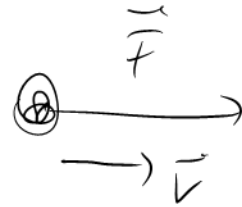


$$p(\vec{r}, t + \frac{a^2}{6D}) = \frac{1}{6} \sum_i p(\vec{r} + a\vec{e}_i, t)$$

$$\partial_t p = D \nabla^2 p$$

What happens if we introduce an external force $\vec{F}(\vec{r}, t)$?



$$\vec{v} = \mu \vec{F}$$

drift velocity mobility

overdamped motion,
no inertia
~ mass unimportant!

New Master eq.

$$p(\vec{r}, t + \frac{a^2}{6D}) = \frac{1}{6} \sum_i p(\vec{r} + a\vec{e}_i, t)$$

$$+ \sum_i T_i(\vec{r} + a\vec{e}_i, t) p(\vec{r} + a\vec{e}_i, t)$$

→ "transfer coefficient", encodes the effect of \vec{T}

$$\sum_i T_i(\vec{r}, t) = 0 \quad \text{conservation of probability}$$

$$T_i = ???$$

require: - T_i dimensionless

- T_i scalar

- $T_i \propto \ddot{F}$ linear response

$$\Rightarrow T_i \propto \ddot{F} \cdot (\text{some vector})$$

$$\hookrightarrow \ddot{c}_i$$

$$T_i \propto \ddot{F} \cdot \ddot{c}_i \rightarrow \text{dimensionless}$$

$$\hookrightarrow \text{unit: } \frac{\text{kg m}}{\text{s}^2}$$

get rid of kg: divide by $k_B T$, or

multiply by $\beta = 1/k_B T$ \hookrightarrow unit: $\frac{\text{kg m}^2}{\text{s}^2}$

$$\Rightarrow T_i \propto \beta \vec{F} \cdot \vec{c}_i \quad \text{unit: } \frac{1}{\text{m}} \text{ (meter)}$$

$$\Rightarrow T_i \propto a \beta \vec{F} \cdot \vec{c}_i \quad (a \text{ is only length})$$

$$\rightarrow T_i = A a \beta \vec{F} \cdot \vec{c}_i \quad A \text{ numerical prefactor}$$

$$\hookrightarrow \sum_i T_i = 0 \quad \text{conservation law}$$

$$p(\vec{r}, t + \frac{a^2}{6D}) = \frac{1}{6} \sum_i p(\vec{r} + a\vec{e}_i, t)$$

$$+ A a \beta \sum_i c_{i\alpha} F_\alpha(\vec{r} + a\vec{e}_i, t) p(\vec{r} + a\vec{e}_i, t)$$

$$F_\alpha(\vec{r} + a\vec{e}_i, t) p(\vec{r} + a\vec{e}_i, t) \simeq$$

$$F_\alpha(\vec{r}, t) p(\vec{r}, t) + a c_{i\alpha} \partial_\alpha F_\alpha(\vec{r}, t) p(\vec{r}, t) + O(a^2)$$

↓
not needed

$$\sum_i c_{i\alpha} F_\alpha(\vec{r} + a\vec{e}_i, t) p(\vec{r} + a\vec{e}_i, t) \simeq$$

$$a \cdot 6 \cdot \frac{1}{3} \sum_\alpha \partial_\alpha F_\alpha(\vec{r}, t) p(\vec{r}, t) = 2a \partial_\alpha F_\alpha(\vec{r}, t) p(\vec{r}, t)$$

$$\frac{a^2}{6D} \partial_t p(\vec{r}, t) = \frac{a^2}{6} \nabla^2 p(\vec{r}, t) + 2 A a^2 \beta(\vec{D}, \vec{F}) p(\vec{r}, t)$$

$$\partial_t p(\vec{r}, t) = D \nabla^2 p(\vec{r}, t) + 12 A D \beta(\vec{D}, \vec{F}) p(\vec{r}, t) \quad \left| \frac{1}{a^3} \right.$$

$$\left| \partial_t P = D \vec{D} \cdot \left[\vec{D} + 12 A \beta \vec{F} \right] P(\vec{r}, t) \right|$$

Smoluchowski equation

$$A = 2, 2, 2$$

force \vec{F} \leftrightarrow potential U $\vec{F} = -\vec{\nabla}U$
(t -independent)

$t \rightarrow \infty$ $P \longrightarrow$ const. $\cdot \exp(-\beta U)$

$$0 = \vec{\nabla} \cdot [\vec{\nabla} + \eta A \beta \vec{F}] \exp(-\beta U)$$

$$\vec{\nabla} \exp(-\beta U) = \exp(-\beta U) (-\beta) \vec{\nabla} U = \beta \vec{F} \exp(-\beta U)$$

$$0 = \vec{\nabla} \cdot [1 + \eta A] \beta \vec{F} \exp(-\beta U) \quad \left(A = -\frac{1}{\eta} \right)$$

$$\Rightarrow \partial_t P = D \nabla \cdot [\nabla - \beta \vec{F}] P$$

final Smoluchowski equation

interpretation as a continuity equation

$$\partial_t P + \nabla \cdot \vec{j} = 0$$

$$\vec{j} = \underbrace{-D \nabla P}_{\text{diffusive current}} + \underbrace{D \beta \vec{F} P}_{\text{drift current}}$$

on the other hand: ↙ drift velocity

$$\text{drift current} = \bar{v} p$$

$$\leadsto \bar{v} = D \beta \bar{F} \quad \text{def. mobility: } \bar{v} = \mu \bar{F}$$

$$\mu = D \beta \quad \left(D = k_B T \mu \right)$$

→ Einstein relation (example of the fluctuation-dissipation theorem)

$$\vec{v} = \mu \vec{F}$$

$$\vec{F} = \zeta \vec{v}$$

L) $\zeta = \frac{1}{\mu}$ friction coefficient

5.3. Langevin Equation

Back to the particle hopping on the lattice

$$\vec{r}(t+h) = \vec{r}(t) + a \vec{c}_i$$

\vec{r}
position of the particle

\vec{c}_i
random variable,
just the direction
that the particle
has picked

$$\Delta \vec{r} = \vec{r}(t+\Delta t) - \vec{r}(t) = a \vec{c};$$

is a random variable

$\langle \Delta \vec{r} \rangle$ mean displacement

$\langle \Delta \vec{r}^2 \rangle$ "square"

$\langle \Delta \vec{r}^k \rangle$ mean kth displacement

$$\langle \Delta \vec{r}^k \rangle = a^k \underbrace{\langle \vec{c}^k \rangle}_{\text{order one!}} = O(a^k)$$

BUT for the asymptotic behavior

we only need to be accurate up to $O(a^2)$

→ only needed (\vec{c}) , (\vec{c}^2)

$(\vec{c}^k) = \sum_i \vec{c}_i^k p_i$ transition probability, or
prob. to pick a jump in
direction i

we know

$$p_i = \frac{1}{6} - T_i \quad \text{jump in direction } -\vec{c}_i \quad \Downarrow$$

$$p_i = \frac{1}{6} - T_i = \frac{1}{6} - A a \beta \vec{F} \cdot \vec{c}_i = \downarrow A = -1/12$$

$$= \frac{1}{6} + \frac{1}{12} a \beta \vec{F} \cdot \vec{c}_i$$

$a \rightarrow 0$

$(h \rightarrow 0) :$

diffusion dominates

$$\langle c_x \rangle = \sum_i p_i c_{ix} = \frac{1}{6} \underbrace{\sum_i c_{ix}}_{=0}$$

$$+ \frac{1}{12} a \beta F_x \underbrace{\sum_i c_{iy} c_{ix}}_{2 \delta_{xy}} = \frac{1}{6} a \beta F_x$$

$$\langle a \bar{c} \rangle = \frac{a^2}{6} \beta \bar{F}$$

$$\langle c_\mu c_\nu \rangle = \sum_i p_i c_{i\mu} c_{i\nu} =$$

$$= \underbrace{\frac{1}{6} \sum_i c_{i\mu} c_{i\nu}}_{\frac{1}{3} \delta_{\mu\nu}} + \frac{1}{12} a \beta F_\alpha \underbrace{\sum_i c_{i\alpha} c_{i\mu} c_{i\nu}}_{=0} =$$

$$= \frac{1}{3} \delta_{\mu\nu}$$

$$\langle (ac_\mu)(ac_\nu) \rangle = 2 \cdot \frac{a^2}{6} \delta_{\mu\nu}$$

centered moment:

$$\langle [(ac_\mu) - \langle ac_\mu \rangle] [(ac_\nu) - \langle ac_\nu \rangle] \rangle =$$

$$\langle (ac_\mu)(ac_\nu) \rangle - \underbrace{\langle ac_\mu \rangle}_{\propto a^2} \underbrace{\langle ac_\nu \rangle}_{\propto a^2} = 2 \cdot \frac{a^2}{6} \int_{\mu\nu}$$

$O(a^4) \rightarrow$ neglect

EQUIVARIANT update procedure

$$\vec{r}(t+h) = \vec{r}(t) + \frac{a^2}{6} \beta \vec{F} + \sqrt{2 \cdot \frac{a^2}{6}} \vec{p}$$

$$\langle \vec{p} \rangle = 0$$

$$\langle p_\alpha p_\beta \rangle = \delta_{\alpha\beta}$$

ONLY

properties that are needed

↓
random vector

$$\left\langle \left(\sqrt{2 \cdot \frac{a^2}{6}} p_\alpha \right) \left(\sqrt{2 \cdot \frac{a^2}{6}} p_\beta \right) \right\rangle = 2 \cdot \frac{a^2}{6} \delta_{\alpha\beta}$$

$$\text{Now, } a^2 = 6 D h \quad \frac{a^2}{6} = D h$$

$$\frac{a^2}{6} \beta = D h \beta = \mu h$$

Einsteil

$$\vec{r}(t+h) = \vec{r}(t) + \mu \vec{F} h + \sqrt{2 D h} \vec{p}$$

Langevin in its discretized
form

$$\frac{\vec{r}(t+h) - \vec{r}(t)}{h} = m \vec{F} + \sqrt{\frac{2D}{h}} \vec{p}$$

$\Rightarrow \frac{d\vec{v}}{dt}$ does not exist

\downarrow diverges for $h \rightarrow 0$]

FORMAL way of writing the update scheme.

Langevin
equation

$$\frac{d\vec{r}}{dt} = \mu \vec{F} + \vec{\eta}$$

noise variable
"Gaussian white noise"

$$\langle \vec{\eta} \rangle = 0$$

$$\langle \eta_\alpha(t) \eta_\beta(t') \rangle = 2D \delta(t-t') \delta_{\alpha\beta}$$

(not so obvious)