8.7. Consider a 3-manifold Σ with a fixed set S of curves on $\partial \Sigma$. Suppose Z is an incompressible (but not neccessarily boundary incompressible) surface of genus g, and $\partial Z = S$. For which families of 3-manifolds Σ does there exists an upper bound on the number of isotopy classes of embeddings of Z that is a constant or depends only on g?

POLYNOMIAL BOUNDS FOR SURFACES

9. Dehn fillings

For manifolds obtained by Dehn filling a link L that satisfies the hypotheses of Theorem 7.1 and Theorem 7.4, we also obtain a bound on the number of embedded surfaces. A result concerning fillings of classical alternating links in the 3-sphere, but excluding finitely many filling slopes, is given in [15]. In this section, both the ambient 3-manifold and the set of slopes are more general.

Theorem 9.1. Let $\pi(L)$ be a weakly generalised alternating projection of a knot L onto a projection surface Π in a compact, irreducible, orientable 3-manifold Y, satisfying Assumptions 2.1 and 2.9. Let the number of crossings of $\pi(L)$ be n. Suppose that there is a universal bound X on the number of isotopy classes of incompressible surfaces properly embedded in Σ with fixed genus and a fixed finite set of boundary curves on $\partial N(\Pi) \cap \partial \Sigma$.

Finally, suppose Y - L is hyperbolic. Take (p,q) to be a nonmeridianal slope of length $\operatorname{len}(p,q) > 2\pi$, and let $Q = 4\pi(g-1)/(\operatorname{len}(p,q)-2\pi)$.

Then the number of isotopy classes of closed orientable genus g surfaces in the manifold obtained by (p,q) Dehn filling on Y - L is at most

(9.2)
$$(2X(g+1))^{-4\chi+2}(6n)^{-800\chi^3+80\chi^2} + \sum_{b=1,\dots,Q} (2X(g+1))^{8g+4b-6}(6n)^{-800(2g+b-2)^3+80(2g+b-2)^2}$$

In particular, the bound is polynomial in n.

Proof. Hass, Rubinstein, and Wang showed in [14, Theorem 4.1] that if Y - L is hyperbolic, then for all but finitely many Dehn filling slopes, the essential surfaces of genus g in the Dehn filling of Y - L along that slope are exactly the essential surfaces in Y - L. Thus for these slopes, the upper bound comes from Theorem 7.4. In general, for all slopes, this is the first term in the sum.

Also in general, for all slopes, if a surface is essential after Dehn filling, then either it was essential before Dehn filling, in which case it will be counted in the first term of the given sum or before Dehn filling it was a genus g essential surface with some number of boundary components, each with slope (p,q) on Y - L. Let b be the number of such boundary components. Then the number of essential surfaces with genus g and b boundary components is counted by Theorem 7.4. For fixed b, there are at most

$$(2X(g+1))^{4(2g+b-2)+2} \cdot (6n)^{-800(2g+b-2)^3+80(2g+b-2)^2}$$

such surfaces. These are the terms in the second part of the sum, summed over all values of b. It remains to bound b.

Let S be an essential surface of genus g embedded in Y - N(L) with b boundary components, each of slope (p,q) on $\partial N(L)$. We may give S a pleating (see, for example [35, Proposition 8.40]); S then inherits a complete hyperbolic metric from the pleating in Y - N(L). Note that the area of S within the cusp of Y - L is at least equal to b times the length of the slope (p,q) (e.g. [35, Lemma 8.44]). Thus $\operatorname{area}(S) \geq b \operatorname{len}(p,q)$. On the other hand, by the Gauss-Bonnet formula we have $\operatorname{area}(S) = -2\pi\chi(S) = 2\pi(2g+b-2)$. It follows that

$$b \operatorname{len}(p,q) - 2b\pi \le 4\pi(g-1), \quad \text{or} \quad b \le \frac{4\pi(g-1)}{\operatorname{len}(p,q) - 2\pi} = Q.$$

Thus summing over all possible integers b in this range gives the result.

If we adjust our hypotheses on the link and the filling slope slightly, the fact that Y - L is hyperbolic will be automatic, and similarly we obtain a bound on the slope length, giving the following.

Corollary 9.3. Let $\pi(L)$ be a weakly generalised alternating projection of a knot Lonto a projection surface Π , with n crossings, in a 3-manifold Y, satisfying Assumptions 2.1 and 2.9 as usual. Suppose further that $Y - N(\Pi)$ contains no essential annuli with both boundary components on ∂Y . Suppose there is a universal bound X on the number of isotopy classes of incompressible surfaces properly embedded in each component of $Y - N(\Pi)$ with fixed genus and fixed boundary. Let $\sigma = (p, q)$ be a slope on $\partial N(K)$, with $|q| > 5.627(1 - \chi(\Pi)/n)$.

Then the number of isotopy classes of closed orientable genus g surfaces in the manifold obtained by (p,q) Dehn filling of Y - L is bounded above by a polynomial function of n, equal to the bound of (9.2).

Proof. Under the given assumptions, Y - L is hyperbolic by [19, Theorem 1.1]. It is shown in the proof of [19, Corollary 7.2] that the length of σ is at least

$$\operatorname{len}(\sigma) \ge \frac{3.35n|q|}{3(n-\chi(\Pi))}.$$

This is at least 2π under the given assumption on q, so Theorem 9.1 holds.

10. Appendix: Proof of Theorem 8.1

Proof of Theorem 8.1. First suppose F is both incompressible and boundary incompressible. If it is orientable, then it must be vertical or horizontal; see for example [20, Theorem VI.34]. In $T^2 \times I$, a vertical surface is of the form $\{\gamma\} \times I$, and a horizontal surface is a torus parallel to the boundary. A non-orientable surface will be pseudo-horizontal or pseudo-vertical in general, as defined and proved by Frohman [10]. However, in $T^2 \times I$, both of these definitions reduce to the above notion of horizontal and vertical, and we are done.

Now assume F is boundary compressible.

If a component of ∂F bounds a disk D on $T^2 \times \{0\}$ or $T^2 \times \{1\}$, then because F is incompressible, ∂D pushed slightly into F bounds a disk in F; it follows that F is a boundary parallel disk, contradicting the hypothesis. So we may suppose that each component of ∂F is essential.

Consider an essential boundary compression disk D for F. The boundary ∂D consists of two arcs $\partial D = \alpha \cup \beta$, with $\alpha \subset F$ and $\beta \subset T^2 \times \{0\}$ or $T^2 \times \{1\}$; without loss of generality, say $T^2 \times \{0\}$. Suppose first that the endpoints of α lie on distinct components γ_1 and γ_2 of ∂F . Then $(T^2 \times \{0\}) - (\gamma_1 \cup \gamma_2)$ consists of two annuli, one containing β , with β being an essential arc on the annulus. This is depicted in Figure 2, on the left. Then $(T^2 \times \{0\}) - N(\beta \cup \gamma_1 \cup \gamma_2)$ has a disk component E in $T^2 \times \{0\}$. The disk is depicted in Figure 2, on the right. Consider the arcs on F given by $\partial N(\alpha) \cap F - N(\partial \alpha)$. Take the union of these with arcs $\gamma_1 \cup \gamma_2 - N(\partial \alpha)$ on



FIGURE 2. Left: The disk D meeting distinct curves on $T^2 \times \{0\}$. Right: The disk E and the disk $D \cup E$.



FIGURE 3. Left: an arc of γ cannot run to the same side of D. Right: Thus $F \cap (T^2 \times [0, \epsilon_1])$ is the union of an annulus and a Möbius band, for ϵ_1 small.

 T^2 . The resulting closed curve bounds a disk $E \cup \partial N(D)$ in $T^2 \times I$, also depicted in Figure 2, on the right. The disk can be isotoped to be parallel to a disk in $T^2 \times \{0\}$. Incompressibility of F implies that it must bound a disk in F as well. It follows that F is a boundary parallel annulus.

So suppose that the arc α has both endpoints on the same curve of ∂F . The arc β cannot cut off a disk E in $T^2 \times \{0\} - \partial F$, else $E \cup D$ would be a compression disk for F. Thus β is an essential arc in an annulus $T^2 \times \{0\} - \partial F$. It follows that ∂F has only one component on $T^2 \times \{0\}$. Thus an arc γ of ∂F runs from one endpoint of $\partial \alpha$ to the other.

Because γ is an essential curve on the torus, it runs from one side of D to the opposite side, as in Figure 3, left. It cannot run to the same side of D, else $\gamma \cup \beta$ would bound a disk E on $T^2 \times \{0\}$, and $E \cup D$ would be a compressing disk for F.

After an isotopy of F that pushes α close to $T^2 \times \{0\}$, for small $\epsilon_1 > 0$ the surface $F \cap T^2 \times [0, \epsilon_1]$ consists of $N(\partial F) \cup N(\alpha) \subset F$. This is the union of an annulus $N(\partial F)$ with a strip $N(\alpha)$ as in Figure 3, right. The strip must connect one side of the annulus $N(\partial F)$ to the other, else γ would run to the same side of D, contradicting the above paragraph or the fact that α intersects only one component γ of ∂F . So $N(\partial F) \cup N(\alpha)$ is nonorientable, and $F \cap T \times [0, \epsilon_1]$ is a Möbius band with a hole removed. One boundary component lies on $T^2 \times \{0\}$, the other on $T^2 \times \{\epsilon_1\}$. Observe that adding $N(\alpha)$ to $N(\partial F)$ adds -1 to the Euler characteristic. Observe also that the boundary component on $T^2 \times \{\epsilon_1\}$ is obtained from that on $T^2 \times \{0\}$ by surgering a neighborhood of β . That is, we remove a neighborhood of $\partial\beta$ from the slope, and attach $\partial N(\operatorname{int}(\beta))$. The result is that the slopes of the curves on $T^2 \times \{0\}$ and $T^2 \times \{\epsilon_1\}$ have intersection number exactly two on T^2 .

Now repeat the argument, applied to $F \cap T^2 \times [\epsilon_1, 1]$. If there is another boundary compressing disk toward $T^2 \times \{\epsilon_1\}$, then again there will be some $\epsilon_2 > \epsilon_1$ so that $T^2 \times [\epsilon_1, \epsilon_2] \cap F$ is a Möbius band with a hole. Thus F is obtained by stacking two of these, yielding a nonorientable surface with genus 2, and unique boundary components on $T^2 \times \{0\}$ and $T^2 \times \{\epsilon_2\}$, with the slope on $T^2 \times \{\epsilon_2\}$ intersecting that on $T^2 \times \{\epsilon_1\}$ exactly twice. This process must terminate with some ϵ_n , because the Euler characteristic of F is finite. This implies that $\epsilon_n = 1$, and we have constructed a nonorientable surface with two boundary components on $T^2 \times \{0\}$ and $T^2 \times \{1\}$, as in case (3). This proves that any incompressible surface in $T^2 \times I$ is as claimed.

Finally, consider uniqueness of the nonorientable surfaces with fixed boundary components. At each step of the proof, we built a surface that is a Möbius band with a hole, with one boundary component on $T^2 \times \{\epsilon_i\}$ and one on $T^2 \times \{\epsilon_{i+1}\}$, and the boundary curves intersecting exactly twice. Adjust the framing on $T^2 \times \{0\}$ so that the original slope $F \cap T^2 \times \{0\}$ is 0/1, and together with a choice of slope 1/0this forms a basis for the fundamental group of T^2 . The construction above then starts with the slope 0/1, and adds a band to the surface to obtain a new boundary slope of the form $\pm 2/q$, intersecting 0/1 exactly twice. At each step, we replace a slope with even numerator by one meeting the first exactly twice, hence the result continues to have even numerator.

Recall that slopes on the torus correspond to elements of $\mathbb{Q} \cup \{1/0\}$. These can be viewed as vertices of the Farey triangulation of \mathbb{H}^2 : identifying \mathbb{H}^2 with the upper half plane, the vertices of the Farey triangulation are points of $\mathbb{Q} \cup \{\infty\}$ on the real line, and the edges run between reduced pairs p/q, r/s if and only if $ps - qr = \pm 1$. Here, ps - qr is the (signed) intersection number of the slopes.

We consider slopes with even numerator and draw an edge between them if they have intersection number ± 2 . Equivalently, we may consider slopes with odd denominator and the edges between them with intersection number ± 1 . This gives a subset of the usual Farey triangulation. Observe that this subset, consisting only of vertices with odd denominators and the edges between them, forms a connected tree; see for example [4, Section 3.1]. Thus for any even slope 2p/q, by following the unique path in this subset of the Farey tree from 0/1 to 2p/q, we may build a nonorientable surface in $T^2 \times [0, 1]$ with slopes 0/1 on $T^2 \times \{0\}$ and 2p/q on $T^2 \times \{1\}$, where following an edge corresponds to adding an appropriate band to the surface.

Observe that traversing an edge, and then returning along it right away, constructs a surface with a compression disk. Thus the construction proceeds monotonically through the Farey tree, and the surface is unique up to isotopy, by uniqueness of the path through the Farey tree. Therefore the pair of slopes uniquely determines the nonorientable surface. $\hfill\square$

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Jessica Purcell School of Mathematical Sciences Monash University 9 Rainforest Walk, Room 401, VIC 3800, Australia jessica.purcell@monash.edu

Anastasiia Tsvietkova Department of Mathematics and Computer Science Rutgers University-Newark 101 Warren Street, Newark, NJ 07102, USA a.tsviet@rutgers.edu

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