

$$\left. \frac{d^2 \psi}{dx^2} = A \exp(\pm \lambda x) \right\}$$

solve $\frac{\beta \epsilon_0 R}{4 \epsilon} = \left(\frac{\sqrt{A}}{2} \frac{R}{2} \right) \tan \left(\frac{\sqrt{A}}{2} \frac{R}{2} \right)$

$$\psi(x) = -2 \ln \cos \left(\frac{\sqrt{A}}{2} x \right)$$

$$E(x) = -\sqrt{2A} \tan \left(\frac{\sqrt{A}}{2} x \right)$$

$$\frac{d}{dx} \epsilon = -\sqrt{2A} \frac{1}{\cos^2\left(\sqrt{\frac{A}{2}}x\right)} \sqrt{\frac{A}{2}} = -\frac{A}{\cos^2\left(\sqrt{\frac{A}{2}}x\right)}$$

$$\stackrel{!}{=} 4\pi\epsilon_0(-c) \Rightarrow \left(c(x) = \frac{A}{4\pi\epsilon_0 \cos^2\left(\sqrt{\frac{A}{2}}x\right)} \right)$$

Is the system charge-neutral? If yes, then

$$2\epsilon \, d(\text{area}) = \text{charge} = d(\text{area}) \int_{-R/2}^{+R/2} dx \, c(x) \cdot e$$

or $\frac{\sigma}{e} = \int_0^{R/2} dx c(x)$ Does this hold?

r.l.s. $\int_0^{R/2} dx c(x) = \frac{A}{4\pi l_B} \int_0^{R/2} \frac{dx}{\cos^2\left(\sqrt{\frac{A}{2}}x\right)} = \int_0^{\sqrt{\frac{A}{2}}\frac{R}{2}} \frac{d\xi}{\cos^2 \xi}$

$$= \frac{A}{4\pi l_B} \sqrt{\frac{2}{A}} \int_0^{\sqrt{\frac{A}{2}}\frac{R}{2}} \frac{d\xi}{\cos^2 \xi} =$$

$$= \frac{A}{4\pi l_B} \sqrt{\frac{2}{A}} \tan\left(\frac{\sqrt{A}}{2}\frac{R}{2}\right) =$$

$$= \frac{1}{4\pi l_B} \frac{4}{R} \left(\sqrt{\frac{A}{2}} \sqrt{\frac{R}{2}} \right) \tan \left(\sqrt{\frac{A}{2}} \sqrt{\frac{R}{2}} \right) =$$

$$= \frac{\beta e \sigma R}{4 \varepsilon}$$

$$= \frac{1}{4\pi l_B} \frac{\beta e \sigma}{\varepsilon} =$$

$$= \frac{\beta e \sigma}{\varepsilon} \frac{1}{4\pi} \left(\frac{e^2}{4\pi \varepsilon k_B T} \right)^{-1} = 2/e \quad \checkmark$$

OK!

$$\frac{\beta e \epsilon R}{4 \epsilon} = \left(\sqrt{\frac{A}{2}} \frac{R}{2} \right) \tan \left(\sqrt{\frac{A}{2}} \frac{R}{2} \right)$$

re-parametrization $A \rightarrow \xi = \sqrt{\frac{A}{2}} \frac{R}{2}$

$$\frac{\beta e \epsilon R}{4 \epsilon} = \pi \underbrace{\frac{e^2}{4 \pi \epsilon k_B T}}_{l_B} \frac{1}{e} \sigma R = \frac{1}{2} \underbrace{\frac{2 \pi l_B \sigma}{e}}_{1/\lambda} R$$

introduce so-called Gouy - Chapman length

$$\lambda = \frac{e}{2\pi l_B \sigma}$$

as a measure for
the surface charge

$$\frac{\beta e \sigma R}{4\epsilon} = \frac{R}{2\lambda} \quad \Rightarrow \quad \left| \frac{R}{2\lambda} = \int \tan \xi \right|$$

$$R \rightarrow \infty \quad \Rightarrow \quad \xi \rightarrow \frac{\pi}{2} \quad \Rightarrow \quad \text{write } \xi = \frac{\pi}{2} - \eta \quad \leftarrow \text{small}$$

$$\tan \delta = \tan \left(\frac{\pi}{2} - \eta \right) = \cot \eta$$

$$\frac{R}{2\lambda} = \left(\frac{\pi}{2} - \eta \right) \cot \eta \quad | \cdot \tan \eta \cdot \frac{2\lambda}{R}$$

$$\tan \eta = \left(\frac{\pi}{2} - \eta \right) \frac{2\lambda}{R}$$

Leading order : $\eta = \frac{\pi}{2} \frac{2\lambda}{R}$ (neglect terms of order $\frac{1}{R^2}$)

$$= \frac{\pi \lambda}{R}$$

$$\xi = \frac{\pi}{2} - \frac{\pi \lambda}{R}$$

$$\sqrt{\frac{A}{2}} = \frac{2}{R} \xi = \frac{\pi}{R}$$

a gain, neglect terms $O\left(\frac{1}{R^2}\right)$

$$A \approx 2 \frac{\pi^2}{R^2}$$

near the right plane

$$x = \frac{R}{2} - y$$

$$y > 0$$

y small

$$\sqrt{\frac{A}{2}} x = \sqrt{\frac{A}{2}} \frac{R}{2} - \sqrt{\frac{A}{2}} y \approx \xi - \frac{\pi}{R} y \approx \frac{\pi}{2} - \frac{\pi \lambda}{R} - \frac{\pi y}{R} =$$

$$= \frac{\pi}{2} - \frac{\pi}{R} (y + \lambda)$$

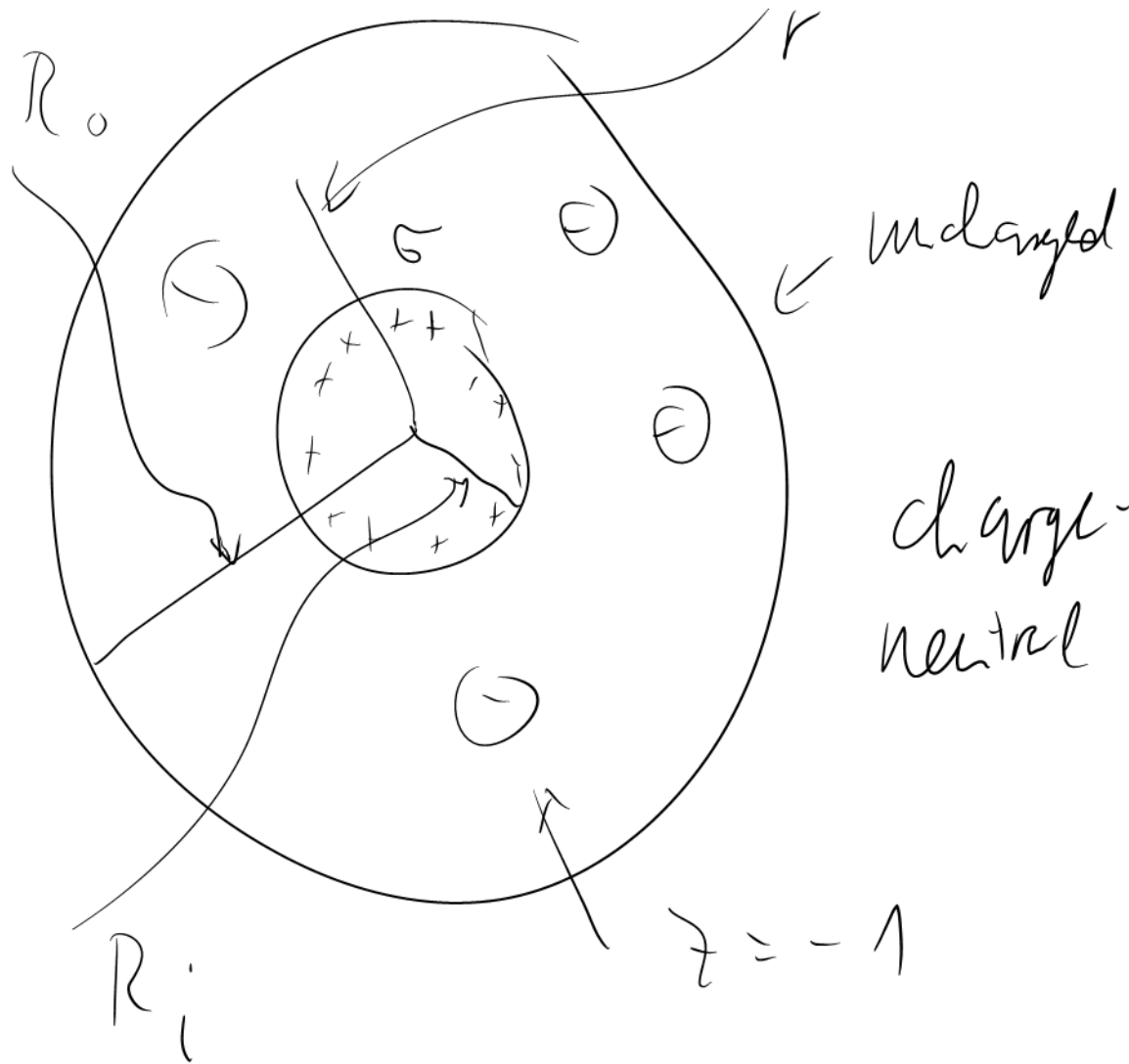
$$\cos\left(\sqrt{\frac{A}{2}} x\right) \approx \cos\left(\frac{\pi}{2} - \frac{\pi}{R} (y + \lambda)\right) = \sin\left[\frac{\pi}{R} (y + \lambda)\right]$$

$$\approx \frac{\pi}{R} (y + \lambda) \rightarrow \text{cosc, profile:}$$

$$c(x) = \frac{\gamma}{4\pi l_B} A \frac{\gamma}{\cos^2\left(\sqrt{\frac{A}{2}} x\right)} \approx \frac{\gamma}{4\pi l_B} 2 \frac{\pi^2}{R^2} \frac{1}{\frac{\pi^2}{R^2} (y + \lambda)^2}$$

$$\Rightarrow c(y) = \frac{1}{2\pi l_B (y + \lambda)^2}$$

7. Counterions in 2d, 3d spherical capacitors



$$-\nabla^2 \psi = A \exp(\psi)$$

We know solutions of

$$\nabla^2 \psi = 0$$

$$\psi(r)$$

$d = 2, 3$ Spatial dimension

α : Cartesian index, Einstein Σ -conv.

$$r^2 = x_\alpha x_\alpha \quad 2r dr = 2x_\alpha dx_\alpha \quad dr = \underbrace{\frac{x_\alpha}{r} dx_\alpha}$$

$$\psi = \psi(r)$$

$$\partial_\alpha \psi = \frac{\partial}{\partial x_\alpha} \psi = \frac{\partial \psi}{\partial r} \frac{\partial r}{\partial x_\alpha} = \frac{x_\alpha}{r} \frac{\partial \psi}{\partial r}$$

$$\partial_\alpha = \frac{x_\alpha}{r} \frac{\partial}{\partial r} \Rightarrow \nabla^2 \psi = \frac{x_\alpha}{r} \frac{\partial}{\partial r} \frac{x_\alpha}{r} \frac{\partial}{\partial r} \psi =$$

$$= \frac{x_\alpha}{r} \left[\frac{1}{r} \frac{\partial x_\alpha}{\partial r} + x_\alpha \frac{\partial}{\partial r} r^{-1} + \frac{x_\alpha}{r} \frac{\partial}{\partial r} \right] \frac{\partial}{\partial r} \psi =$$

$$= \left(\frac{x_\alpha}{r^2} \frac{r}{x_\alpha} + r(-1) \frac{1}{r^2} + \frac{r^2}{r^2} \frac{\partial}{\partial r} \right) \frac{\partial}{\partial r} \psi =$$

$$= \left(\frac{1}{r} d - \frac{1}{r} + \frac{\partial}{\partial r} \right) \frac{\partial}{\partial r} \psi = \left(\frac{d-1}{r} + \frac{\partial}{\partial r} \right) \frac{\partial}{\partial r} \psi$$

nonlinear transformation

$r \rightarrow p(r)$ (some invertible fct. of r)

$$\frac{dp}{dr} = p'(r)$$

$$\frac{\partial \psi}{\partial r} = \frac{\partial \psi}{\partial \rho} \rho'(r) \quad \frac{\partial}{\partial r} = \rho'(r) \frac{\partial}{\partial \rho}$$

$$\frac{\partial^2 \psi}{\partial r^2} = \rho''(r) \frac{\partial \psi}{\partial \rho} + \rho'(r) \frac{\partial}{\partial r} \left(\frac{\partial \psi}{\partial \rho} \right) =$$

$$= \rho''(r) \frac{\partial \psi}{\partial \rho} + \left[\rho'(r) \right]^2 \frac{\partial^2 \psi}{\partial \rho^2}$$

$$\begin{aligned} \vec{\nabla}^2 \psi &= \frac{d-1}{r} \rho'(r) \frac{\partial \psi}{\partial \rho} + \rho''(r) \frac{\partial \psi}{\partial \rho} + \left[\rho'(r) \right]^2 \frac{\partial^2 \psi}{\partial \rho^2} \\ &= \left[\vec{\nabla}^2 \rho \right] \frac{\partial \psi}{\partial \rho} + \left[\rho'(r) \right]^2 \frac{\partial^2 \psi}{\partial \rho^2} \end{aligned}$$

Choose p such that $\bar{\nabla}^2 p = 0$

$$\Rightarrow p(r) = \begin{cases} \ln r & d=2 \\ -1/r & d=3 \end{cases}$$

$$\Rightarrow \text{PBE} : \left(p'(r) \right)^2 \frac{\partial^2 \psi}{\partial p^2} = A \exp(\psi)$$

$$\psi = \psi_1 + \psi_2$$

$$p^{12} \frac{\partial^2}{\partial p^2} \Psi = A e^{\psi_1} e^{\psi_2}$$

∴ choose ψ_1 such that $e^{\psi_1} = p^{12}$

$$\text{i.e., } \psi_1 = \ln(p^{12}) = 2 \ln p'$$

$$\frac{\partial^2}{\partial p^2} [2 \ln p' + \psi_2] = A e^{\psi_2}$$

$$\left[\frac{\partial^2}{\partial p^2} \psi_2 = A \exp(\psi_2) - 2 \frac{\partial^2}{\partial p^2} \ln p' \right]$$

inertia

force from
an external
potential

force with an
explicit time
dependence

check: $\} d: \quad p = -\frac{1}{r}, \quad p' = +\frac{1}{r^2} = p^2$

$$\ln p' = \ln p^2 = 2 \ln p$$

$$\frac{\partial}{\partial p} \ln p' = \frac{2}{p}$$

$$\frac{\partial^2}{\partial p^2} \ln p' = -\frac{2}{p^2}$$

$$-2 \frac{\partial^2}{\partial p^2} \ln p' = +\frac{4}{p^2}$$

time-dependent force \rightarrow no closed analytic
solution is known,

Approximate solution

Lee White, 1977

apart from that: numerics

2d: $p = \ln v$ $p' = \frac{1}{v}$ $\ln p' = -\ln v = -p$

$$\frac{\partial}{\partial p} \ln p' = -1 \quad \frac{\partial^2}{\partial p^2} \ln p' = 0$$

lucky: time-dependent force is $\mathbb{Z} \mathbb{E} \mathbb{R} \circ \mathbb{B}_0$

PBE:

$$\frac{\partial^2}{\partial p^2} \psi_2 = A \exp(\psi_2)$$

as in

1d \mathbb{B}_0

Ansatz:

$$\Psi_2(p) = \Psi_0 - 2 \ln \cos [k(p + \delta)]$$

Ψ_0, k, δ : constants

$$\frac{\partial \Psi_2}{\partial p} = -2 \frac{1}{\cos [k(p + \delta)]} \left\{ -\sin [k(p + \delta)] \right\} k =$$

$$= 2k \tan [k(p + \delta)]$$

$$\frac{\partial^2 \psi_2}{\partial p^2} = 2k \frac{1}{\cos^2[k(p+s)]} k = \frac{2k^2}{\cos^2[k(p+s)]}$$

$$A \exp(\psi_2) = A \exp(\psi_0) \frac{1}{\cos^2[k(p+s)]}$$

$$\boxed{A \exp(\psi_0) = 2k^2}$$

$$\psi_n = 2 \ln p' = -2p$$

$$\psi = \psi_0 - 2p - 2 \ln \cos [k(p + s)]$$

$$\left(\psi = \psi_0 - 2 \ln r - 2 \ln \cos [k(\ln r + s)] \right)$$

with $k^2 = \frac{\Delta}{2} \exp(\psi_0)$

RL - parametrization $\delta = -\ln R_M$

R_M : "Manning radius"

$$\ln r + \delta = \ln r - \ln R_M = \ln \frac{r}{R_M}$$

$$k^2 = \frac{A}{2} \exp(\Psi_0) \quad \exp(\Psi_0) = \frac{2}{A} k^2 = \left(\sqrt{\frac{2}{A}} k \right)^2$$

$$\Psi_0 = -2 \ln \left(\sqrt{\frac{A}{2}} \frac{1}{k} \right)$$

$$\psi = -2 \ln \left[\sqrt{\frac{A}{2}} \frac{1}{k} \right] - 2 \ln r - 2 \ln \cos \left[k \ln \frac{r}{R_M} \right]$$

$$\psi = -2 \ln \left\{ \sqrt{\frac{A}{2}} \frac{r}{k} \cos \left(k \ln \frac{r}{R_M} \right) \right\}$$

$$\xi = - \frac{\partial \psi}{\partial r} = \frac{2}{r} + \frac{2}{\cos \left[k \ln \frac{r}{R_M} \right]} \left\{ -\sin \left[k \ln \frac{r}{R_M} \right] \right\} k \frac{1}{r}$$

$$\Sigma = \frac{2}{r} \left\{ 1 - k \tan \left[k \ln \frac{r}{R_m} \right] \right\}$$

$$r = R_0 \Rightarrow \Sigma = 0 \Rightarrow k \tan \left[k \ln \frac{R_0}{R_m} \right] = 1$$

$$r = R_i \Rightarrow E = \frac{\sigma}{\epsilon} = \underline{\underline{\epsilon = \frac{\beta e \sigma}{\epsilon}}}$$

$$= \frac{1}{e} \sigma \frac{e^2}{\epsilon k_B T} = \frac{1}{e} \sigma 4 \pi l_B = 2 \frac{2 \pi l_B \sigma}{e} = \underline{\underline{\frac{2}{\lambda}}}$$

Gouy-Chapman \rightarrow

$$\Rightarrow \frac{Z}{\lambda} = \frac{Z}{R_i} \left\{ 1 - \tan \left(k \ln \frac{R_i}{R_m} \right) \right\}$$

define Manning parameter $\xi \equiv$

of elementary charges on the rod per

Bjerrum length

$$2\pi R_i l_B \sigma = e \xi \Rightarrow \xi = \frac{R_i}{\lambda}$$

$$\xi = 1 - k \tan \left[k \ln \frac{R_i}{R_m} \right]$$

$$\xi < 1 = k \tan \left[k \ln \frac{R_m}{R_i} \right]$$

R_c interior

$$1 = k \tan \left[k \ln \frac{R_o}{R_m} \right]$$

R_c exterior

consider $\xi > 1$ strongly damped case