

RW Rouse Model

harmonic Hamiltonian

$$\dot{\vec{r}}_n = -\mu \frac{\partial \mathcal{H}}{\partial \vec{r}_n} + \vec{f}_n$$



transformed to normal modes \vec{X}_p

$$\dot{\vec{X}}_p = -\mu \frac{\partial \mathcal{H}}{\partial \vec{X}_p} + \vec{f}_p$$

INDEPENDENT
MODEL

↳ Brownian motion in a harm. pot.

$$\frac{\langle \vec{x}_p(t) - \vec{x}_p(0) \rangle}{\langle \vec{x}_p^2 \rangle} = \exp\left(-\frac{t}{\tau_p}\right)$$

$$\tau_p = \frac{b^2}{n \mu k_B T} \frac{1}{\sin^2\left(\frac{p\pi}{2N}\right)} \approx \frac{b^2}{3\pi^2 \mu k_B T} \left(\frac{N}{p}\right)^2$$

p small

$$\tau_R \equiv \tau_1 \propto N^2$$

$$\langle \Delta R_{cm}^2 \rangle = 6D_{cm}t, \quad D_{cm} = \frac{\mu k_B T}{N}$$

$$\langle \Delta R_{cm}^2 \rangle \Big|_{t=t_R} = \frac{\pi}{\pi^2} \langle R_G^2 \rangle$$

mean square displacement of a monomer

$$\Delta \vec{r}_n = \sum_p \phi_{np} \Delta \vec{x}_p$$

modes are
independent
↓

$$\langle \Delta \vec{r}_n^2 \rangle = \sum_p \sum_q \phi_{np} \phi_{nq} \langle \Delta \vec{x}_p \cdot \Delta \vec{x}_q \rangle =$$

$$= \sum_p \phi_{np} \phi_{np} (\Delta \bar{X}_p^2)$$

average over monomers

$$\langle \Delta r^2 \rangle = \frac{1}{N} \sum_n \langle \Delta \bar{r}_n^2 \rangle =$$

$$= \sum_p \langle \Delta \bar{X}_p^2 \rangle \underbrace{\frac{1}{N} \sum_n \phi_{np} \phi_{np}}_{=1} = \frac{1}{N} \sum_p \langle \Delta \bar{X}_p^2 \rangle$$

$$p=0: \quad \vec{X}_0 = \frac{1}{\sqrt{N}} \sum_n \vec{r}_n$$

$$\Delta \vec{X}_0 = \frac{1}{\sqrt{N}} \sum_n \Delta \vec{r}_n = \sqrt{N} \Delta \vec{R}_{cm}$$

$$\langle \Delta \vec{X}_0^2 \rangle = N \langle \Delta \vec{R}_{cm}^2 \rangle, \quad \frac{1}{N} \langle \Delta \vec{X}_0^2 \rangle = \langle \Delta \vec{R}_{cm}^2 \rangle$$

$$\langle \Delta r^2 \rangle = \langle \Delta \vec{R}_{cm}^2 \rangle + \frac{1}{N} \sum_{p=1}^{N-1} \langle \left[\vec{X}_p(t) - \vec{X}_p(0) \right]^2 \rangle$$

$$\langle [\bar{X}_p(t) - \bar{X}_p(0)]^2 \rangle =$$

$$\langle \bar{X}_p(t)^2 \rangle + \langle \bar{X}_p(0)^2 \rangle - 2\langle \bar{X}_p(t) \bar{X}_p(0) \rangle =$$

$$= 2\langle \bar{X}_p^2 \rangle - 2\langle \bar{X}_p(t) \bar{X}_p(0) \rangle =$$

$$= 2\langle \bar{X}_p^2 \rangle \left[1 - \exp\left(-\frac{t}{\tau_p}\right) \right]$$

$$= \frac{b^2}{2 \sin^2\left(\frac{p\pi}{2a}\right)} \left[1 - \exp\left(-\frac{t}{\tau_p}\right) \right]$$

$$\langle \Delta \bar{r}^2 \rangle = \langle \Delta \bar{R}_{cm}^2 \rangle + \frac{b^2}{2N} \sum_{p=1}^{N-1} \frac{1 - \exp(-t/\tau_p)}{\sin^2\left(\frac{p\pi}{2N}\right)}$$

$$\approx \langle \Delta \bar{R}_{cm}^2 \rangle + \frac{b^2}{2N} \left(\frac{2N}{\pi}\right)^2 \sum_{p=1}^{\infty} \frac{1}{p^2} \left[1 - \exp\left[-\frac{3\pi^2 \mu k_B T}{b^2} \frac{p^2}{N^2} t\right] \right]$$

$$\approx \langle \Delta \bar{R}_{cm}^2 \rangle + \frac{2}{\pi^2} b^2 N \int_0^{\infty} dx \frac{1}{x^2} \left[1 - \exp(-a x^2) \right]$$

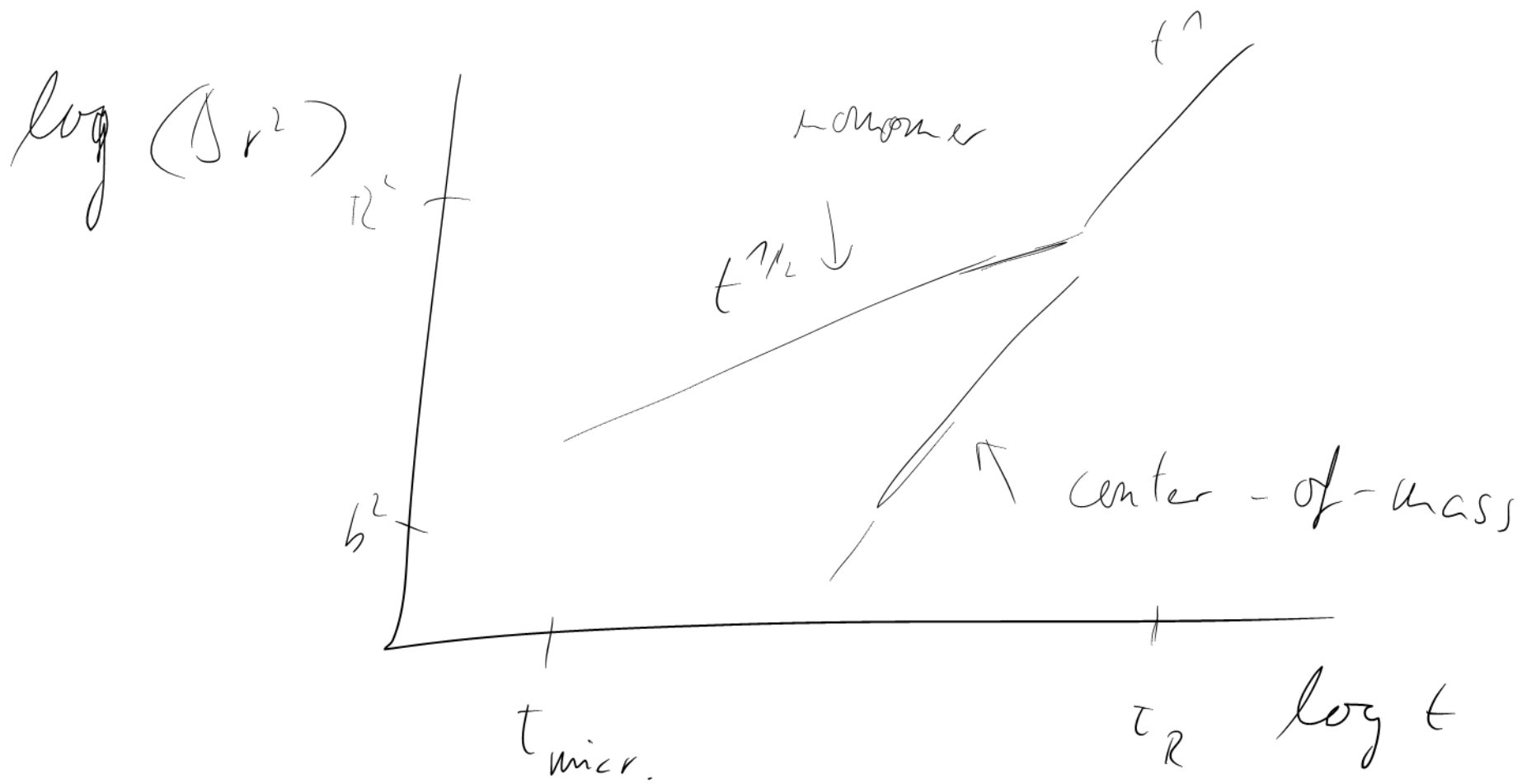
$a = \frac{3\pi^2 \mu k_B T t}{b^2 N^2}$
 $\sqrt{\pi a}$

$$= \langle \Delta \vec{R}_{cm}^2 \rangle + \frac{2}{\pi^2} b^2 N \sqrt{3\pi} \frac{\pi}{bN} \sqrt{\mu k_B T t} =$$

$$= \langle \Delta \vec{R}_{cm}^2 \rangle + 2 \sqrt{\frac{3}{\pi}} b \sqrt{\mu k_B T t} \quad \hookrightarrow t^{1/2}$$

$$t = t_R \Rightarrow \sqrt{\mu k_B T t_R} = \sqrt{\frac{b^2}{3\pi^2} N^2} = \frac{bN}{\sqrt{3}\pi}$$

$$\langle \Delta r^2 \rangle \Big|_{t=t_R} = \frac{12}{\pi^2} R_g^2 + \frac{2}{\pi^{3/2}} b^2 N = \frac{12}{\pi^2} R_g^2 + \frac{12}{\pi^{3/2}} R_g^2$$



$$\mu k_B T \tau_{micr} = b^2$$

$$\frac{\mu k_B T}{N} \tau_R = R^2$$

5.5. Dynamic Scaling

recall chain statistics for RW / SAW

NO length scale in the problem except

b and $R \rightarrow$ power law $R_{\zeta} \propto N^{\nu}$

$$\nu = 0.5 \text{ RW}$$

$$\nu = 0.6 \text{ SAW}$$

dynamics

No time scale between

$$\tau_{\text{micro}} \approx \frac{b^2}{\mu b_0 T}$$

and

τ_R = relaxation time of the whole chain

→ power law

$$\tau_R \propto N^{\nu z} \propto R^z$$

ζ : "dynamic exponent"

links time scales and length scales

τ_R \rightarrow diffusion: After τ_R , the chain

has just moved its own size

$D \equiv$ diffusion constant of the whole chain:

$$D \tau_R \sim R^2 \Rightarrow D R^z \propto R^2 \Rightarrow D \propto R^{2-z}$$

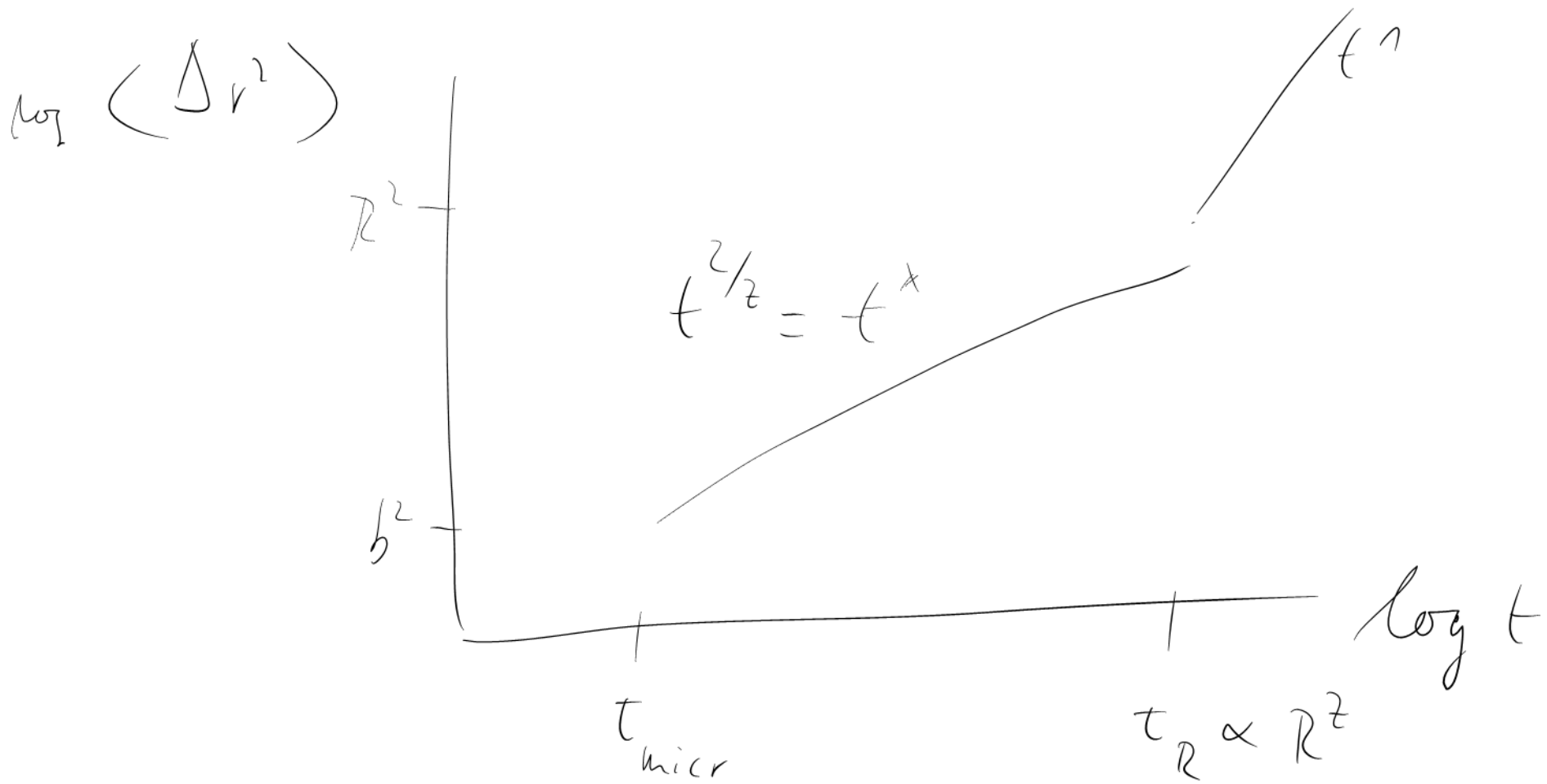
→ z can be inferred from a model for $D(R)$

RW Rouse model:

$$\langle \Delta \vec{R}_{(u_n)}^2 \rangle \propto \frac{6\mu k_B T}{N} t \quad \rightarrow \quad D \propto \frac{1}{N}$$

$$D \propto \frac{1}{R^2} = R^{-2} \stackrel{!}{=} R^{2-z} \quad \Rightarrow \quad \underline{\underline{z=4}}$$

$$\tau_R \propto R^4 \propto \underline{\underline{N^2}}$$



$$\frac{t_R}{t_{micr}} = \left(\frac{R}{b}\right)^2 \quad \text{and} \quad \left(\frac{t_R}{t_{micr}}\right)^x = \frac{R^2}{b^2} \quad | \quad ()^{1/x}$$

$$\Rightarrow z = \frac{z}{x} \quad x = \frac{z}{z}$$

RW Rouse: $z = \zeta \rightarrow \underline{\underline{t^{1/2}}}$

General Rouse model (excluded volume)

$$\ddot{r}_n = -\mu \frac{\partial \mathcal{H}}{\partial r_n} + \ddot{f}_n$$



but \mathcal{H} is no longer harmonic

\rightarrow no exact solution

$$\vec{P}_{cm} = \frac{1}{N} \sum_n \vec{p}_n = \frac{1}{N} \sum_n \vec{F}_n$$

↑
Newton III

$$\Rightarrow D_{cm} = \frac{M k_B T}{N} \quad \text{as before}$$

friction coefficients, add up!

$$D \propto N^{-1} \propto R^{-1/\nu} \stackrel{!}{=} R^{2-z}$$

$$R \propto N^\nu \rightarrow N^{-1} \propto R^{-1/\nu}$$

$$z = 2 + \frac{1}{\nu}$$

SAW Rowse mode $z \approx 3.7$

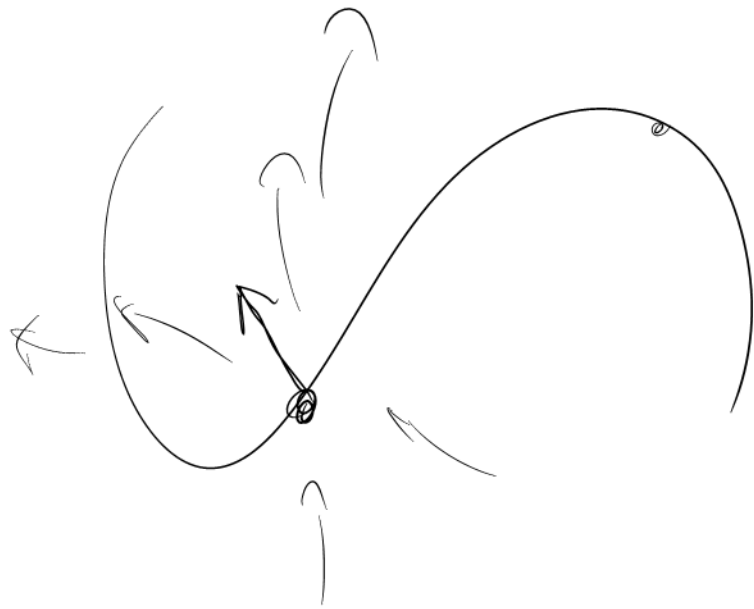
$$(\Delta r^2) \sim t^{2/3.7} \sim t^{0.54}$$



5.6. Zimm Model

Hydrodynamic interactions

polymer in solvent



particle kicked

+ hydrodynamic flow

- spreads out quickly

(hydrodynamics \equiv

diffusive momentum transport, $z = 2$)

→ another observer will see that
flow (practically instantaneously!)

→ CORRELATIONS in the stochastic
displacements!

→ these correlations are long-range
(flow decays like $1/r$)

single particle : $\langle \Delta r^2 \rangle = 6D t$

many particles, correlated:

$$\langle \Delta r_i^\alpha \Delta r_j^\beta \rangle = 2 D_{ij}^{\alpha\beta} t, \quad t \text{ small}$$

α, β : Cartesian indexes

↑
diffusion tensor

$$D_{ij}^{\alpha\beta} = D_{ij}^{\alpha\beta}(\{\vec{r}_i\})$$

correlates monomers i and j

Einstein: $D_{ij}^{\alpha\beta} = k_{BT} \mu_{ij}^{\alpha\beta}$

↳ mobility tensor

Langevin:

$$\dot{r}_i^\alpha = \sum_j \mu_{ij}^{\alpha\beta} F_j^\beta + f_i^\alpha$$

$$\langle f_i^\alpha(t) f_j^\beta(t') \rangle = 2k_{BT} \mu_{ij}^{\alpha\beta} \delta(t-t')$$

Smoluchowski

$$\frac{\partial}{\partial t} P(\{\vec{r}_i\}, t) = \sum_{ij} \frac{\partial}{\partial \vec{r}_i} \cdot \overleftrightarrow{D}_{ij} \cdot \left(\frac{\partial}{\partial \vec{r}_j} - \beta \overleftrightarrow{F}_j \right) P$$

interpretation of $\overleftrightarrow{M}_{ij}$

$\overleftrightarrow{M}_{ij} \cdot \frac{\partial}{\partial \vec{r}_j} \equiv$ flow field that particle i sees,
as a result of all the forces

Strategy:

- calculate \vec{T} from hydrodynamics
- " D_{cm}
- infer $D_{cm}(R)$
- read off z
- apply dynamic scaling

$$\langle \Delta r_i^\alpha \Delta r_j^\beta \rangle = 2k_B T \mu_{ij}^{\alpha\beta} t + O(t^{3/2}) \quad t \rightarrow 0$$

$$\langle \Delta \vec{R}_{cm}^2 \rangle = \left\langle \left[\frac{1}{N} \sum_i \Delta r_i^\alpha \right] \left[\frac{1}{N} \sum_j \Delta r_j^\alpha \right] \right\rangle$$

$$= \frac{1}{N^2} \sum_{ij} \langle \Delta r_i^\alpha \Delta r_j^\alpha \rangle =$$

$$= \frac{2k_B T t}{N^2} \sum_{ij} \langle \mu_{ij}^{\alpha\alpha} \rangle = \frac{2k_B T t}{N^2} \sum_{ij} \text{Tr} \langle \hat{\mu}_{ij} \rangle$$

$$D = \frac{1}{3} \frac{k_B T}{N^2} \sum_{ij} \tau_r \langle \vec{\mu}_{ij} \rangle$$

short-time diffusion coefficient

assume: long-time " " "
($t \gg \tau_R$) is essentially the same
(seems reasonably justified)

$$i=j \quad \langle \vec{\mu}_{ii} \rangle = \mu_0 \uparrow$$

μ_0 known
mobility

$$D = \frac{\mu_0 k_B T}{N} + \frac{1}{3} \frac{k_B T}{N^2} \sum_{i \neq j} \text{Tr} \langle \vec{\mu}_{ij} \rangle$$

↓
Rouse

+ contribution from
hydrodyn. interactions

$\vec{h}_{ij} \equiv \dots$

$\vec{h}_{ij} = \vec{F}_j$ is flow field

at position \vec{r}_i , generated by force \vec{F}_j

problem: \vec{F} at origin \rightarrow what flow field?

stationary \leftarrow

$$\eta \nabla^2 \vec{u} - \nabla p + \vec{F} \delta(\vec{r}) = 0$$

η shear viscosity \rightarrow flow field (velocity) \rightarrow pressure

$$\nabla \cdot \vec{u} = 0$$

incompressibility

$$\vec{u}(\vec{r}) = \frac{1}{(2\pi)^3} \int d^3\vec{k} \vec{v}(\vec{k}) \exp(-i\vec{k} \cdot \vec{r})$$

$$\delta(\vec{r}) = \frac{1}{(2\pi)^3} \int d^3\vec{k} \exp(-i\vec{k} \cdot \vec{r})$$

$$p(\vec{r}) = \frac{1}{(2\pi)^3} \int d^3\vec{k} \tilde{p}(\vec{k}) \exp(-i\vec{k} \cdot \vec{r})$$

$$-\eta k^2 \vec{v} + i\vec{k} \tilde{p} + \vec{F} = 0 \quad | \vec{k}.$$

$$\vec{k} \cdot \vec{v} = 0$$

$$i k^2 \tilde{p} + \vec{k} \cdot \vec{F} = 0 \Rightarrow \tilde{p} = -i \frac{\vec{k} \cdot \vec{F}}{k^2}$$

$$i \vec{k} \cdot \tilde{p} = -\frac{1}{k^2} \vec{k} (\vec{k} \cdot \vec{F}) = -(\hat{k} \otimes \hat{k}) \vec{F}$$

$$\hat{k} = \frac{\vec{k}}{k} \text{ unit vector}$$

↑ tensor product

$$\vec{v} = \frac{1}{\gamma k^2} \left[\mathbb{1} - \hat{k} \otimes \hat{k} \right] \vec{F}$$

How field in
Fourier space

mobility tensor in Fourier space

$$\vec{\mu}(\vec{r}) = \frac{1}{(2\pi)^3} \int d^3\vec{k} \frac{1}{\eta k^2} \left(\mathbb{1} - \hat{k} \otimes \hat{k} \right) \exp[-i\vec{k} \cdot \vec{r}] =$$

$$= \frac{1}{8\pi\eta r} \left(\mathbb{1} + \hat{r} \otimes \hat{r} \right)$$

without
proof

$$\text{Tr} \vec{\mu} = \frac{2}{(2\pi)^3} \frac{1}{\eta} \int d^3\vec{k} \frac{1}{k^2} \exp(-i\vec{k} \cdot \vec{r}) =$$

$$= \frac{2}{(2\pi)^3} \frac{1}{\eta} C_{1\pi} \int_0^{\infty} dk k^2 \frac{1}{k^2} \frac{\sin(kr)}{kr} =$$

$$= \frac{1}{\pi^2} \frac{1}{\eta r} \underbrace{\int_0^{\infty} dx \frac{\sin x}{x}}_{\pi/2} = \frac{1}{2\pi \eta r}$$

$$\left. \frac{1}{3} \text{Tr} \tilde{\mu} = \frac{1}{6\pi \eta r} \right\}$$

$$D = \frac{M_0 k_B T}{N} + \frac{k_B T}{6\pi\eta} \underbrace{\frac{1}{N^2} \sum_{i \neq j} \left\langle \frac{1}{r_{ij}} \right\rangle}_{\left\langle \frac{1}{R_H} \right\rangle}$$

for large N ,
hydrodynamic
term dominates,

$$D = \frac{M_0 k_B T}{N} + \frac{k_B T}{6\pi\eta} \left\langle \frac{1}{R_H} \right\rangle$$

hydrodynamic
radius

$$R_H \sim R_G \sim N^\nu \quad \nu = \begin{matrix} 1/2 & \text{RW} \\ 0.6 & \text{SAW} \end{matrix}$$

$$D \sim \frac{1}{R}$$

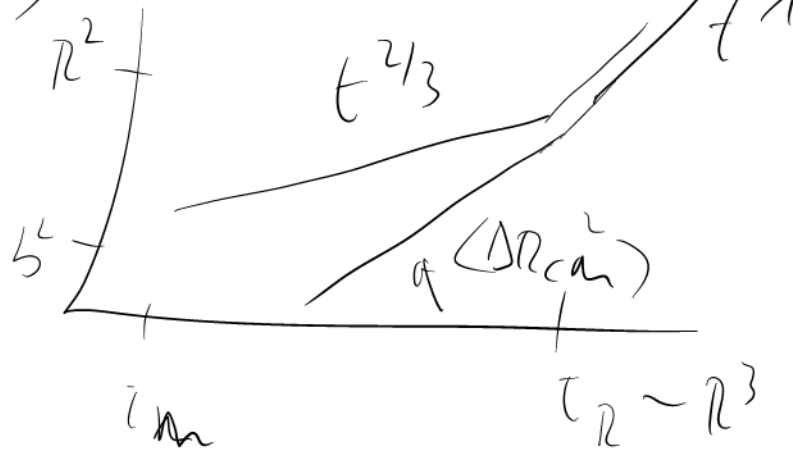
Zinn chain behaves
like a Stokes sphere
("non-free draining")

$$D \sim R^{-1} \sim R^{2-z}$$

$$z = 3$$

$$t^{2/2} = t^{2/3}$$

$\log(Dr^2)$



$$t_R \sim R^3$$

$\log t$