

The Science of Monetary Policy: An Imperfect Knowledge Perspective

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Abstract

This document details a proposal reviewing monetary policy design under imperfect knowledge for the Journal of Economic Literature.

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1 Introduction

The past twenty years witnessed the emergence of a coherent theory of monetary policy. This New Keynesian theory identifies a set of basic principles that are central to thinking about the design and implementation of monetary policy. These principles rely on the ability of central banks to manage effectively market expectations, with policy prescriptions typically derived under the assumption of rational expectations. An implication is expectations are consistent with the prevailing policy regime, or ‘anchored’, at all times. Despite these advances, recent events have engendered a re-evaluation of the theory and practice of monetary policy. The challenging macroeconomic environment bequeathed by the financial crisis has led many to question of the efficacy of monetary policy, and, particularly, question whether central banks can influence expectations with as much control as previously thought.

The objective of this survey is to review what is understood about the challenges to this paradigm posed by imperfect knowledge and to assess the degree of confidence with which one should hold the basic prescriptions of modern monetary economics. Imperfect knowledge is interpreted in a narrow sense, pertaining to models of learning dynamics. We view models of learning as a simple metaphor for households’ and firms’ incomplete knowledge about their environment, including the prevailing policy regime. The assumption of rational expectations is clearly strong: it seems sensible to understand contexts in which beliefs need not exactly coincide with objective probabilities of the economic model. An appealing feature of such model environments is, because beliefs can differ from the objective probabilities implied by the economic model, one can define meaningfully the notion of anchored expectations as those beliefs consistent with the monetary policy strategy of the central bank. The possibility of beliefs being inconsistent with monetary policy strategy and, therefore, unanchored, presents a challenge for stabilization policy. Indeed, policymakers conduct monetary policy facing substantial uncertainty about the economic environment they operate in. A policymaker committed to achieve sound economic policy objectives might still deliver a suboptimal performance in an environment of imperfect knowledge, no matter how well-intentioned and no matter how advanced their modeling frameworks.

The survey integrates the results and analysis of the literature into a single framework. In this framework market participants and policymakers optimize given their subjective beliefs. Beliefs are formed using a-theoretical econometric models which are updated in real time, as new information becomes available. The key aspect of the learning models considered here is that the economic system is “self-referential” in the sense of Marcat and Sargent (1989): beliefs affect the data-generating process, which in turn affect beliefs. As expectation errors are propagated through the economy, they become partially self-fulfilling, opening the door to instability. Desirable policies then prevent or limit this self-sustaining drift in expectations.

The paper delineates what dimensions rational expectations policy advice is robust to imperfect knowledge and on what dimensions it is not. The dimensions on which it is not constitute important practical challenges confronting actual policy making. Indeed a central theme is that once one departs from the symmetry of rational expectations equilibrium modeling, one has to be careful in specifying the types of information that different

agents possess — in particular, that information possessed by the Central Bank and that possessed by agents. Informational asymmetries generically impose constraints on what monetary policy can achieve relative to the rational expectations benchmark. It is hoped that identification of these issues will serve to inspire future research.

The title “The Science of Monetary Policy: An Imperfect Knowledge Perspective” deliberately recalls the seminal piece by Clarida, Gali, and Gertler (1999) also appearing in the *Journal of Economic Literature*. It is a pivotal reference in the monetary policy literature, summarizing the key principles to be re-examined through the lens of imperfect knowledge — directly motivating our title. Like that paper, we will organize our discussion around a sequence of formally stated results. The results in turn will be grouped in to two major themes of the paper: i) that the basic logic of monetary policy design under rational expectations continues to obtain under imperfect knowledge. In particular, the management of expectations remains central; but ii) the nature of dependence of monetary policy decisions on expectations must be of a particular kind, rendering aggregate demand management and inflation control in general more difficult than under rational expectations. While much has been learned about monetary policy design in recent decades, an imperfect knowledge perspective suggests one should be less sanguine about the potency of monetary policy.

Before advancing to the main objectives of this survey, it is worth emphasizing that models of learning dynamics have considerable merit given their consistency with basic facts about measured expectations and basic facts about forecasting macroeconomic time series. First, it has been widely documented that survey measures of expectations exhibit some degree of autocorrelated forecast errors, which is inconsistent with the strongest form of rational expectations usually assumed in the literature. Roberts (1995) and Adam and Padula (2011) document this for inflation expectations in the US, while Eusepi and Preston (2011) provide evidence for a range of macroeconomic variables. Second, as shown in **Figures 1, 2 and 3** survey-based long-term expectations drift over time. As can be seen from the figures, some of the variation in short-term forecasts is incorporated in longer-range projections. In contrast, the baseline New Keynesian model implies near-constant medium-term forecasts — see, for example, Gürkaynak, Sack, and Swanson (2005). This drift in long-term expectations reflects both revised beliefs about the long-term behavior of the economy and beliefs about policy. The central leitmotif of what follows concerns whether this drift in beliefs can modify some of the optimal policy prescriptions derived under rational expectations.

In writing this piece, we are aware that there are numerous other surveys in the literature.¹ The intention here is to bring together insights that are specifically focused on monetary policy in the New Keynesian framework. Our reading of the learning literature is that the analysis of monetary policy is one area of research that has progressed sufficiently far to merit such integration and critical reflection. In so doing we hope to articulate more clearly what differences emerge under learning vis-a-vis rational expectations, and show that they are manifestations of a common mechanism. A cost of the approach is that it will lack breadth, unavoidably failing to cover interesting work in the learning literature. Such work

¹See for example Evans and Honkapohja (2003a), Evans and Honkapohja (2009a), Evans and Honkapohja (2009b) and Woodford (2012).

clearly demands attention, but falls outside the purview of the current discussion.

This survey is organized as follows. Sections 2 and 3 review the basic New Keynesian model and the basic principles underpinning the science of monetary policy under rational expectations. Section 4 introduces the methodological framework underlying the analysis of learning dynamics and its implications for policy design. Sections 5 and 6 discuss the main results in the baseline model. Section 5 investigates the robustness of desirable policies under rational expectations to small expectations errors (E-Stability), while Section 6 shows how optimal policy that fully takes into account of agents' learning process might be different from policy advise under rational expectations. Section 7 considers extensions to the baseline framework: in particular, the role of central bank communication for stabilization policy, monetary and fiscal policy interactions, and the consequences for policy design of the zero lower bound on the policy rate. Sections, 8 and 9 discuss possible further directions for the literature and conclusions. The conclusion highlight to what degree learning alters the policy prescriptions under rational expectations that are presented in section 3.

2 The Basic New Keynesian Model

This section develops a parsimonious version of the canonical New Keynesian model widely used for monetary policy analysis. A range of assumptions are made for expositional simplicity — for example log utility and linear disutility of labor supply. Results for which these are assumptions are pertinent, or lack generality, will be noted where relevant. Further details on the microfoundations can be found in Woodford (2003a) and Galí (2008).

A continuum of households i on the unit interval maximize utility

$$\hat{E}_t^i \sum_{T=t}^{\infty} \bar{C}_T \beta^{T-t} [\ln c_T(i) - \chi n_T(i)],$$

where $0 < \beta < 1$ and $\chi > 0$, by choice of sequences for consumption, $c_t(i)$, and labor supply, $n_t(i)$, subject to the flow budget constraint

$$b_t(i) \geq (1 + i_t) \pi_t^{-1} b_{t-1}(i) + W_t n_t(i) + \Gamma_t(i)$$

and the No-Ponzi condition

$$\lim_{T \rightarrow \infty} \hat{E}_t^i \left(\prod_{s=0}^{T-t} (1 + i_{t+s}) \pi_{t+s}^{-1} \right)^{-1} B_T(i) \geq 0.$$

The variable $b_t(i) \equiv B_t(i)/P_t$ denotes real bond holdings (which in equilibrium are in zero net supply), i_t the nominal interest rate, $\pi_t \equiv P_t/P_{t-1}$ the inflation rate, W_t is the hourly wage, $\Gamma_t(i)$ dividends from equity holdings of firms and \bar{C}_T exogenous preference shifter. The operator \hat{E}_t^i denotes agents' subjective expectations, which might differ from rational expectations. The latter is defined by the operator \mathbb{E}_t .

A continuum of monopolistically competitive firms maximize profits

$$\hat{E}_t^j \sum_{T=t}^{\infty} \alpha^{T-t} Q_{t,T} [p_t(j) y_T(j) - W_T n_T(j)]$$

by choice of $p_t(j)$ subject to the production technology and demand function $y_T(j) = n_T(j) = (p_t(j)/P_T)^{-\theta_t} Y_T$ for all $T \geq t$, with the elasticity of demand across differentiated goods an exogenous process satisfying $\theta_t > 1$; and exogenous probability $0 < \alpha < 1$ of not being able to reset their price in any subsequent period. When setting prices in period t , firms are assumed to value future streams of income at the marginal value of aggregate income in terms of the marginal value of an additional unit of aggregate income today giving the stochastic discount factor $Q_{t,T} = \beta^{T-t}(P_t Y_t)/(P_T Y_T)$.

In a symmetric equilibrium $c_t(i) = c_t = w_t \equiv W_t/P_t = n_t = Y_t$ for all i , $p_t(j) = p_t(j)$ and $b_t(i) = b_t(j)$ for all i, j . To a first-order log-linear approximation, in the neighborhood of a zero-inflation steady state, individual consumption and pricing can be expressed as

$$\hat{c}_t(i) = \hat{E}_t^i \sum_{T=t}^{\infty} \beta^{T-t} [(1 - \beta) \hat{w}_{T+1} - (\hat{i}_T - \hat{\pi}_{T+1} - \beta(\bar{c}_T - \bar{c}_{T+1}))] \quad (1)$$

$$\hat{p}_t(j) = \hat{E}_t^j \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [(1 - \alpha\beta)(\hat{w}_T + u_T) + \alpha\beta\hat{\pi}_{T+1}] \quad (2)$$

where for any variable z_t , $\hat{z}_t = \ln(z_t/\bar{z})$ the log-deviation from steady state \bar{z} , with the exceptions $\hat{p}_t(j) = \ln(p_t(j)/P_t)$, $\hat{i}_t = \ln[(1 + i_t)/(1 + \bar{i})]$, $u_t = \ln(\theta_t/\bar{\theta})$ and $\bar{c}_t = \ln(\bar{C}_t/\bar{C})$. With a slight abuse of notation, the caret denoting log deviation from steady state is dropped for the remainder, so long as no confusion results. Aggregating across the continuum of households and firms, and imposing market-clearing conditions, the economy is described by the aggregate demand and supply equations

$$x_t = \hat{E}_t \sum_{T=t}^{\infty} \beta^{T-t} [(1 - \beta) x_{T+1} - (i_T - \pi_{T+1} - r_T^n)] \quad (3)$$

$$\pi_t = \hat{E}_t \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [\kappa(x_T + u_T) + (1 - \alpha)\beta\pi_{T+1}] \quad (4)$$

where the output gap is defined as

$$x_t = y_t - y_t^n = w_t$$

the difference between output and the natural rate of output, the level of output determined by a flexible price economy: here $y_t^n = 0$. The associated natural rate of interest $r_t^n = (\beta\bar{c}_t - \hat{E}_t\bar{c}_{T+1})$ is determined by fluctuations in the propensity to consume, which along with the cost-push shock are exogenous processes described when necessary. The aggregate demand equation determines the output gap as the discounted expected value of future wages, with the second term capturing variations in the real interest rate, applied in future periods, due to changes in the nominal interest rates and goods price inflation. That expected future dividends are irrelevant to consumption plans, to the first-order, reflects the assumption of an infinite Frisch elasticity of labor supply. The aggregate supply curve determines inflation as the discounted future sequence of marginal costs and the inflation rate. The slope of

the Phillips curve is measured by $\kappa = (1 - \alpha\beta)(1 - \alpha)/\alpha$, while the exogenous process u_t captures variations in firms' desired markup reflecting variations in elasticity of demand θ_t .

The model is closed with assumptions on fiscal and monetary policy. For now we abstract from fiscal policy.² Monetary policy is discussed in detail in subsequent sections. To facilitate that discussion note under rational expectations the aggregate demand and supply equations can be given the familiar recursive representation

$$x_t = \mathbb{E}_t x_{t+1} - (i_t - \mathbb{E}_t \pi_{t+1} - \hat{r}_T^n) \quad (5)$$

$$\pi_t = \kappa x_t + \beta \mathbb{E}_t \pi_{t+1} + u_t. \quad (6)$$

The conditions under which relations (3) and (4) are reducible to these expressions are discussed in section 4.4.

3 Basic Principles: Rational Expectations

3.1 Optimal Policy

The policymaker minimizes the loss function

$$\mathbb{E}_t \sum_{T=t}^{\infty} \beta^{T-t} (\pi_T^2 + \lambda_x x_T^2) \quad (7)$$

where $\lambda_x > 0$ determines the relative weight given to output gap versus inflation stabilization. This welfare-theoretic loss function represents a second-order approximation to household utility. Feasible sequences of inflation and the output gap must satisfy the aggregate demand and supply equations (3) and (4). Under rational expectations the optimal commitment solution requires satisfaction of the first-order conditions

$$\frac{\lambda_x}{\kappa} x_t + \Lambda_t + \sum_{j=1}^{\infty} a^j \Lambda_{t-j} = 0 \quad (8)$$

$$\pi_t + \Lambda_t - \frac{(1 - \alpha)}{\alpha} \sum_{j=1}^{\infty} a^j \Lambda_{t-j} = 0 \quad (9)$$

for all t where Λ_t is the Lagrange multiplier in the aggregate demand equation.³ The presence of the lagged Lagrange multipliers reflects the well-known property of history de-

²We assume a cashless economy with no government spending and no government debt. This will be relaxed in section 7.2.

³Attention is confined to optimality from the “timeless perspective” meaning the Central Bank, when contemplating a new commitment, sets policy as if it had in fact committed to this same policy at an earlier date, infinitely far in the past. See Woodford (2003, chap 7) for a detailed discussion.

pendence, with the infinite sequence of lags reflecting the dependence of optimal decisions on expectations into the indefinite future.⁴

Combining first-order conditions provides

$$\pi_t = -\frac{\lambda_x}{\kappa} (x_t - x_{t-1}). \quad (10)$$

This consolidated first-order condition — called a target criterion by Giannoni and Woodford (2002, 2010) and Woodford (2003) — requires the central bank to ensure inflation is proportional to the change in the output gap. The lagged output gap captures the history dependence of the optimal commitment solution, a summary statistic of the infinite sequence of Lagrange multipliers in (8) and (9). Under the optimal commitment policy the state-contingent paths for inflation, output and nominal interest rates satisfy

$$\pi_t = (1 - \mu) \frac{\lambda_x}{\kappa} x_{t-1} + \frac{\mu}{1 - \beta\mu\rho_u} u_t \quad (11)$$

$$x_t = \mu x_{t-1} - \frac{\kappa}{\lambda_x} \cdot \frac{\mu}{1 - \beta\mu\rho_u} u_t \quad (12)$$

and

$$i_t = \frac{\lambda_x - \kappa}{\kappa} (1 - \mu) \mu \cdot x_{t-1} + \frac{\lambda_x - \kappa}{\lambda_x} \cdot \frac{\mu(\mu + \rho_u - 1)}{1 - \beta\mu\rho_u} \cdot u_t + r_t^n \quad (13)$$

where μ is the model's only eigenvalue lying in the unit circle, and the cost-push shock is assumed to be a first-order autoregressive process with eigenvalue $0 < \rho_u < 1$.

The target criterion (10) can be recast in terms of the price level as

$$p_t = \bar{k} - \frac{\lambda_x}{\kappa} x_t \quad (14)$$

some constant \bar{k} . Relation (10) is a first-order difference equation for which (14) is the complementary solution. The state-contingent evolutions in each case involve the same equilibrium responses to shocks that occur in each period, and the same long-run average values of all variables.⁵ To keep matters simple we set the constant, \bar{k} , equal to zero.⁶ Using (14) in (11), (12) and (13) gives the equilibrium paths of prices, the output gap and nominal interest rates for all t .

An important property of the optimal commitment solution is the independence of inflation and the output gap from variations in the natural rate of interest. Only cost-push shocks represent a fundamental trade-off: optimal policy completely stabilizes inflation and the output gap. This property, which is manifest in substantially more complex models used

⁴Because rational expectations equilibrium is typically represented by recursive Euler equations there is only one lagged multiplier in the standard formulation of this problem. The two policy problems are equivalent, however, under the assumption of rational expectations on the part of households and firms.

⁵They differ in a transitory, deterministic component of the solution that will depend on initial conditions — that is, on the value of \bar{k} . For one particular choice of \bar{k} that depends on the lagged price level at the time a new commitment is being contemplated the solutions will be identical.

⁶This is not important for the learning analysis being a normalization.

for policy evaluation — see, for example, Justiniano, Primiceri, and Tambalotti (2013) — has been called “Divine Coincidence” — see Blanchard and Galí (2007) and Clarida, Gali, and Gertler (1999).

Complete stabilization of disturbances to the natural rate of interest remains a feature of optimal policy under discretion. Taking expectations as given in the above policy problem implies

$$\sum_{j=1}^{\infty} a^j \Lambda_{t-j} = 0,$$

providing a targeting rule of the form

$$\pi_t = -\frac{\lambda_x}{\kappa} x_t. \tag{15}$$

Solving with (4) under rational expectations gives the optimal state-contingent paths for inflation and output gap as

$$\begin{aligned} \pi_t &= \frac{\lambda_x}{\kappa^2 + \lambda_x (1 - \beta \rho_\mu)} u_t \\ x_t &= -\frac{\kappa}{\kappa^2 + \lambda_x (1 - \beta \rho_\mu)} u_t \end{aligned} \tag{16}$$

which are again independent of the natural rate of interest. Two other differences emerge relative to the optimal commitment solution. First, there is no history dependence. Second, the optimal state-contingent response to disturbances differs, a property referred to as stabilization bias.

3.2 Policy Implementation

From the work of Sargent and Wallace (1975) and McCallum (1981, 1983) it is well known that policy rules of the form (13) which only respond to exogenous or predetermined variables — sometimes referred to as fundamentals-based policy rules — may imply multiple equilibria. While they are consistent with the optimal equilibrium, they may be equally consistent with many less desirable equilibria. Desirable policies should deliver a unique bounded rational expectations equilibrium. This can be achieved by appropriate conditioning of nominal interest rates on contemporaneous endogenous variables.

A prominent and elegant approach, of which actual inflation targeting regimes are an example, characterizes the central bank’s decision procedure in terms of specific targeting rules: such rules specify a relationship between one or more target variables that must be checked each time an interest-rate decision is made. The instrument setting is deemed appropriate if the specified “target criterion” is satisfied. Giannoni and Woodford (2002) show that a central bank which implements policy according to targeting rules of the form (10), (14) and (15) will deliver a locally unique rational expectations equilibrium for all parameter values under maintained assumptions. To determine the instrument setting in

any period the central bank requires a completely specified model of the economy to solve for the equilibrium path of the policy instrument. For example, the target criterion (10) implicitly defines the interest-rate rule

$$\hat{i}_t = -x_t^* + \mathbb{E}_t \sum_{T=t}^{\infty} \beta^{T-t} [(1 - \beta) x_{T+1} - (\beta i_{T+1} - \pi_{T+1} - r_T^n)] \quad (17)$$

where

$$x_t^* = \frac{\lambda_x}{\lambda_x + \kappa^2} x_{t-1} - \frac{\lambda_x}{\lambda_x + \kappa^2} \left[\mathbb{E}_t \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [\kappa\alpha\beta (x_{T+1} + u_T) + (1 - \alpha) \beta \pi_{T+1}] \right] \quad (18)$$

is the level of output gap jointly satisfying (15) and (4) under rational expectations. Policy depends upon current and projected paths of demand, supply and cost-push disturbances. This choice of nominal interest rate guarantees the target criterion is satisfied each period.

The target criterion approach possesses a number of important characteristics. First, the specific form of optimal targeting rule does not depend on the exact nature of disturbances judged relevant to the economy at any given time. Obviously, appropriate interest-rate policy will depend on perceived current and projected disturbances, but the architecture of the target criterion is invariant to these complications of implementation. For an extensive discussion see Svensson (2003).

Second, as emphasized by Clarida, Gali, and Gertler (1999), implicit interest-rate rules of this kind have the property that nominal interest rates move more than proportionately to movements in inflation. This point is most easily seen by employing the usual recursive representation of equilibrium conditions under rational expectations which implies the reaction function

$$i_t = -\frac{\lambda_x}{\kappa^2 + \lambda_x} x_{t-1} + \left(1 + \frac{\kappa\beta}{\kappa^2 + \lambda_x} \right) \mathbb{E}_t \pi_{t+1} + \mathbb{E}_t x_{t+1} + r_t^n + \frac{\kappa^2}{\kappa^2 + \lambda_x} u_t. \quad (19)$$

Nominal interest rates move more than proportionally to expected inflation. This is a defining feature of optimal policy, both under commitment and under discretion, and a property that Clarida, Gali, and Gertler (2000) find holds for US monetary policy in the post-Volcker policy regime. It has been linked to the period of economic stability up to the Great Recession.

A criticism of the target criterion approach is that it relies on the central bank being able to exploit the true structure of the economy to infer the appropriate interest-rate setting. Not only is this informationally intensive, but a policy that is optimal for one model, might nonetheless perform poorly in closely related models. This motivates interest in specifications of policy which are less informationally demanding, while at the same time performing relatively well across a range of models. Indeed, Levin, Wieland and Williams (1999, 2003) and others have argued that particular classes of simple rules exhibit such robustness while still being consistent with determinacy of rational expectations equilibrium and desirable from a welfare perspective.

A prominent example of this kind of policy is the generalized Taylor rule

$$\dot{i}_t = \rho \dot{i}_{t-1} + (1 - \rho) r_t^n + \phi_\pi \pi_t + \phi_x x_t \quad (20)$$

prescribing interest rates to be adjusted in response to current economic conditions as captured in the contemporaneous inflation rate, output gap and the natural rate of interest, as well past developments embodied in the previous-period's interest-rate setting. This rule delivers local determinacy of rational expectations equilibrium if and only if

$$\kappa \phi_\pi + (1 - \beta) \phi_x > 1 - \rho. \quad (21)$$

Woodford (2003a) refers to this condition as the Taylor Principle as it requires nominal interest rates to move more than proportionately in response to inflation variations in the long run. An inertial response to past interest rates implies less aggressive responses to current inflation and output are required for determinacy of equilibrium. Taylor's (1993) prescription did not include interest-rate inertia, though Woodford (2003b) demonstrates history dependence permits such rules to approximate the optimal commitment policy for the model developed above. Rotemberg and Woodford (1999) in a closely related model show that policy rules with $\rho \rightarrow 1$, first-difference interest-rate rules, also approximate fairly closely the fully optimal policy rule. Furthermore, such rules are robust to model uncertainty, performing well across a range of models.

These results constitute the main principles of policy design under a new Keynesian perspective discussed in Clarida, Gali, and Gertler (1999). For future reference, they are summarized here.

1. Absent cost-push shocks optimal policy under commitment or discretion completely stabilize disturbances to the natural rate.
2. Optimal policy under commitment or discretion implies the policy rate responds more than proportionally to expected inflation.
3. Optimal commitment policy induces history dependence which improves the short-run stabilization trade-off between inflation and the output gap.
4. Policy implementation can be delivered through an inflation targeting rule of the form (10) or an equivalent price-level targeting rule (14), or by simple policy rules of the form (20).
5. Simple policy rules that satisfy the Taylor principle and incorporate a sufficient degree of interest smoothing come close to delivering fully optimal policy under commitment and are robust to model mis-specification.

4 The Methodological Framework

4.1 Modeling Imperfect Information

The rational expectations paradigm comprises two stipulations: (i) agents optimize given their beliefs about the joint probability distribution for various state variables that are in-

dependent of their actions and that matter for their payoffs; and (ii) the probabilities that they assign coincide with the predictions of the model. This survey adopts an expository framework which retains (i) while replacing (ii) with the assumption that the joint probabilities are formed using an a-theoretical econometric model. Equations (1) and (2) describe the optimal consumption and pricing decisions for arbitrary subjective beliefs about variables outside the control of households and firms. Agents have a completely specified belief system but do not know the equilibrium mapping between the aggregate state of the economy and the variables, exogenous to their decision problems, that they need to forecast. The predictions of their econometric model need not coincide with the predictions of the theoretical model. This follows a now large literature founded on seminal work by Bray (1982), Bray and Savin (1986), Marcet and Sargent (1989), Grandmont (1998), Sargent (1993), Evans and Honkapohja (1994, 1998) and comprehensively reviewed in Evans and Honkapohja (2001).

Although easily generalized, most models discussed in this survey embed the following assumptions about agents' information. First, agents are assumed to have identical beliefs, though they do not understand this to be true as they have no knowledge of the tastes and beliefs of other agents. By implication, agents cannot infer aggregate probability laws. Second, the econometric model nests the minimum-state-variable solution to the associated rational expectations problem. Third, market participants can perfectly observe aggregate state variables and have full information about the data-generating process of the exogenous aggregate shocks.

As shown in section 3.1, the optimal commitment equilibrium can be written as a linear function of the variables $\{x_{t-1}, u_t, r_t^n\}$. Agents make use of the forecasting model

$$z_t = \omega_{0,t-1} + \omega_{1,t-1}z_{t-1} + \omega_{2,t-1}r_{t-1}^n + \omega_{3,t-1}u_{t-1} + e_t, \quad (22)$$

where $z_t = (\pi_t, x_t, i_t)'$ and beliefs in period $t+1$ are given by the set of conformable matrices $\omega_t = (\omega_{0,t}, \dots, \omega_{3,t})'$. Expectations can then be evaluated for any future period $T > t$ as

$$\begin{aligned} \hat{E}_t z_T &= (I_3 - \omega_{1,t-1})^{-1} (I_3 - \omega_{1,t-1}^{T-t}) \omega_{0,t-1} + \omega_{1,t-1}^{T-t} z_t \\ &\quad + (I_3 \rho_{r^n} - \omega_{1,t-1})^{-1} (I_3 \rho_{r^n}^{T-t} - \omega_{1,t-1}^{T-t}) \omega_{2,t-1} \rho_{r^n} r_{t-1}^n \\ &\quad + (I_3 \rho_u - \omega_{1,t-1})^{-1} (I_3 \rho_u^{T-t} - \omega_{1,t-1}^{T-t}) \omega_{3,t-1} \rho_u u_t \end{aligned} \quad (23)$$

where I_3 is a (3×3) identity matrix, and ρ_{r^n} denotes the autoregressive coefficient of the natural rate, also assumed to be a first-order autoregressive process.

Beliefs are updated each period as new data become available according to the class of algorithms

$$\omega_t = \omega_{t-1} + g_t t^{-1} R_t^{-1} y_{t-1} (y_t - \omega'_{t-1} y_{t-1})' \quad (24)$$

$$R_t = R_{t-1} + g_t t^{-1} (y_{t-1} y'_{t-1} - R_{t-1})$$

where $y_t = (1, z_t, r_t^n, u_t)'$. Different assumptions about the variable g_t deliver different gains in the filtering problem. When $g_t = 1$ the updating rule (24) is recursive least squares. When $g_t = \bar{g}t$ recursive updating is given by a constant-gain algorithm, implying past observations are discounted more heavily. An observation n periods old receives a weight of $(1 - \bar{g})^n$. This survey discusses the consequences of both gain assumptions for stabilization policy.

The forecasting models considered in the learning literature embed a key challenge confronting forecasting in practice. Observed changes in macroeconomic data must be decomposed into high- and low-frequency components. Different assumptions about the gain imply different inferences about the relative importance of these components when new information arrives. For example, a constant gain permits tracking new low-frequency patterns in data, such as a change in the stance of policy. In contrast, a decreasing-gain algorithm asymptotically ascribes forecast errors to be solely high-frequency movement in data. Such inference problems are also quite common in macroeconomic theory and empirical applications, starting from Kydland and Prescott (1982). Recent work demonstrates that statistical models with time-varying drifts are able to explain quite well the behavior of output growth, inflation and nominal interest rate — see, for example, Cogley and Sbordone (2008), Stock and Watson (1989, 2007), Cogley and Sargent (2005a), Laubach and Williams (2003), Cogley, Primiceri, and Sargent (2010) and Gürkaynak, Sack, and Swanson (2005). In addition, such models successfully track the evolution of long- and short-term survey forecasts — see Branch and Evans (2006), Edge, Laubach, and Williams (2007) and Kozicki and Tinsley (2012). The belief structure posited in relations (22) and (24) is consistent with these features.⁷

4.2 On the Nature of Irrationality

While one might be prepared to admit beliefs that are in some way misspecified, one might nonetheless insist decisions to account fully for the on-going revision of subjective beliefs.⁸ However, solving for optimal decision rules under learning can be extremely complex, as it requires agents to keep track of anticipated future revisions to beliefs when making current decisions.⁹ Most of the literature sidesteps this problem by adopting the ‘anticipated utility’ approach to individual optimization (Kreps (1998), Sargent (1999), Preston (2005) and Evans and McGough (2014)). Given current beliefs, decisions in period t are made assuming beliefs are time invariant over the forecast horizon, even though they are in fact subsequently revised. This is one manifestation of the bounded rationality inherent in learning models.

This assumption is used by the vast majority of the literature. There are notable exceptions. Cogley and Sargent (2008) consider a simple consumption decision problem with imperfect information. They solve for both the anticipated utility and fully optimal solutions and conclude that model dynamics are close for low degrees of risk aversion. Adam and Marcet (2011) solve for the fully optimal solution in a simple asset pricing model with risk neutral investors, where only one-step-ahead forecasts matter for equilibrium determination.

⁷For a discussion about the correspondences between the algorithm (24) and the Kalman filter see Bullard (1992), Sargent and Williams (2005) and Berardi and Galimberti (2013).

⁸Adam and Marcet (2011) refer to this solution concept as ‘internal rationality’.

⁹This issue is discussed in detail in Sargent (1999) and, in particular, Cogley and Sargent (2008).

Adam, Beutel, and Marcet (2013) extend that analysis to an asset pricing model with risk averse investors. In this case, the agents' learning problem is conveniently re-interpreted as a filtering problem. The forecasting model can be described as a one-dimensional version of (22) where

$$z_t = \omega_{0,t-1} + e_t, \quad (25)$$

with the unobserved drift $\omega_{0,t}$ believed to evolve according to a random-walk

$$\omega_{0,t} = \omega_{0,t-1} + \eta_t$$

with innovation η_t . Importantly, agents have immutable priors about the constant variances of the innovations e_t and η_t . In this case, the updating equation from the Kalman filter is

$$\omega_{0,t} = \omega_{0,t-1} + \bar{g}(z_t - \omega_{0,t-1}) \quad (26)$$

where \bar{g} is a function of agents' perceived signal-to-noise ratio. This implies $\hat{E}_t \omega_{0,T} = \omega_{0,t}$ for $T > t$ so that the anticipated utility solution corresponds to the optimal solution.¹⁰ In light of this, the sequel gives primacy to the anticipated utility solution, acknowledging that establishing results in more general environments would be useful.

In the rest of the survey we focus on belief structures of the form (25) where agents learn only about the drift parameter. This is for four reasons. First, it considerably simplifies the exposition when developing analytical results. Second, it is more general than might be thought. Eusepi and Preston (2013) show such beliefs represent a first-order approximation of (24) in the neighborhood of the model's mean dynamics discussed below. Third, in the literature the drift term is generally the source of the most interesting dynamics, and generally imposes the strictest requirements on policy for stability. Fourth, the drift itself has a clean economic interpretation as representing fundamental uncertainty about the long-run values of each variable of interest. In the case of inflation it reflects uncertainty about a central bank's inflation target. In the case of income, or equivalently wages, it reflects long-run uncertainty about technological advance and productive capacity.

4.3 Stability Analysis: A Simple Example

Consider a flexible-price version of the model described above without cost-push shocks and assuming r_t^n is i.i.d.. Assume agents understand the interest rate is set according to the simple interest-rate rule $i_t = \phi_\pi \pi_t$. Then inflation is determined by

$$\pi_t = \phi_\pi^{-1} \hat{r}_t^n - \phi_\pi^{-1} \hat{E}_t \sum_{T=t}^{\infty} \beta^{T-t} [(\phi_\pi \beta - 1) \pi_{T+1}].$$

Agents have the forecasting model of the form (25)

$$\pi_t = \omega_{0,t-1}^\pi + e_t \quad (27)$$

¹⁰According to the agent's model the forecast error $z_t - \omega_{0,t-1}$ has zero mean and a constant variance.

which nests the stationary rational expectations solution of the model. Substituting for agent forecasts $\hat{E}_t \hat{\pi}_{T+1} = \omega_{0,t-1}^\pi$ for each $T > t$ gives the true data-generating process for inflation

$$\pi_t = \phi_\pi^{-1} \hat{r}_t^n - \frac{\beta - \phi_\pi^{-1}}{1 - \beta} \omega_{0,t-1}^\pi = \phi_\pi^{-1} \hat{r}_t^n + T(\omega_{0,t-1}^\pi). \quad (28)$$

Several observations require comment. First with $\omega_{0,t}^\pi = 0$ for all t the equilibrium is the rational expectations solution. As discussed above, this is a feature common to all models discussed in this survey. Second, the true data-generating process displays a time-varying drift. The model is therefore “self-referential” in the sense of Marcet and Sargent (1989): beliefs affect the data-generating process, which in turn affect beliefs. This is a key propagation mechanism of learning models. Third, the true data-generating process and the self-referential aspect of learning dynamics is regulated by monetary policy. Inspecting (28) the choice of policy coefficient ϕ_π clearly affects the drift of the inflation process. This inextricable link between beliefs and policy lies at the heart of this survey and defines the central challenge that learning poses for policy design.

To clarify the effect of policy on the evolution of the economy requires study of the convergence properties of the learning process. Agents update their estimate of the drift according to

$$\omega_{0,t}^\pi = \omega_{0,t-1}^\pi + g_t t^{-1} \left(\phi_\pi^{-1} \hat{r}_t^n - \frac{1 - \phi_\pi^{-1}}{1 - \beta} \omega_{0,t-1}^\pi \right) \quad (29)$$

where we have substituted for the true data-generating process of inflation. The methodology to analyze the convergence properties of learning dynamics was developed by Marcet and Sargent (1989) and Evans and Honkapohja (2001). The limiting behavior of beliefs can be described by an ordinary differential equation, reflecting the mapping between the perceived drift $\omega_{0,t}^\pi$ in (27) and the actual drift described in (28). The learning literature refers to the implied dynamics as the ‘mean dynamics’. In compact terms, the ODE is

$$\dot{\omega}_0^\pi = T(\omega_0^\pi) - \omega_0^\pi = -\frac{1 - \phi_\pi^{-1}}{1 - \beta} \omega_0^\pi. \quad (30)$$

When agents use recursive least-squares learning, $g_t = 1$, the local stability of the ODE determines whether the learning process converges point-wise to rational expectations. The rational expectations equilibrium is said to be expectationally stable, or E-Stable, if this differential equation is locally stable in the neighborhood of that equilibrium.¹¹ Equation (30) shows that the ODE is stable if and only if $\phi_\pi > 1$, that is the Taylor principle holds. By responding more than proportionally to inflation the policymaker successfully breaks the self-referential mechanism in the model: an increase in inflation expectations is met by a decline in actual inflation (equation (28)) which in turn implies a downward revision in the estimated drift (equation (29)). This discussion is summarized as the first result in our analysis of monetary policy under learning dynamics.

Result 1a. *Interest-rate rules of the form (20) deliver locally stable rational expectations equilibria under learning dynamics if and only if they satisfy the Taylor Principle.*

¹¹The connection between conditions for E-stability and local convergence of systems under real time recursive learning is discussed in detail in Evans and Honkapohja (2001).

In the case of a constant-gain learning, $g_t = \bar{g}t$, the learning process does not converge point-wise to rational expectations as the estimated drift is constantly revised with new information. For values of \bar{g} that are sufficiently close to zero the ODE (30) determines the conditions for convergence to an invariant distribution centered around the rational expectations equilibrium. Details can be found in Evans and Honkapohja (2001). The result is important because it establishes the property of expectational stability as fundamental to a proper understanding of both decreasing- and constant-gain belief structures. However, for larger values of the constant-gain parameter, describing situations where agents’ forecasts are further away from rational expectations, convergence requirements can be altered. Evans and Honkapohja (2009c) discuss conditions for stability in this case. Noting that with $g_t = \bar{g}t$ relation (29) is a first-difference equation in beliefs, stability is determined by the eigenvalue

$$1 - \bar{g} \frac{1 - \phi_\pi^{-1}}{1 - \beta}.$$

For a given policy rule a sufficiently high value of \bar{g} ensures this eigenvalue lies outside the unit circle, implying instability. This case, which describes expectations that are further away from the equilibrium under full rationality, is discussed in later sections.

4.4 Anticipated Utility and “Euler Equation” Learning

This survey integrates and enumerates the contributions of the learning literature through the lens of the anticipated utility approach. An alternative approach, most clearly articulated by Evans, Honkapohja, and Mitra (2013), asserts decisions rules in which only one-period-ahead expectations matter for spending and pricing decisions. The rational expectations Euler equations (31) and (32) are taken as the behavioral rules governing decisions of households and firms, with the rational expectations assumption replaced by the belief structure delineated above to give

$$x_t = \hat{E}_t x_{t+1} - \left(i_t - \hat{E}_t \pi_{t+1} - \hat{r}_T^n \right) \tag{31}$$

$$\pi_t = \kappa x_t + \beta \hat{E}_t \pi_{t+1} + u_t. \tag{32}$$

Examples include Evans and Honkapohja (2001, chap 10) which studies the standard real business cycle model, Bullard and Mitra (2002) which documents E-Stability conditions in the New Keynesian model above, and Slobodyan and Wouters (2012a) which introduces learning in an estimated medium-scale dynamic stochastic general equilibrium model. Evans and Honkapohja (2013) provide a survey of contributions in this literature.

The methodology is referred to as the “Euler Equation” approach, because equations (31) and (32) are suggestive of being the first-order conditions of household and firm maximization problems.¹² It is important to stress that the two approaches share the same *learning*

¹²Evans, Honkapohja and Mitra (2013), Preston (2005) and Eusepi and Preston (2011a) discuss more broadly the relative merits and limits of these two approaches. Bullard and Eusepi (2014) discuss the different convergence properties that the different approaches imply in a general class of forward-looking models.

rule and thus the same methodology to evaluate the convergence properties of learning dynamics. Where they differ is in the assumed *decision rules* used by households and firms to make spending and pricing decisions. Under rational expectations the two decision rules yield the same optimal decisions. However, this is generally not true under learning: the two decision rules imply different dynamic behavior and they can deliver different convergence properties — the economics of each framework is fundamentally different.

The survey adopts the anticipated utility framework for expository purposes with the understanding that the Euler Equation approach has contributed greatly to the issues explored and is discussed accordingly. In the authors' view, the following considerations make the anticipated utility approach more appealing. First, Preston (2005) demonstrates that the optimal decision rules (3) and (4) are reducible to (31) and (32) only by applying rational expectations logic. The Euler Equation approach implicitly assumes that agents understand all relevant market clearing conditions in all periods. While this assumption might appear innocuous in the context of a model with homogenous agents that are constrained in equilibrium to consume identical incomes, it is in general hard to defend. Market clearing conditions are, after all, part of the set of rational expectations equilibrium restrictions that agents are attempting to learn. Furthermore, even if the aggregate Euler equation is interpreted as an individual consumption Euler equation, one of the necessary conditions for household optimality, the approach is internally inconsistent with household optimization. Computing $\hat{E}_t c_{t+1}^i$ as $\hat{E}_t x_{t+1}$, as implied by equation (31), represents a forecast of the agent's own future decision that differs from what it expects to be optimal given its current forecasts of future income, inflation and interest rates and given the agent's understanding of its own decision problem. If agents have internally consistent beliefs, such forecasts would differ from what the agent should now be forecasting about their own period $t + 1$ forecasts. The anticipated utility approach ensures consistency among the various things agents are assumed to know, and as a result, makes appropriate distinction between control variables and those variables exogenous to the decision problem that need to be forecasted.

Second, the anticipated utility approach has the further advantage that if the econometric model used by agents to produce forecasts is correctly specified then the resulting behavior is *asymptotically* optimal. That is, behavior under the learning algorithm differs from what would be optimal behavior under the true probability laws by an amount that is eventually arbitrarily small. For the examined monetary policies, a correctly specified econometric model posits inflation, output and the nominal interest rate to be linear functions of variables appearing in the minimum-state-variable solution under rational expectations. The consistency of the ordinary-least-squares estimator implies the coefficients that agents use in forming their beliefs are eventually close to the true coefficients. Since the optimal decision rule is a continuous function of the coefficients of the agents' forecasting rule, beliefs that are arbitrarily close to the correct ones imply behavior that is arbitrarily close to being optimal. This is not a property of the Euler Equation approach.¹³

Third, because rational expectations equilibrium can be represented in many different

¹³Suppose one half of households have positive wealth which in equilibrium is lent to the other half of households whom are otherwise identical. Then the Euler equation approach stipulates that when beliefs converge creditors permanently under consume, and debtors over consume, relative to what is optimal.

ways, the Euler equation approach is only one of many possible ways to characterize equivalent economic decisions. Different rational expectations representations imply different dynamics under learning. While this point is central to Preston (2005) several interesting examples are developed by Cho (2014). Kurozumi and Zandweghe (2014) argue that because different representations imply different properties under learning this is a pitfall of E-Stability analysis. More accurately it is a limitation of the Euler equation approach.

Lastly, the anticipated utility framework retains interpretability being consistent with solving infinite-horizon intertemporal decision problems and renders the deviation from full optimality clear by retaining the importance of long-term beliefs about policy and macroeconomic fundamentals ignored by the Euler equation approach. For example, the Euler equation approach is inconsistent with the standard characterization of the transmission mechanisms of monetary policy which stipulates that not only the current interest rate, but also the entire future sequence of expected one-period rates affects spending plans today; and in the case that assets, such as public debt, are in positive supply, the Euler equation approach fails to account for the wealth effects on consumption demand through the intertemporal budget constraint. Differences such as these engender different conclusions on various dimensions of policy design.

5 Robustness of REE policy advice to learning

This section employs expectational stability analysis to evaluate the robustness of rational expectations policy advice. Robustness here is interpreted in the relatively narrow sense of equilibrium selection. Under rational expectations good policies satisfy the criterion of local determinacy or uniqueness of the equilibrium. Expectational stability analysis restricts this class of policy further by imposing an additional criterion: good policies also ensure rational expectations equilibria are robust to small expectational errors.¹⁴ McCallum (2007) and Ellison and Pearlman (2011) demonstrate that for a certain class of model there appears to be a close relationship between these two criteria for equilibrium selection. Bullard and Eusepi (2014) discuss a more general class of models with decision rules based on anticipated utility and with information delays where this equivalence typically breaks down. The following results underscore that E-Stability is generally a stricter requirement than determinacy for monetary policy design and the choice of monetary rule.

5.1 Taylor Principle and Stability

The Taylor Principle has become a central tenant of monetary policy practice. The previous section demonstrates its relevance in a simple endowment economy under learning. The following generalizes **Result 1a** to the New Keynesian model and covers the general class of rules in (20). In the benchmark model under learning dynamics the following result holds.

¹⁴As attention is restricted to policies that ensure determinacy of equilibrium this survey does not review an extensive literature on sunspots and their learnability. See Bullard (2006) and Evans and Honkapohja (2009a) for a review.

Result 1b. *If monetary policy is specified by policy rules of the form (20), then rational expectations equilibrium is E-Stable if the Taylor Principle (21) holds.*

The foundations of this result were laid out in Howitt (1992) which shows the Taylor Principle ensures expectations stability in a simple monetary model. Bullard and Mitra (2002) establish this result with no interest-rate inertia in the case of the New Keynesian framework in which household and firm decisions depend upon one-period-ahead expectations. Bullard and Mitra (2007) extend their earlier analysis to inertial interest-rate rules. Preston (2005) demonstrates Bullard and Mitra (2002) results continue to hold in a model of anticipated utility. Analytic results for the case with interest-rate inertia have not been established. Despite there being many model modifications that can break this principle, even under rational expectations, it constitutes an important robustness result.¹⁵

Two additional points are worth underscoring. First, the fundamentals-based rule delivered as the special case $\rho = \phi_\pi = \phi_x = 0$ is undesirable under both rational expectations and learning. Evans and Honkapohja (2003b) and Preston (2005) provide results on expectations stability. Taken together these results underscore the basic rational expectations insights of Sargent and Wallace (1975) and McCallum (1983) regarding implementation of policy using nominal interest-rate rules continue to be germane under learning dynamics. Second, rules that exhibit history dependence promote stability under learning dynamics in so far as weaker responses to contemporaneous inflation and the output gap are permitted. While this observation is an immediate implication of Result 1b, it holds more generally. Preston (2008) provides a number of related examples in which nominal interest rates respond to the past price level or the output gap. The intuition for this property stems from the self-referential nature of learning dynamics. Greater inertia makes nominal interest rates more predictable, which facilitates learning the true data-generating process describing the evolution of interest rates. The role of history dependence in promoting expectational stability deserves further study, in particular in models with decision rules based on the anticipated utility framework, where aggregate demand depends on the entire path of future expected interest rates. It is a property of desirable policies under learning dynamics to which this survey repeatedly returns.

Taylor rules responding to contemporaneous information have garnered criticism on the ground that central banks do not possess such information in practice. For example, McCallum (1999) argues policy should be operational, responding only to endogenous variables that are observed prior to making an interest-rate decision. Additional practical complications arise from key macroeconomic variables being imperfectly observed because of time lags in data collection; because of frequent revisions in estimates provided by statistical agencies; or because variables like the natural rate of output are not directly observable. A central bank might also not want to respond to contemporaneous information because of

¹⁵For example, Duffy and Xiao (2011) show that including capital alters many basic results under both learning and rational expectations. The review also assumes a closed economy: there are open-economy extensions such as Llosa and Tuesta (2008), Llosa and Tuesta (2009), Bullard and Singh (2008) and Bullard and Schaling (2005). Branch, Davig, and McGough (2008) examine the stability properties of the New Keynesian model with regime switching in policy rules. We also do not discuss questions of hyperinflation — see Marcet and Nicolini (2003) and Adam, Evans, and Honkapohja (2006).

lags in the transmission of monetary policy. Such delays in evaluating the effects of policy on its target variables poses the problem of how to monitor policy performance. Because of these considerations Svensson (2003) argues that policy should be formulated in terms of forecast targeting. For example, a central bank should aim to achieve targets of the form

$$\hat{E}_{t-j}\pi_{t+k} + \frac{\lambda_x}{\kappa} \left(\hat{E}_{t-j}x_{t+k} - \hat{E}_{t-j}x_{t+k-1} \right) = 0, \text{ for } j, k \geq 0 \quad (33)$$

an immediate generalization of the optimal commitment target criterion. More generally, researchers have explored policy rules that respond to expectations of inflation and the output gap such as

$$i_t = r_t^n + \phi_\pi \hat{E}_{t-j}\pi_{t+k} + \phi_x \hat{E}_{t-j}x_{t+k} \quad (34)$$

with the understanding that the central bank either responds to measured private-sector forecasts, or constructs forecasts in identical fashion. Rules of this kind are argued to perform well on several dimensions.¹⁶ First, for a wide range of parameters they deliver a locally unique equilibrium under rational expectations.¹⁷ Second, they have been shown to be robust to model uncertainty by Batini and Haldane (1999) and Levin, Wieland, and Williams (2003), and have been given empirical support by Clarida, Gali and Gertler (1998, 2000). However, learning models indicate some caution is appropriate.

Result 2. *Policy rules of the form (34) with response coefficients implying determinacy may not be robust to learning.*

This result due to Preston (2006) is developed further by Eusepi and Preston (2010) in a related analysis. To give a specific example, consider the policy rule (34) with $j = 1$ and $k = 0$, $\phi_x = 0$. In the benchmark model in the neighborhood of flexible prices ($\alpha \rightarrow 0$)

$$\phi_\pi > \frac{1}{1 - \beta}$$

is a necessary condition for expectational stability. This is a radically different prescription for policy, than mere satisfaction of the Taylor Principle. The discount factor of households is central here because it regulates the effects of shifting expectations on household spending plans, and, through the stochastic discount factor, firm price setting. The greater the patience, the more important are beliefs about future macroeconomic conditions for current economic outcomes — requiring a more aggressive policy to ensure price stability.

Further insight is provided by examining the long-term interest rate, implicitly defined in the New Keynesian model as

$$r_t^L = i_t + \hat{E}_t \sum_{T=t}^{\infty} \beta^{T-t} (\beta i_{T+1} - \pi_{T+1}).$$

¹⁶Modified versions of such rules can be designed to implement (33) at least under rational expectations — Eusepi and Preston (2010).

¹⁷Bernanke and Woodford (1997) show that local indeterminacy is possible when the response to inflation is overly aggressive. In the class of models considered here, the magnitude of the policy coefficient required for indeterminacy is outside the range of empirically plausible coefficients.

Agents have the forecasting model of the form (25) for inflation, interest rates and income. Consider a small increase in the perceived drift in inflation ($\omega_{t-1}^\pi > 0$) while initial expectations of income and the policy rate remain at steady state ($\omega_{t-1}^x = \omega_{t-1}^i = 0$). Substituting for the perceived drifts in inflation and interest-rate expectations we obtain

$$\begin{aligned} r_t^L &= \phi_\pi \omega_{t-1}^\pi + \frac{1}{1-\beta} (\beta \omega_{t-1}^i - \omega_{t-1}^\pi) \\ &= \phi_\pi \omega_{t-1}^\pi - \frac{1}{1-\beta} \omega_{t-1}^\pi \end{aligned}$$

where the second inequality substitutes for the initial beliefs about the interest rate. When $\phi_\pi < 1/(1-\beta)$ the expected path of the real rate declines, leading to higher aggregate demand, and, through the Phillips curve, an increase in inflation which partially validates the increase in expectations.

A crucial difference to a rational expectations analysis of this class of policy rule is the expected path of interest rates does not adjust immediately in response to the shift in inflation expectations. Because beliefs themselves are sluggish, and monetary policy adjusts with a one-period delay, long-term interest-rates increase only gradually.¹⁸ This places much of the burden of stabilization policy on current interest rates, rather than expected future rates — under rational expectations small changes in the current policy rate are efficiently transmitted to changes in long-rates to ensure determinacy of equilibrium. Observe also such rules are likely to generate substantial volatility in the policy rate, which would feedback in to interest-rate expectations. This self-referentiality is particularly important to later discussion of optimal policy and also the conduct of monetary policy when the zero lower bound on nominal interest rates is relevant.

This kind of instability contrasts with Bullard and Mitra (2002) which finds expectations-based rules (34) are consistent with E-Stability when the Taylor Principle holds. They conduct their analysis using equations (31) and (32) as decision rules and therefore the expected path of the interest rate plays no role for aggregate demand determination.¹⁹ Bullard and Eusepi (2014) present examples, both under anticipated utility and Euler equation approach, where policy rules of the form (34) can be unstable under learning while inducing a determinate equilibrium. The key factors that break the equivalence are information delays and the presence of a cost channel of monetary policy.²⁰

Result 2 rests on the assumption that the policy rate responds to forecasts produced using the same reduced-form model adopted by private agents. Evidently the use of such forecasts can be undesirable outside of rational expectations equilibrium. Preston (2006)

¹⁸Eusepi and Preston (2010) shows that the instability problem worsens if the private sector has the same information as the central bank. That is consumption and pricing decisions are taken with information delays.

¹⁹Eusepi (2005) and Ascari, Florio, and Gobbi (2014) provide similar examples of instability in models where only one-period-ahead expectations matter, but interest-rate decisions are made one-period in advance. These models differ to Bullard and Mitra (2002) in that expectations of one period interest rates affect consumptions plans — not the realized contemporaneous interest rate.

²⁰Bullard and Mitra (2002) and Evans and McGough (2007) also show that determinacy need not imply E-Stability in policy rules that are operational, responding only to lagged variables instead of forecasts.

shows that if a central bank instead forms inflation and output gap forecasts conditional on the correct model of the economy, which includes agents' expectations formation mechanism, then the Taylor principle is restored. Forecasting procedures of this kind internalize the consequences of current interest-rate decisions on household and firm expectations, including beliefs about future interest rates. An implication is even when implementing relatively simple instrument rules, a central bank may nonetheless require a sophisticated structural model to conduct monetary policy effectively. This is a feature of any forecast-based decision procedure. Evaluating expectations using a reduced-form model, such as a vector-autoregression, leads to potential instability. This topic is discussed further in subsequent sections.

5.2 Implementing optimal policy under REE

Modern central banks rarely articulate monetary policy strategy in terms of simple rules. Rather, the objective of policy is specified by a numerical target for inflation. For example, the Bank of England pursues an inflation targeting strategy in which policy is set to ensure forecasted inflation is at 2 percent at a two-year horizon. Similarly, the Reserve Bank of New Zealand is charged with keeping inflation between 1 and 3 percent over the medium term. More recently the Federal Reserve announced an inflation target of 2 percent. In addition to a numerical target considerable effort is undertaken: i) to assess the state of the economy; and ii) to convey information about how the target is to be achieved, specifically information regarding the economic model, or logic, guiding the choice of interest rate at any given time. Such communication helps manage expectations optimally, and also helps the public evaluate the credibility of announced policy commitments.

These strategies are examples of target criteria. The targeting rule approach appears to be an effective way to implement optimal monetary policy and is argued to be robust to a range of assumptions concerning the nature of economic disturbances that affect the economy. This section evaluates the robustness of target criteria considered optimal from the perspective of rational expectations. Like the previous discussion of simple rules, robustness is interpreted as the conditions required for expectational errors to be eliminated asymptotically.

Suppose the central bank correctly understands agents' behavior, accurately observes all long-horizon forecasts, and attempts to implement the inflation targeting rule

$$\pi_t = \frac{\lambda_x}{\kappa} (x_t - x_{t-1})$$

which is consistent with the optimal commitment equilibrium under rational expectations. The monetary authority therefore understands the true structural relations of the economy are given by (3) and (4). It can guarantee that the target criterion is satisfied by adjusting interest rates according to the following implied reaction function

$$\hat{i}_t = -x_t^* + \hat{E}_t \sum_{T=t}^{\infty} \beta^{T-t} [(1 - \beta) x_{T+1} - (\beta \hat{i}_{T+1} - \hat{\pi}_{T+1} - \hat{r}_T^n)] \quad (35)$$

where

$$x_t^* = \frac{\lambda_x}{\lambda_x + \kappa^2} x_{t-1} - \frac{\lambda_x}{\lambda_x + \kappa^2} \left[\hat{E}_t \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [\kappa\alpha\beta (x_{T+1} - u_T) + (1 - \alpha) \beta\pi_{T+1}] \right]$$

is the level of the output gap that jointly satisfied (4) and (10).

The implied reaction function is an example of an expectations-based instrument rule. The appropriate stance of policy at any point in time depends not only on the past output gap, but also expectations of income, interest rates, inflation, as well as the anticipated component of natural rates and cost-push shocks. Similar calculations and remarks apply to the target criterion (15) for optimal discretion. The discussion of simple instrument rules would perhaps suggest this approach to be susceptible to instability — this is not the case.

Result 3. *If the monetary authority correctly understands the structural equations (3) and (4), and is charged with implementing the inflation targeting rules (10), (15) then the economy is stable under learning dynamics for all parameter values.*

Evans and Honkapohja (2003, 2006) and Preston (2008) contain various stability results for this and related target criteria. An immediate implication is that the requirements for expectational stability and determinacy of rational expectations equilibrium are identical. This is our second important robustness result. Conditional on beliefs being in a sufficiently small neighborhood of rational expectations equilibrium, the target criterion approach, implemented by the implicit instrument rule (35), eliminates expectational errors and ensures convergence of the optimal commitment equilibrium. Woodford (2007) argues this to be a fundamental strength of the target criterion approach.

An obvious question presents itself: why is the instability inherent in simple forecast-based instrument rules not manifest here? The answer lies in the specific nature of dependence of interest-rate policy on expectations. The target criterion approach has the property that, conditional on current expectations, an interest rate can always be found that ensures satisfaction of the target criterion. Hence the dependence of policy on expectations is of a very specific kind, and one that ensures the objectives of policy are met. This is not the case for simple instrument rules. This confirms that implementation of optimal policy requires a substantial amount of information on the part of the central bank.

5.3 E-Stability under model mis-specification

Of course, a critical assumption is the central bank has knowledge of the true structural relations. Absent this information, the approach can lend itself to greater instability, providing insight into the practical concern of model uncertainty. Preston (2008) considers implementing the target criterion when the central bank projects the evolution of the economy mistakenly assuming either rational expectations, or that dynamics are given by the Euler equation approach (31) and (32). Because the true structural relations are given by (3) and (4) the instrument rules given by this decision procedure fail to ensure satisfaction of the target criterion. This leads to instability for many reasonable parameter values. To

give a concrete example, suppose the central bank mistakenly projects the evolution of the economy using (31) and (32) when in fact the true structural relations are (3) and (4). The target criterion then provides the implicit instrument rule (19) albeit with different expectations operator

$$i_t = \hat{E}_t x_{t+1} - \frac{\lambda_x}{\lambda_x + \kappa^2} x_{t-1} + \left(\frac{\beta\kappa}{\lambda_x + \kappa^2} + 1 \right) \hat{E}_t \pi_{t+1} + \frac{\kappa}{\lambda_x + \kappa^2} u_t + r_t^n.$$

But this rule generates instability for the same reasons as do rules covered by **Result 2** — even though it ensures unique implementation of the optimal commitment equilibrium under rational expectations, and would similarly ensure expectational stability if the true model under learning were given by relations (31) and (32).

What steps can a central bank take to mitigate instability from model uncertainty? Better outcomes can be achieved by the price-level targeting rule (14). As discussed, under rational expectations the target criteria (10) and (14) are equivalent, in so far as they imply the same state-contingent responses to economic disturbances. The difference between these two rules, in the case of learning dynamics, is that the price-level targeting rule specifies a different kind of subsequent behavior when one finds that (because the private sector does not behave as they were projected to do) one has failed to achieve the target criterion precisely. Thus the difference between the two rules is a different commitment as to how one will react to seeing that one has missed one's target. Under price-level targeting, current interest-rate policy does not inherit past mistakes — compare the target criterion (10) which depends on the lagged output gap. Freedom from this dependence eliminates scope for self-fulfilling expectations for the same logic underlying simple instrument rules that do not depend on one-period forecasts. The price-level targeting rule is more robust to learning dynamics and suggests optimal monetary policy might best be implemented by explicit reference to the path of the price level rather than the inflation rate.

To facilitate later discussion of the zero lower bound on nominal interest rates, it's useful to have an explicit characterization of a rule implied by price-level targeting. Suppose the central bank projects the evolution of the economy using (31) and (32) when implementing the price-level targeting rule (14). The implied instrument rule is

$$i_t = \frac{\kappa - \lambda_x}{(\kappa^2 + \lambda_x + \beta\lambda_x)} (p_{t-1} + u_t) + \hat{E}_t x_{t+1} + \frac{\beta\kappa + (\kappa^2 + \lambda_x)}{(\kappa^2 + \lambda_x + \beta\lambda_x)} \hat{E}_t p_{t+1} + r_t^n. \quad (36)$$

Again, this instrument rule uniquely implements the optimal commitment solution, and ensures expectational stability for all maintained parameters if the true economy is described by (31) and (32). However, it also ensures expectational stability for all plausible parameter values in the benchmark model. Price-level targeting rules display robustness to model uncertainty.

Result 4. *Implementation of PLT implies E-Stability under different models of the economy.*

6 Optimal Policy Under Learning

The previous section evaluates the robustness of optimal policy under rational expectations to small expectational errors. Emphasis was given to convergence: under what conditions will the economy under learning converge to rational expectations equilibrium. This is a rather narrow evaluation of optimal policy. Equally important is to assess whether the proposed policies perform well during the *transition to rational expectations* or in contexts where beliefs fail to converge to rational expectations equilibrium. For example, because economies are subject to constant structural change, agents might periodically update their forecasting models. A simple approach to modelling concern for structural change is perpetual learning, an example of which are the constant-gain algorithms discussed in section 4. This section discusses optimal policy design from the point of view of a policymaker facing an economy where market participants are constantly updating their model of the economy, or where initial beliefs are not too ‘close’ to rational expectations.

6.1 Optimal Simple Rules

Consider the class of targeting rule

$$\pi_t + \psi^{-1}x_t = 0 \tag{37}$$

where ψ is chosen by the monetary authority to maximize agents’ welfare. Different choices of ψ implicitly define different preferences over output gap and inflation stabilization. Because any choice of policy within this class will not be consistent with the optimal commitment equilibrium, this class of policy is referred to as a simple rule. Assume the central bank has direct control of the output gap as the instrument of policy and correct knowledge of the economy. The policymaker minimizes the loss function (7) by choice of ψ subject to the Phillips curve (4) and beliefs. Firms forecast future marginal costs, which are proportional to the output gap, and inflation using the a model of the form (25)

$$\begin{bmatrix} \pi_t \\ x_t \end{bmatrix} = \begin{bmatrix} \omega_{t-1}^\pi \\ \omega_{t-1}^x \end{bmatrix} + e_t$$

with beliefs revised according to the constant-gain algorithm (26). Evaluating agents’ expectations in the Phillips curve and substituting for the current output gap using the targeting rule (37) gives

$$\pi_t = \frac{\alpha\beta\kappa}{(1 + \psi\kappa)(1 - \alpha\beta)}\omega_{t-1}^x + \frac{(1 - \alpha)\beta}{(1 + \psi\kappa)(1 - \alpha\beta)}\omega_{t-1}^\pi + \frac{\kappa}{1 + \psi\kappa}u_t.$$

Because in equilibrium beliefs satisfy $\omega_t^x = -\psi\omega_t^\pi$, only expectations about long-term inflation play an important role in inflation dynamics.²¹ Model dynamics are summarized by

²¹Assume for simplicity that initial beliefs are $\omega_0^\pi = \omega_0^x = 0$.

the equations

$$\pi_t = T_\pi(\psi) \cdot \omega_{t-1}^\pi + \frac{\kappa}{1 + \psi\kappa} u_t \quad (38)$$

$$\omega_t^\pi = \omega_{t-1}^\pi + \bar{g} \left(\left[(T(\psi) - 1) \omega_{t-1}^\pi + \frac{\kappa}{1 + \psi\kappa} u_t \right] \right) \quad (39)$$

where

$$T_\pi(\psi) = \frac{\beta}{(1 - \alpha\beta)} \left(\frac{1}{(1 + \psi\kappa)} - \alpha \right).$$

The second term on the right hand side of (38) corresponds to the inflation response under rational expectations where $\omega_{t-1}^\pi = 0$ for all t — compare the solution under optimal discretion. The first term captures the drift in realized inflation generated by time-varying beliefs. Orphanides and Williams (2005c) refer to drift in beliefs about inflation as *inflation scares*. Cost-push shocks lead to fluctuations in beliefs, which in turn move inflation, partially validating the initial shift in expectations. This is another analytical example of the self-referential aspect of learning central to the design of monetary policy. Higher estimates of the inflation drift translate into higher actual inflation. More importantly, the stronger the feedback effects, as measured by the drift coefficient, the more self-confirming any changes in beliefs. In the limiting case where the coefficient approaches unity, the drift becomes a random walk: perceived and actual model of the economy can then be arbitrary close.

A policy rule that is more aggressive towards inflation (i.e. one that assigns less weight to output gap stabilization) weakens the feedback from inflation expectations to actual inflation. For sufficiently low values of ψ the coefficient on long-term inflation expectations is positive, implying strong feedback effects. As ψ decreases, and policy becomes more aggressive, these feedback effects decline until they are reversed: an increase in inflation expectations is met by a decline in actual inflation. This is the key insight of papers by Bomfim, Tetlow, von zur Muehlen, and Williams (1997), Orphanides and Williams (2005a, 2005b, 2005c, 2007) and Ferrero (2007). Optimal monetary policy in this class of rule prescribes the central bank to be more conservative than it would be under rational expectations, to respond more aggressively to inflation and inflation expectations.

Figure 4 illustrates this point, plotting the variances of inflation and output gap as a function of the parameter $\tilde{\lambda}_x = \psi^{-1}\kappa$.²² The solid gray line corresponds to the model under rational expectations, where volatility is minimized with $\psi^{-1} = \lambda_x/\kappa$. The dashed black line, the model under learning, indicates a targeting rule with less weight on the output gap (roughly half in this example) leads to a better outcome. This can be interpreted as a more conservative central banker with $\tilde{\psi}^{-1} = \tilde{\lambda}_x/\kappa$, where $\tilde{\lambda}_x < \lambda_x$. Notice that we consider an example where the central bank assigns non-trivial weight to output gap stabilization. As the weight λ_x decreases the differences between rational expectations and learning become negligible.

²²The Figure is produced using standard parameters in the literature: $\alpha = 0.7$; $\beta = 0.99$; σ_u^2 , the variance of the cost-push shock is set to one. Finally, the preference parameter is set to $\lambda_x = 0.25$.

In the model described above agents use a constant-gain algorithm. The same results obtain if agents instead update their parameters according to a decreasing-gain algorithm. In this case, the time-varying drifts eventually vanish as agents learn the rational expectations equilibrium. However, as discussed in Tetlow and von zur Muehlen (2001) and Ferrero (2007), policy plays a key role in determining the speed of convergence of the learning process. A targeting rule with an aggressive response to inflation implies fast convergence to rational expectations. Conversely a targeting rule implying higher weight on output gap stabilization induces slow convergence.²³ Ferrero (2007) also shows that the asymptotic variance of the estimated drift is larger for less aggressive policies. In other words, the volatility of agents' beliefs is determined by the strength of feedback effects from learning.

Formally Ferrero (2007) considers the performance under learning of a particular class of monetary policy rules analogous to the expectations-based rule (19) for optimal discretion:

$$i_t = \gamma_\pi \hat{E}_t \pi_{t+1} + \hat{E}_t x_{t+1} + r_t^n.$$

Orphanides and Williams (2005) and Ferrero (2007) emphasize monetary policy rules that respond to *expected inflation* have powerful stabilizing properties. Using the Euler equation approach Ferrero (2007) characterizes the set of adjusted-learning-speed parameters, γ_π^{ALS} , that are consistent with both asymptotic convergence to optimal discretion policy under rational expectations and a further requirement that learning is suitably quick.²⁴ Parameter values for γ_π^{ALS} that are larger than the corresponding coefficient in the expectations-based reaction function (under optimal discretion and rational expectations) imply faster convergence and, for many parameter values, higher welfare.

Result 5. *Under learning, a stronger response to inflation relative to optimal policy under rational expectations improves the stabilization trade-off.*

Orphanides and Williams (2007, 2008) push this analysis further to understand the performance of simple rules when confronted with model uncertainty. They consider a class of New Keynesian models of the form

$$\begin{aligned} x_t &= (1 - \xi_x) \hat{E}_{t-1} x_{t+1} + \xi_x x_{t-1} - \sigma^{-1} \hat{E}_{t-1} \left(i_t - \hat{E}_t \pi_{t+1} - r_t^n \right) + \varphi_t \\ \pi_t &= \kappa \hat{E}_{t-1} x_t + (1 - \xi_\pi) \hat{E}_{t-1} \pi_{t+1} + \xi_\pi \pi_{t-1} + u_t, \end{aligned} \tag{40}$$

where σ^{-1} denotes the sensitivity of aggregate demand to real interest rate changes, φ_t is a first-order autoregressive demand shock and u_t are i.i.d. cost-push shocks. The lagged values of inflation and gap can be motivated by inflation indexation in price setting, ξ_π , and some form of habit persistence in consumption demand, ξ_x , while the timing of information can be justified with information delays — Woodford (2003a) details these model extensions. In contrast to the model of section 2, x_t is interpreted as unemployment. To provide a

²³As shown in Marcat and Sargent (1989), if the coefficient on the drift $T_\pi(\cdot)$ is less than 0.5 then the agents' estimate of the drift converges at the same speed as it would in absence of self-referential effects.

²⁴See also Ascari, Florio, and Gobbi (2014) for a related analysis in models with trend inflation.

quantitative assessment on the effects of learning on the design of optimal policy, the model is estimated using US data.²⁵

Policy analysis is conducted via model simulation. Expectations are formed using the framework described in section 4. The forecasting model of agents is a vector autoregression in unemployment, inflation and the interest rate. In the case where the natural rate of interest and the natural unemployment rate are constant ($r_t^n = y_t^n = 0$), which is the one considered here, this forecasting model nests the minimum-state-variable solution under rational expectations. The forecasting model is updated using a constant-gain learning algorithm of the form (24). The range of constant gains used is calibrated to imply expectations that have comparable properties with survey-based forecasts.

Two main conclusions emerge from this analysis, generalizing **Result 5**. First, consistent with the asymptotic stability analysis of Evans and Honkapohja (2006) and Preston (2008), optimal control policies derived under rational expectations perform poorly when the true model has constant-gain learning. The key reason behind this failure is such policies imply a response to inflation that is too mild to stabilize inflation expectations under learning. Optimal control policies under rational expectations that would arise under a more conservative central banker deliver a better performance under learning, consistent with **Figure 4**. Second, simple operational policy rules, which respond to expected or lagged inflation, lagged unemployment gaps and lagged interest rate deliver a consistently good performance under learning. A key feature of such rules is the relatively strong response to inflation and a high degree of interest smoothing — further evidence that interest-rate inertia is desirable under both rational expectations and learning dynamics, and that such rules are robust to model uncertainty.

6.2 Optimal policy under full control

The previous section explores optimal policy design within a restricted class of policies. The analysis now turns to characterizing the fully optimal policy under learning dynamics. To do this assume that the central bank has rational expectations and has complete knowledge of the true structural relations describing household and firm behavior. Interpret this as a best-case scenario. To the extent that learning dynamics impose constraints on what the central bank can achieve, these difficulties will only be more acute with limited information. Moreover, the nature of these constraints might inform the choice of simple policy rules.

Continue with the thought experiment of the previous section and assume the central bank has direct control of the output gap as the instrument of policy. The consequences of modeling the transmission mechanism is taken up in the sequel. The policymaker minimizes the loss function (7) subject to the Phillips curve (4) and the evolution of beliefs ω_t^x and

²⁵The observable variables used in estimation are inflation and the unemployment rate, together with survey-based forecasts of inflation, unemployment and the short-term interest rate as proxies for expectations, taken from the Survey of Professional Forecasters. The unemployment gap is proxied using available estimates of NAIRU from the Congressional Budget Office.

ω_t^π , updated according to the constant-gain algorithm

$$\begin{bmatrix} \omega_t^\pi \\ \omega_t^x \end{bmatrix} = \begin{bmatrix} \omega_{t-1}^\pi \\ \omega_{t-1}^x \end{bmatrix} + \bar{g} \left(\begin{bmatrix} \pi_t \\ x_t \end{bmatrix} - \begin{bmatrix} \omega_{t-1}^\pi \\ \omega_{t-1}^x \end{bmatrix} \right). \quad (41)$$

In contrast to a rational expectations analysis beliefs are now part of the state space — there is no distinction between commitment and discretion. The loss function continues to be the welfare-theoretic loss implied by a second-order approximation to utility. Imperfect knowledge does not affect these calculations. First-order conditions to the optimal policy problem are

$$\begin{aligned} \pi_t - \lambda_{1,t} + \bar{g}\lambda_{2,t} &= 0 \\ x_t + \lambda_{1,t} \frac{(1-\alpha)(1-\alpha\beta)}{\lambda_x \alpha} + \frac{1}{\lambda_x} \lambda_{3,t} \bar{g} &= 0 \\ (1-\alpha)\beta E_t \lambda_{1,t+1} - \lambda_{3,t} + \beta(1-\bar{g}) E_t \lambda_{3,t+1} &= 0 \\ \frac{(1-\alpha)\beta}{1-\alpha\beta} \beta E_t \lambda_{1,t+1} - \lambda_{2,t} + \beta(1-\bar{g}) E_t \lambda_{2,t+1} &= 0. \end{aligned}$$

where $\{\lambda_{1t}, \lambda_{2t}, \lambda_{3t}\}$ are the Lagrange multipliers on the constraints (4) and (41). To give further insight to these relations, consider an economy in the neighborhood of flexible prices so that $\alpha \rightarrow 0$. Using the fact that the optimal welfare-theoretic weight on the output gap is $\lambda_x = \kappa/\bar{\theta}$ — see Woodford (2003a) — permits derivation of the consolidated first-order condition

$$\pi_t = \bar{\theta}^{-1} \left(x_t - \bar{g}\beta^2 \mathbb{E}_t \sum_{T=t}^{\infty} [\beta(1-\bar{g})]^{T-t} x_{T+1} \right). \quad (42)$$

This target criterion, first derived by Molnar and Santoro (2013), states inflation should be proportional to the output gap, adjusted for the expected discounted value of the sequence of output gaps into the infinite future. The relevant discount is given by the product of the households discount factor, β , and one minus the gain.

Several insights are forthcoming. First, for gains in the neighborhood of zero, $\bar{g} \rightarrow 0$, optimal policy is equivalent to optimal discretion under rational expectations — compare equation (15). The intuition is immediate. For gain coefficients that are nearly zero, beliefs are almost never revised: policy cannot influence them. The policy problem is then formally equivalent to optimal discretion under rational expectations. This logic also holds for the asymptotic behavior of an economy where agents update their beliefs using a time-dependent gain sequence, $g_t = t^{-1}$. Second, for a given gain coefficient, policy will be more aggressive towards inflation relative to optimal discretion. Consider a sequence of positive forecasts for the output gap. The target criterion stipulates inflation should be lower today relative to the optimal policy under rational expectations. Policy should limit drift in inflation expectations by keeping inflation close to target, implicitly defined as price stability. This result, consistent with the findings of Ferrero (2007) and Orphanides and Williams (2005a)

discussed above, underscores learning dynamics present an additional trade-off confronting monetary policy. Drifting beliefs constrain what can be achieved by the monetary authority today.

Result 6. *Optimal policy reveals an additional intertemporal trade-off. Policy is more responsive to inflation to limit future movements in inflation expectations which worsen the short-run trade-off between inflation and the output gap.*

The source of this trade-off resides in the sluggish adjustment of beliefs which induce history dependence in the optimal adjustment of the policy instrument. The solution for the output gap and inflation under optimal policy takes the form

$$\begin{bmatrix} \pi_t \\ x_t \end{bmatrix} = \bar{c}_\pi \omega_{t-1}^\pi + \bar{c}_x \omega_{t-1}^x + \bar{c}_u u_t. \quad (43)$$

Solving (41) recursively backwards in conjunction with (43) permits (42) to be written

$$\pi_t = \bar{\theta}^{-1} x_t - \sum_{j=1}^{\infty} (1 - \bar{g})^j (\tilde{c}_\pi \pi_{t-j} + \tilde{c}_x x_{t-j}) - \tilde{c}_u u_t.$$

This formulation emphasizes that optimal policy under learning shares some of the features of optimal policy under commitment in the case of rational expectations. To better see this, **Figure 5** displays impulse responses of inflation and the output gap to a one standard deviation shock to u_t , under different policy configurations.²⁶ The top panels describe impulse responses when the weight on output gap stabilization is consistent with the model's microfoundations ($\lambda_x = \kappa/\bar{\theta} \simeq 0.014$). The black solid line denotes the impulse response with optimal policy under learning, the solid gray line shows the response with the targeting rule (10) under learning. Finally, the dashed black line describes the impulse response under optimal commitment. The two policies under learning imply very similar responses, because the weight on the output gap consistent with microfoundations is fairly small. Similarly to optimal commitment under rational expectations, optimal policy under learning drives inflation below its steady state, although the size of the decline is smaller. Recall this decline is absent under optimal discretion. This decline in inflation leads to faster convergence to the equilibrium.

The response of the output gap is different. The output gap exhibits inertia, but, in contrast with the commitment solution, converges monotonically from above steady state. The reason for this is lower inflation leads to a downward revision of the *entire path* of inflation expectations, increasing the output gap in equilibrium. Under rational expectations inflation expectations decline only in the short-term, leading to smaller but still negative output gap. When the central bank has a stronger preference for output stabilization, inflation remains positive under the optimal learning policy, but the central bank is more aggressive towards inflation compared to a targeting rule that does not take expectations

²⁶The parameters used are the same as for Figure 4.

formation into account. Overall, optimal policy is closer to the commitment solution than under the simple targeting rule.²⁷

The gains from policy inertia are taken up further in Gaspar, Smets and Vestin (2007, 2010) and Mele, Molnar, and Santoro (2012). Gaspar, Smets and Vestin consider a model in which only one-period-ahead expectations matter to spending and pricing decisions. In contrast to the above discussion, beliefs include additional state variables and are non-linear, formed by least-squares regression. They show that optimal policy conditional on this more general belief structure continues to be inertial, and continues to be more aggressive towards inflation compared to optimal discretion. Mele, Molnar and Santoro (2013) adopt a similar modeling strategy to find that the optimal commitment equilibrium is not optimal under learning: for decreasing-gain learning algorithms the optimal long-run policy under learning is optimal discretion. As discussed in section 7.6, because the commitment solution yields the highest welfare gain when a zero lower bound is considered, further research should evaluate the robustness of this result in such model environment.

Result 7. *Optimal policy under learning displays history dependence which results in tighter inflation control. However, it is a different kind of history dependence than what is implied by optimal commitment under rational expectations. In particular, agents' expectations need not display history dependence beyond what implied by their beliefs' updating rule.*

A final property of the Molnar and Santoro optimal policy problem is that policy delivers Divine Coincidence — disturbances to the natural rate of interest are completely stabilized. This property emerges as a special case in the anticipated utility environment, but fails to hold more generally. Suppose firm production is subject to an aggregate exogenous productivity shock. Aggregating the optimal pricing rules of firms yields the Phillips curve

$$\pi_t = \hat{E}_t \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [\kappa(w_T - a_T + u_T) + (1 - \alpha)\beta\pi_{T+1}]$$

where a_t denotes technology shocks. In this model the output gap is not the same as the real wage. Formally $x_t = y_t - y_t^n = y_t - a_t = w_t$. If agents forecast real wages according to

$$\omega_t^w = \omega_{t-1}^w + \bar{g}(x_t + a_t - \omega_{t-1}^w)$$

an additional shock enters in the central bank's constraint set, creating a trade-off. The equilibrium dynamics under optimal policy become

$$\begin{bmatrix} \pi_t \\ x_t \end{bmatrix} = \hat{c}_\pi \omega_{t-1}^\pi + \hat{c}_x \omega_{t-1}^x + \hat{c}_a a_t + \hat{c}_u u_t$$

²⁷These results rely on the central bank having correct knowledge of the agents' expectations formation mechanism. However, Molnar and Santoro show that these policy prescriptions are robust to policymaker uncertainty about the expectations formation process. In particular, using either a robust control max-min or Bayesian model averaging criterion they show that optimal policy under learning performs well even when private agents have rational expectations.

so that full stabilization of both inflation and output gap is not possible. Because technology shocks affect beliefs about the permanent level of real wages, firm’s marginal cost structures shift as households adjust labor supply. Positive technology shocks are stagflationary — see Eusepi, Giannoni, and Preston (2012). The next section reveals this stabilization challenge becomes more acute once one models the transmission mechanism of monetary policy. This is another example where the Euler Equation and anticipated utility approaches provide different conclusions.

6.3 Modeling the Transmission Mechanism

A large literature in monetary economics concerns the transmission mechanism: how do changes in short-term interest rates, the policy instrument under control of the policy-maker, affect economic decisions? The previous sections side-step this question by assuming the central bank has direct control of the output gap. This assumption is now relaxed. In the context of the current model, the transmission mechanism operates through aggregate demand: current and expected future interest rates regulate current spending and savings plans. This section demonstrates that additional trade-offs confront policymakers when account is taken of the transmission mechanism. Importantly, the case for aggressive monetary policy is weakened, and indeed, reversed: relative to optimal discretion, interest rates should adjust by less in response to economic disturbances. As a consequence, Divine Coincidence does not hold — it is no longer possible to fully stabilize inflation and the output gap, even in absence of technology shocks.

To introduce the result, recall when implementing the optimal targeting rule under rational expectations (10), the implied reaction function is given by (35). This rule reveals *policy expectations* play a key role in the ability of the central bank to stabilize the economy. The effectiveness of monetary policy in the New Keynesian model lies in the ability to manage the entire term structure of interest-rate expectations. Under rational expectations, interest-rate beliefs are consistent with the monetary policy strategy of the central bank, permitting tight control of aggregate demand. Under imperfect information, policy expectations need not be consistent with policy strategy, with important consequences for policy design. Reflecting this difficulty, and in contrast to the E-Stability results discussed in section 5, Eusepi, Giannoni, and Preston (2012) show that under constant-gain learning, targeting rules of the form (15) cannot be implemented: reaction functions of the form (35) imply instability under learning for many plausible parameter values — recall in section 4.3 E-Stability and stability conditions under constant-gain learning need not be the same.²⁸

The key to this instability is the dynamics of policy expectations. In the benchmark model, households and firms must forecast inflation, income and interest rates. Assume agents update their estimate of the drifts according to

$$\begin{bmatrix} \omega_t^\pi \\ \omega_t^x \\ \omega_t^i \end{bmatrix} = \begin{bmatrix} \omega_{t-1}^\pi \\ \omega_{t-1}^x \\ \omega_{t-1}^i \end{bmatrix} + \bar{g} \left(\begin{bmatrix} \pi_t \\ x_t \\ i_t \end{bmatrix} - \begin{bmatrix} \omega_{t-1}^\pi \\ \omega_{t-1}^x \\ \omega_{t-1}^i \end{bmatrix} \right). \quad (44)$$

²⁸See Evans and Honkapohja (2009c) for a detailed analysis of this issue.

To keep things simple suppose there are only i.i.d. shocks to the natural rate r_t^n and beliefs are initially consistent with rational expectations equilibrium providing $\omega_{t-1}^\pi = \omega_{t-1}^x = \omega_{t-1}^i = 0$. Period t equilibrium is determined by the aggregate supply and demand curves, (3) and (4), which simplify to

$$\pi_t = \kappa x_t \quad \text{and} \quad x_t = -(i_t - r_t^n).$$

Given a disturbance to the natural rate of interest, complete stabilization is possible in period t . Nominal interest-rate policy must track the natural rate, $i_t = r_t^n$, giving $\pi_t = x_t = 0$. But this implies subsequent movements in long-run interest-rate beliefs according to

$$\omega_t^i = \omega_{t-1}^i + \bar{g} (r_t^n - \omega_{t-1}^i).$$

The next-period's stabilization problem — and every subsequent period — is given by the pair of equations

$$\begin{aligned} \pi_{t+1} &= \kappa x_{t+1} \\ x_{t+1} &= -(i_{t+1} - r_{t+1}^n) - \frac{1}{1-\beta} \beta \omega_t^i. \end{aligned}$$

Stabilization is again possible with nominal interest rates tracking long-run expectations and the natural rate of interest. But is this interplay sustainable? Imposing full stabilization $x_{t+1} = \pi_{t+1} = 0$ the aggregate demand constraint defines the implicit policy rule

$$i_{t+1} = r_{t+1}^n - \frac{\beta}{1-\beta} \omega_t^i$$

in every period t . Substituting into the updating rule for beliefs, ω_t^i , gives

$$\omega_{t+1}^i = \left(1 + \frac{\bar{g}}{1-\beta}\right) \omega_t^i + \bar{g} r_{t+1}^n$$

which is a first-order difference equation. Sustainable policy requires the dynamics of beliefs to be stationary. The following restriction must hold

$$\bar{g} < 2(1-\beta).$$

For larger gains, stability is not feasible, implying beliefs and, concomitantly, interest rates are explosive. This is not a permissible, or at least desirable, feature of optimal policy if only because the zero lower bound on interest rates obviates such solutions.

Result 8. *In the benchmark model given by (3) and (4), and shocks to the natural level of output, Divine Coincidence does not hold in absence of cost-push shocks.*

This result, due to Eusepi, Giannoni, and Preston (2012), stands in direct opposition to the earlier literature. The crucial difference when compared to rational expectations

and the Euler equation approach to learning is that the optimal policy problem includes aggregate demand (3) as a constraint, because interest-rate beliefs are also a relevant state variable. Given unique paths for income and inflation, and associated beliefs, there need not be a unique path for interest rates — depending as they do on households’ interest-rate projections.

Optimal policy, for plausible gains, stipulates less aggressive responses to economic developments. The transmission mechanism embodies a new intertemporal trade-off confronting optimal policy. The difficulty emerges from drift in interest-rate beliefs, and in consequence, long-term interest rates themselves. In response to a natural-rate disturbance the central bank would like to increase current interest rates. Subsequently, in revising beliefs, the resulting positive forecast error is parsed into permanent and transitory effects on beliefs, resulting in a belief that interest rates are permanently higher. This process induces instability in the yield curve which, in turn, generates instability in aggregate demand. For higher gain coefficients this difficulty becomes more acute. A given sized disturbance translates into a larger revision to the permanent component of beliefs making it optimal to move interest rates even less.

Figure 6 shows the standard deviations of output gap (dashed lines) and interest rate (solid lines) as a function of the constant gain \bar{g} under the optimal policy. Only variations in the natural rate r_t^n , assumed to be i.i.d., drive economic fluctuations. The figure describes outcomes under the loss function (7), captured by the black lines, and under a loss function that also penalizes volatility in the interest rate (gray lines).²⁹ Recall optimal discretion (rational expectations) corresponds to the case where $\bar{g} = 0$. Under the standard loss function a knife edge result obtains: for $\bar{g} < 2(1 - \beta)$ the output gap is fully stabilized even if this induces substantial volatility to the interest rate. For larger values of \bar{g} , the policymaker loses the ability to stabilize the output gap. Feasible policy permits limited variation in the policy rate, translating into increasing volatility of the output gap. If the policymaker has some preference for interest-rate stabilization (perhaps reflecting zero lower bound considerations), then the increase in output volatility occurs continuously with the size of the gain. Even relatively small values of the gain lead to considerable output gap volatility.

Figure 7 shows the volatility of inflation and output (weighted with λ_x) as a function of λ_x , for three different optimization problems. In this exercise the economy is driven by both cost-push and natural-rate shocks, assumed to be i.i.d.. The first policy (gray solid line) is optimal discretion, the second policy (dashed black line) is optimal policy under learning with the central bank having direct control of the output gap. The third policy is the optimal policy subject to the aggregate demand constraint. The figure suggests that, even in this very simple modeling framework, the quantitative impact of the aggregate demand constraint on monetary policy effectiveness can be nontrivial. Under full control of the output gap, optimal policy under learning tracks quite closely optimal discretion, at least for sufficiently low values of λ_x .

The consequences of the aggregate demand constraint are not specific to optimal policy. For example, **Figure 8** describes the stability properties under constant-gain learning of

²⁹The weight on interest rate volatility is calibrated to be equal to $\lambda_i = 0.004$.

a simple Taylor rule, where interest rates respond to inflation and the output gap — an example of ‘robust learning stability’ proposed by Evans and Honkapohja (2009c). Each of the three lines describe the stability frontier in the constant gain and inflation response coefficient space. Parameter regions above a plotted contour indicate local instability of the equilibrium. The black solid line corresponds to $\phi_x = 0.5/4$ (the standard Taylor rule), while the solid and dashed grey lines correspond to output response coefficients which are half and a third of the standard rule respectively. The figure reveals an aggressive stance on inflation, advocated in **Results 5** and **6**, might not be feasible. Secondly, a lower response to the output gap enhances stability but only for ranges of ϕ_π close to empirically plausible estimates.³⁰ Further investigation of the quantitative implications of drifting interest-rate beliefs has clear merit. In particular, understanding the advantages, if any, of interest-rate inertia, or policies that depend on the lagged price level would be beneficial. Optimal policies within these classes of rule should also be studied.³¹

6.4 Optimal policy with central bank learning

A defining feature of virtually all interest-rate decision procedures evaluated in this survey is the requirement that a central bank must have a structural model of the economy to implement policy. This is true of forecast-based Taylor rules, the inflation and price-level targeting rules, and also the various conceptions of optimal policy under learning.³² All these policies require the central bank to take a stand on the projected evolution of the economy given the policy framework when choosing the appropriate interest rate in any given period. This complication distinguishes the policymaker’s problem from that of households and firms, which, understanding their own objective and constraints, need only employ an a-theoretical statistical model to forecast variables exogenous to their decision problem. Some examples of the consequences arising from a central bank with a misspecified model have already been given. For example, a central bank that makes interest-rate decisions based on a rational expectations model, when in fact agents are learning. But this kind of misspecification is quiet on the issue of how a central bank might adjust their structural model in the light of poor performance. This section explores the consequences of central bank learning about the structural relations governing aggregate conditions.

Evans and Honkapohja (2003b) consider a central bank which sets optimal discretionary policy using an expectations-based instrument rule, as described in section 5. In contrast to earlier discussion, the policymaker has incomplete information about true structure of the economy. Specifically, it lacks knowledge of two key structural parameters which govern the transmission mechanism of monetary policy: the interest elasticity of aggregate demand and the slope of the Phillips curve. Because the central bank observes all aggregate data, including expectations, it can recursively estimate the structural parameters, ϕ and κ , using

³⁰Evans and Honkapohja (2009c) obtain a similar result under a forecast-based policy rule.

³¹For example, Evans and McGough (2007) study the E-stability properties of a class of optimized Taylor-type rules. Constant-gain algorithms are not considered.

³²Technically, any decision procedure in which nominal interest rates respond to endogenous contemporaneous information requires the central bank to have structural model. This includes the standard Taylor rule.

the regressions

$$x_t - \hat{E}_t x_{t+1} - r_t^n = -\phi \left(i_t - \hat{E}_t \pi_{t+1} \right) + e_{x,t}$$

$$\pi_t - u_t - \beta \hat{E}_t \pi_{t+1} = \kappa x_t + e_{\pi,t}.$$

The central bank's reaction function

$$i_t = \left(1 + \frac{\hat{\kappa}_{t-1} \beta}{(\hat{\kappa}_{t-1}^2 + \lambda_x) \hat{\phi}_{t-1}} \right) \hat{E}_t \pi_{t+1} + \hat{\phi}_{t-1}^{-1} \hat{E}_t x_{t+1} + \frac{\hat{\kappa}_{t-1}}{(\hat{\kappa}_{t-1}^2 + \lambda_x) \hat{\phi}_{t-1}} u_t$$

has time-varying coefficients being functions of the current parameter estimates $\hat{\phi}_{t-1}$ and $\hat{\kappa}_{t-1}$. Estimation errors feedback into the economy through policy decisions, in turn affecting the beliefs of households and firms. However, given that the policymaker can observe private expectations, its model of the economy remains well-specified even during the learning process, unlike the private sector. This assumption limits the impact of central bank learning on the convergence process. And, for this reason, when both the private sector and the central bank are learning, convergence to rational expectations obtains.

A similar conclusion is reached by Dennis and Ravenna (2008) which considers a different information set up. The policymaker does not observe private-sector expectations and assumes incorrectly that expectations are formed rationally. The two structural parameters are then estimated using a general instrumental variable estimator, which imposes the orthogonality restrictions implied by rational expectations. Despite model mis-specification, numerical analysis shows that the economy converges to rational expectations. Policymaker learning can induce higher or lower welfare relative to rational expectations, depending on initial beliefs of both the central bank and the private sector.

These studies mainly focus on asymptotic outcomes under central bank learning. A particularly interesting literature extends these ideas to investigate the role of central bank learning in explaining the evolution of inflation in the post-war period, with particular emphasis on the Great inflation and the Volcker disinflation. At the core of these theories is an optimal policy framework in which policy deliberations are made with a potentially misspecified Phillips curve. Starting with the seminal work of Sargent (1999) various papers show how changing beliefs about the short-run inflation-unemployment trade-off can explain the evolution of US inflation in the 1970s and 1980s. The analyses are motivated by the observation that during the 1960s policymakers believed in an exploitable trade-off between unemployment and inflation and choose policy accordingly. The subsequent decade with high inflation and unemployment then induced belief in a version of the natural-rate hypothesis where no exploitable trade off exists, leading to the Volcker disinflation.

To give content to these ideas, introduce a Phillips curve of the form

$$\pi_t = \mu \pi_{t-1} + (1 - \mu) \mathbb{E}_{t-1} \pi_t + \kappa x_t + u_t \tag{45}$$

which can be derived by assuming a constant fraction of goods prices are fully flexible, while the remaining fraction are set one period in advance, on the basis of period $t - 1$

information, along with a fraction $(1 - \mu)$ of firms forming rational expectations, while the remaining fraction sets expectations in purely adaptive form: $\hat{E}_{t-1}\pi_t = \pi_{t-1}$. The output gap is assumed to be imperfectly measured, reflecting the practical challenge of obtaining an estimate of natural level of output y_t^n . (In the papers discussed here the Phillips curve is expressed in term of the unemployment gap, but this is not important for our discussion.) The central bank updates its estimate \hat{y}_t^n according to the updating rule

$$\hat{y}_t^n = \hat{y}_{t-1}^n + \bar{g}_y (\hat{y}_t - \hat{y}_{t-1}^n), \quad (46)$$

reflecting the belief that the natural level of output evolves according to a random walk. Orphanides (2001), Orphanides and Williams (2002) and Laubach and Williams (2003) document and discuss the evidence for very noisy estimates of natural rates, in particular during the 1970s.

Denote the estimate of the output gap as \hat{x}_t in each period t . This is the policy instrument of the central bank, albeit subject to control error. The central bank does not know the true structural Phillips curve. Policy is instead determined using the following empirical model for inflation

$$\pi_t = \omega_{0,t} + \omega_{\pi,t-1}\pi_{t-1} + \omega_{x,t-1}\hat{x}_t + u_t, \quad (47)$$

re-estimated every period using the recursive least-squares algorithm of the form (24) described in section 4. Furthermore, the monetary policy authority faces a one-period information delay so that the optimal policy, given their beliefs, that minimizes (7) is set according to the target criterion

$$\hat{E}_{t-1}\pi_t + \frac{\lambda_x}{\omega_{x,t-1}}\hat{E}_{t-1}(\hat{x}_t - \beta\omega_{\pi,t-1}\hat{x}_{t+1}) = 0. \quad (48)$$

The one-period delay captures reasonable information constraints on the part of the central bank.

Primiceri (2005) shows this class of model explains fairly well the rise and fall in inflation in post-war US. Three periods are identified. The first, referred to as the period of over optimism, is characterized by the wrong beliefs that the natural level of output was high relative to the truth, coupled with a low estimate of inflation persistence, $\omega_{\pi,t}$. Consistent with these beliefs, optimal policy tolerates rising inflation until the early 1970s. Because of this expansionary policy, during the second period, which spans the 1970s, policymakers revised upward their estimate of inflation persistence. A higher estimate of $\omega_{\pi,t}$ is consistent with a stronger response to inflation under optimal policy: expected inflation (an expected negative output gap) requires a lower current output gap, the higher the persistence of inflation. However, at the same time as updating beliefs to a more persistent inflation process, policymakers revised downward substantially their estimate of the slope of the Phillips curve, $\omega_{x,t}$. This reflected the joint rise of unemployment (a negative output gap) and inflation during the period. Again from (48), a flatter Phillips curve implies a weaker inflation response, which prevented policymakers aggressively fighting inflation delivering a period of over pessimism. Not until the 1980s did an upward revision of $\omega_{x,t}$ towards its true value lead to a successful disinflation.

In a closely related analysis, Sargent, Williams, and Zha (2006) show a combination of macroeconomic shocks and the central bank’s evolving beliefs can explain the rise and fall of inflation in the US. The parameters of the central bank’s learning algorithm and the true data-generating process are estimated to reverse engineer a sequence of government beliefs and shocks consistent with the evolution of inflation during the 1970s and 1980s. A key difference relative to Primiceri is the direction of fit in the estimation of the Phillips curve. In Sargent, Williams, and Zha (2006) the policymaker estimates a new classical version of (45), where the output gap (unemployment in the paper) is the dependent variable. In this setup, if the policymaker were to observe a weaker correlation between the output gap and inflation, resulting in a flat estimated Phillips curve, it would promote a quick disinflation because there is no short-run trade-off. This is exactly the opposite of the new Keynesian Phillips curve in Primiceri (2005): a flatter Phillips curve implies a more costly disinflation — observe the target criterion (48). For this reason Cogley and Sargent (2002) argue that during the 1970s a policymaker using a new classical Phillips curve should have detected the absence of trade-off fairly quickly. It becomes hard then to reconcile the late start of the Volcker disinflation with a new classical Phillips curve.

Cogley and Sargent (2005b) propose a solution by introducing model uncertainty. In particular, the policymaker is concerned about robustness and chooses optimal policy using three alternative models for the evolution of inflation. The models are estimated recursively, and the posterior probabilities associated with each model computed every period. Optimal policy is determined by a Bayesian model-averaging procedure. The first model is of the form (47). The second includes inflation in first differences as the dependent variable, implying no long-run trade-off between inflation and output gap. Finally the third is a New Classical Phillips curve with no short-run trade-off, where unemployment is the dependent variable. This is also chosen to be the correct reference model.

In absence of a concern for robustness the central bank would quickly learn about the correct model and disinflate quickly. However, disinflation would be very costly if the truth were in fact represented by one of the first two models with a relatively flat Phillips curve. Indeed, Cogley and Sargent (2005b) show that the loss from full disinflation would be unbounded! Even a small weight on these alternative models would justify a cautious approach to disinflation. Only when all models generated finite costs of disinflation does the policymaker act aggressively toward inflation. These results highlight that even a policymaker committed to maximizing the right loss function can induce persistent sub-optimal outcomes as a result of imperfect knowledge about the correct structure of the economy.

The results in section 5.3 emphasize uncertainty and imperfect information about the private sector’s expectations formation process, while here private-sector expectations formation does not play as much of a role. Orphanides and Williams (2002, 2007, 2013), however, show that the interaction between mismeasurement of natural rates and private sector learning adds a substantial degree of complexity to the central bank’s stabilization problem. Policymaker mistakes stemming from imperfect information about the economic environment are amplified by private-sector learning and forecasting problems.³³ The result

³³Although they do not focus on optimal policy, Lansing (2002) and Bullard and Eusepi (2005) emphasize that private-sector misperceptions about the natural rate and, more generally, about the model of the

is articulated using the estimated model described in section 6.1. In this case the natural rates r_t^n and y_t^n evolve according to first-order autoregressive processes. Neither the private sector nor the central bank observe these rates. The policymaker formulates its policies using estimates of the current natural rates and using an updating rule of the form (46). The private sector continues to form expectations according to a VAR in the observable variables.³⁴ Policy conducted using optimal control methods, under the assumption of rational expectations and perfect information, can perform very poorly. Using the model Orphanides and Williams (2012) explain the rise of inflation during the 1970s with a combination of three main factors. First, the central bank assigned a relatively high weight on output gap stabilization, λ_x . Second, its estimate of the natural level of output y_t^n was too optimistic. Third, optimal policy was designed without taking into account the uncertainty surrounding the correct model of the economy. Optimal policy resulted in the great inflation.

Finally, there are two additional stories that account for the US inflation trends in the 1970s and 1980s. The first is pioneered by Sargent (1999) and further explored in Cho, Williams, and Sargent (2002) and Sargent and Williams (2005). It adopts the same model described above, where the true data-generating process is a new classical Phillips curve, but adopts a parameter configuration that emphasizes specific dynamics under learning. They show the economy converges to the neighborhood of the time-consistent equilibrium outcome with positive inflation, reflecting a perceived trade-off between inflation and unemployment. However, in response to certain sequences of shocks the economy can temporarily ‘escape’ to the optimal Ramsey, time-inconsistent, outcome. During these episodes the central bank learns the natural-rate hypothesis and proceeds to disinflate.³⁵ The second story, in Lubik and Matthes (2014), assumes the private sector has full information and rational expectations, while the policymaker conducts policy using a reduced-form model of the economy that is re-estimated each period. In addition, the policymaker faces imperfect information about the current state of the economy. In this model, learning by the central bank results in a policy reaction function which induces an indeterminate equilibrium, generating inflation fluctuations similar to those observed during the 1970s. Overall, these contributions point to the following conclusion.

Result 9. *Imperfect information about natural rates and the structure of the model can lead to persistent deviations from policy objectives, despite full commitment by the policymaker.*

What kind of policy strategy could have avoided this outcome? Using simulation methods described in section 6.1, Orphanides and Williams (2007, 2013) show that inertial policy rules, which respond more aggressively to inflation and less to economic activity than under rational expectations, are robust to both private-sector learning (characterized by different constant gains \bar{g}) and alternative degrees of mismeasurement in natural rates — which is

economy, were as important in explaining the run up in inflation in the 1970s as the mistakes by the policymaker.

³⁴Note that, unlike for the case with constant natural rates, private agents’ forecasting model no longer nests the rational expectations solution.

³⁵Details on the study of escape dynamics can be found in Williams (2014).

related to the volatility of y_t^n and r_t^n , and the parameters in the updating rule (46). Policy rules with high inertia that respond the growth rate of output gap (unemployment) by construction do not respond as much to variations in the estimated natural rate, avoiding the propagation of policy mistakes on expectations. Orphanides and Williams (2007) show that inertial rules with such features can be justified as the outcome of a robust policy exercise using either Bayesian model averaging or a robust control approach. Moreover, Orphanides and Williams (2013) show with counterfactual simulations that, had the Federal Reserve followed such a rule, the great inflation would have been avoided and inflation expectations would have remained anchored through the 1970s and the 1980s. This result strengthens the claim in the previous sections that inertial rules are desirable under learning and imperfect information.

Summing up, the results exposed in 6 rely on the central bank having correct knowledge of the agents' expectations formation mechanism. However, the discussion above shows that these policy prescriptions are robust to policymaker uncertainty about the expectations formation process. In particular, they perform relatively well even when private agents have rational expectations or when derived under alternative parameters of the agents' learning process.

Result 10. *Operational policy rules of the form (20) with $\rho \rightarrow 1$ are robust to imperfect knowledge about the model environment.*

7 Extensions

The recent financial crisis and concomitant policy response raise fundamental questions about the generality of the theory explicated above. Two omissions are notable: the role of fiscal policy in monetary policy design; and the consequences of the zero lower bound on nominal interest rates for the choice of monetary policy rule. This section redresses this, demonstrating that both considerations represent important constraints on what monetary policy can achieve, but nonetheless, that the basic lessons already learned become of greater importance in these environments. Before tackling these issues we discuss the role of central bank communication in improving the efficacy of monetary policy. While a topic of considerable interests in its own right, it serves to introduce some ideas relevant to subsequent analysis.

7.1 Central Bank Communication

A central bank's communication strategy is a crucial ingredient of inflation targeting. Inflation targeting central banks devote considerable effort to communicating information about monetary policy. This includes providing an assessment of the state of the economy, as well as numerous details on the projected evolution of different macroeconomic variables of interest, and how these projections inform the stance of monetary policy. For example, many inflation targeters publish their forecasts of inflation and real activity, where these forecast

are conditioned on ‘appropriate policy’ which remains undisclosed. Notably, the Riksbank and Norges Bank also present forecasts of their key policy rate.

While such practice offers basic accountability, it serves another purpose — to influence inflation expectations to achieve the most efficient short-run trade-off between output and inflation. Indeed, it is often argued that the greatest benefit from successful implementation of inflation targeting is the anchoring of expectations, with its stabilizing effect on macroeconomic activity. Failing to anchor expectations might result in undesired fluctuations and economic instability. Yet despite the importance of communication strategies, relatively little formal analysis in the context of dynamic stochastic general equilibrium models has been done on the mechanisms by which communication might prove beneficial.

An appealing feature of learning models is the property that subjective beliefs can differ from the objective probabilities implied by the economic model. This permits defining meaningfully the notion of anchored expectations as those beliefs consistent with the monetary policy strategy of the central bank. The possibility of beliefs being inconsistent with monetary policy strategy and, therefore, unanchored, presents a challenge for stabilization policy and permits examination of the role of communication in policy design. Communication can be modeled as providing households and firms with certain kinds of information about the monetary authority’s policy strategy. This information serves to simplify the forecasting problem of agents and to coordinate expectations in a desirable way.

To give content to these ideas recall the discussion of forecast-based instruments rules that underpin **Result 2**. Such rules encourage divergent learning dynamics: the central difficulty is that agents, using a reduced-form model of inflation, income and nominal interest rates, project a path for real interest rates that is inconsistent with the monetary strategy of the central bank. Because forecasts for future real rates is the mechanism by which the central bank influences aggregate demand, stabilization policy is compromised. But what if the central bank conveys information about the adopted policy rule? Suppose the central bank announces policy will be implemented according to the simple rule (34) in all future periods. If this announcement is credible, knowledge of this rule simplifies agents’ forecasting problem. Rather than forecasting interest rates and inflation independently, forecasts can be made by combining reduced-form inflation forecasts with the policy rule to generate a policy-consistent forecast of the nominal interest rate. An advantage of this approach is agents’ forecasts of nominal interest rates will satisfy the Taylor Principle assuming $\phi_\pi > 1$. This confers advantages for stabilization policy. In fact, if agents make policy consistent forecasts then the Taylor principle is restored.

This basic insight is found in Preston (2006) and developed further by Eusepi and Preston (2010). They propose various strategies of this kind varying the types of information conveyed to private agents. In general, so long as the systematic component of policy is communicated, and understood to a reasonable degree of accuracy — for example agents have enough information to verify central bank’s rule by use of statistical analysis — then this result continues to hold: communication improves the management of expectations.

Result 11. *If the central bank conveys enough information so that the private sector can infer its reaction function, then the Taylor Principle is restored.*

The result suggests that publishing the forecast path for the policy rate is an important aspect of a central bank communication strategy. The joint publication of inflation, economic activity and interest-rate forecast, together with a fully articulated rationale behind the forecasts, allows agents to learn about the central bank reaction function. Indeed, one of the stated reasons for the Norges Bank to present its policy forecast is:

“As one of the reasons for publishing the forecast is to improve the general understanding of the Bank’s response pattern, it has been important to explain the logic behind the forecast. This includes shedding light on the considerations underlying each interest rate forecast and what their objectives and the trade-offs between them are”, Deputy Governor Jan F. Qvigstad, Limassol, 3 September 2010.

A range of papers explore related aspects of this basic idea. Orphanides and Williams (2005b) present a non microfounded model of inflation dynamics, where a central bank has direct control of inflation as the instrument of policy. While their model is always E-Stable, they show that communicating the inflation target, so that agents need not estimate a drift in their belief structure, enhances inflation control and is welfare improving. Eusepi and Preston (2010) demonstrates that communicating the inflation target may not assist if shocks are persistent. Central then is an understanding of the systematic component of policy. Branch and Evans (2013) demonstrate in a global analysis of the New Keynesian model, under the Euler equation approach, conditions under which inflation beliefs approximate a random walk and are nearly self-fulfilling. Such beliefs hamper implementation of the central bank’s inflation target. Again, credible communication of the intended inflation target resolves instability.

Similarly, Cogley, Matthes, and Sbordone (2014) consider the question of an optimal disinflation within a class of Taylor rules. They show agent uncertainty about the new policy can generate substantial instability leading to particular choices of monetary policy rule. Ascari, Florio, and Gobbi (2014), build on Eusepi (2005), showing communication improves E-Stability in models where only one-period-ahead expectations matter, but where average inflation rates are greater than zero. Finally, Honkapohja and Mitra (2014) provide a global analysis of the zero lower bound, and show communication greatly enhances stabilization properties of price level rules. This is further discussed in section 7.6.

Before moving on, a clear implication of the optimal policy exercises in section 6 is that interest-rate beliefs impose a fundamental constraint on a central bank’s pursuit of price stability. Of course, in the simple example developed there, if agents understood that long-term interest rates were in fact zero in deviations from steady state in all periods, then the aggregate demand equation would no longer be a constraint. While highly simplistic, it does suggest that communicating information about interest-rate policy, by providing projections of future interest-rate decisions in addition to inflation and output, is highly desirable. Announced paths of inflation and output may be consistent with a range of beliefs about future interest rates — which may lead to instability.

To conclude, the efficacy of monetary policy depends on two related ingredients. First, the central bank’s commitment to the policy is credible. Second, private agents can properly

evaluate the effects policy on economic decisions. While both these properties are intrinsic to a rational expectations equilibrium analysis, they need not be present in a learning analysis. When they are absent shifting expectations can confound a central bank's effort to implement their objectives. Communication plays a fundamental role in assisting agent understanding of the systematic component of policy, promoting economic stability.

7.2 A Model with Debt

This section introduces fiscal policy and explores the consequences for monetary policy design. A minimal set of assumptions are made to permit discussion of debt-management and tax policy. Consider a government seeking to finance a constant level of government purchases G by issuing government debt and levying lump-sum taxes. Two types of nominal assets are supplied by the government: one-period debt, B_t^s , in zero net supply with price $P_t^s = (1 + i_t)^{-1}$; and a more general portfolio of debt, B_t^m , in positive net supply with price P_t^m . Following Woodford (1998, 2001), the latter asset has payment structure $\rho^{T-(t+1)}$ for $T > t$ and $0 \leq \rho \leq 1$. The value of such an instrument issued in period t in any future period $t + j$ is $P_{t+j}^{m-j} = \rho^j P_{t+j}^m$. The asset can be interpreted as a portfolio of infinitely many bonds, with weights along the maturity structure given by $\rho^{T-(t+1)}$. Varying the parameter ρ varies the average duration of the asset. For example, when $\rho = 0$ the portfolio comprises one-period debt; and when $\rho = 1$ the portfolio comprises consol bonds. Taken together the flow budget constraint of the government is to a first-order approximation

$$\hat{b}_t^m = \beta^{-1} \left(\hat{b}_{t-1}^m - \hat{\pi}_t \right) + (\rho - 1) \hat{P}_t^m - (\beta^{-1} - 1) \hat{\tau}_t$$

where $b_t^m \equiv B_t^m / P_t$; $\hat{b}_t^m = \ln(b_t^m / \bar{b}^m)$; $\hat{P}_t^m = \ln(P_t^m / \bar{P}^m)$ and $\hat{\tau}_t = \ln(\hat{\tau}_t / \bar{\tau})$.

For simplicity of exposition, assume an endowment economy where individual income is determined by an exogenous i.i.d. process $y_t(i)$. Most results discussed below can be established with the endogenous supply of output and sticky prices. Eusepi and Preston (2013) demonstrate optimality, to a first-order approximation, requires

$$\hat{c}_t(i) = (1 - \beta) \hat{y}_t(i) - \sigma^{-1} \beta \hat{E}_t^i \sum_{T=t}^{\infty} \beta^{T-t} (\hat{i}_T - \hat{\pi}_{T+1}) + \delta \left(\hat{b}_{t-1}^m(i) - \hat{\pi}_t + \rho \beta \hat{P}_t^m + \beta \hat{E}_t^i \sum_{T=t}^{\infty} \beta^{T-t} (\hat{i}_T - \hat{\pi}_{T+1} - (\beta^{-1} - 1) \hat{\tau}_t(i)) \right) \quad (49)$$

where δ is the steady-state structural surplus to GDP ratio, which is proportional to the debt-to-GDP ratio and σ^{-1} is the consumption intertemporal elasticity of substitution. This consumption decision rule is a joint implication of first-order conditions governing the intertemporal allocation of consumption, the portfolio allocation decision across short- and long-term debt, and transversality.

Optimal decisions require forecasts of nominal interest rates, inflation and taxes into the indefinite future. The top line in (49) describes the evolution of consumption in absence of wealth effects from holding debt. This captures the standard transmission mechanism of

monetary policy in the model under rational expectations, under a Ricardian fiscal policy. The bottom line in (49), referred to as the ‘non-Ricardian’ component of consumption demand, measures the wealth effects from holding government debt net of taxes. It comprises three components. The first is the real value of debt holdings, the second measures the present value of real returns from holding debt (purchased in the current period) and the third component denotes the present value of taxes. In a rational expectations equilibrium analysis, these terms sum precisely to zero — they constitute the intertemporal budget constraint of the government. Under imperfect knowledge, incorrect forecasts of returns and taxes imply the public debt is perceived as net wealth.³⁶ The model therefore has two competing and opposing channels through which monetary policy affects aggregate demand: the first is the usual intertemporal substitution of consumption (measured by the parameter σ^{-1}); the second is wealth effects from asset holding (measured by the parameter δ).

From the households’ first-order conditions for asset holdings, a log-linear approximation to the no-arbitrage restriction yields the familiar expectations hypothesis of the yield curve. The price of the bond portfolio is

$$\hat{P}_t^m = -\hat{E}_t^i \sum_{T=t}^{\infty} (\beta\rho)^{T-t} \hat{v}_T. \quad (50)$$

The multiple-maturity debt portfolio is priced as the expected present discounted value of all future one-period interest rates, where the discount factor is given by $\beta\rho$. Finally, the model is closed with a description of monetary and fiscal rules, and market-clearing conditions. Once again, the central bank sets nominal interest rates according to a Taylor-type rule

$$\hat{v}_t = \phi_\pi \hat{\pi}_t.$$

The fiscal authority adjusts lump-sum taxes according to the rule

$$\hat{\tau}_t = \phi_b \hat{b}_t^m.$$

Market clearing requires

$$\int_0^1 \hat{c}_t(i) di = \hat{c}_t = \hat{y}_t \text{ and } \int_0^1 \hat{b}_t^m(i) di = \hat{b}_t^m.$$

The model is completed with a description of beliefs, which is deferred until after results under rational expectations are discussed.

³⁶Despite Ricardian Equivalence not being a general property of models with learning dynamics, the proposition does hold in several special cases of interest. When debt is in zero supply so that $\delta = 0$ then the non-Ricardian component of consumption demand is absent to a first-order approximation. Similarly, there will be no wealth effects on consumption demand if households hold certain beliefs that government debt will be retired by appropriate current and future tax policy. As noted by Evans, Honkapohja, and Mitra (2012), which examines the conditions for Ricardian Equivalence to hold in under both transition dynamics and convergence, beliefs must also satisfy certain conditions. Subsequent discussion will not impose these conditions. Further empirical work understanding fiscal beliefs would greatly assist evaluating the effects of fiscal policy in models of learning.

7.3 The role of fiscal policy: Rational Expectations

The properties of the model under rational expectations are well understood. Leeper (1991) demonstrates two configurations of monetary and fiscal policy are consistent with a unique bounded rational expectations equilibrium in this class of model. Either monetary policy is active and fiscal policy is passive such that

$$1 < \phi_\tau < \frac{1 + \beta}{1 - \beta} \text{ and } \phi_\pi > 1$$

with inflation dynamics determined as $\hat{\pi}_t = \phi_0 \hat{y}_t$ for all t ; or monetary policy is passive and fiscal policy is active such that

$$0 \leq \phi_\pi < 1 \text{ and } 0 \leq \phi_\tau < 1 \text{ or } \phi_\tau > \frac{1 + \beta}{1 - \beta}$$

with inflation dynamics determined as $\hat{\pi}_t = \phi_1 \hat{b}_t + \phi_2 \hat{y}_t$.

The first configuration of policy generates a Ricardian Equilibrium in the sense that debt has no monetary consequences. Here the Taylor principle holds and is the active arm of stabilization policy. In contrast, the second configuration of policy engenders a non-Ricardian equilibrium: debt has monetary consequences. This is the so-called fiscal theory of the price level. Monetary policy is passive, adjusted to ensure intertemporal solvency of the government accounts, while fiscal policy stabilizes inflation. These results also hold in the benchmark New Keynesian model. Due to space constraints subsequent discussion under learning gives focus to the conventional assignment of policy. However, there is a growing body of evidence that the fiscal theory of the price level better characterizes certain episodes of US monetary history. Evans and Honkapohja (2007) and Eusepi and Preston (2011b) discuss stability of such equilibria under learning.

7.4 The role of fiscal policy: Learning Dynamics

Assume agents have the general forecasting model of the form (25):

$$z_t = \omega_{t-1} + \Phi z_{t-1} + e_t \tag{51}$$

where $\omega_t = (\omega_t^\pi \ \omega_t^\tau)'$, $z_t = (\pi_t \ \tau_t)'$ and e_t is the noise term. Noting the minimum-state-variable rational expectations solution is defined by

$$\omega^* = \mathbf{0}_{2 \times 1}; \ \Phi^* = \begin{bmatrix} 0 & 0 \\ 0 & \lambda_b \end{bmatrix}$$

make the simplifying assumption that agents understand $\Phi = \Phi^*$ so that they only face uncertainty about the intercepts ω_t .³⁷ Agents use the following recursive algorithm to update their estimates, $\hat{\omega}_t$, of ω_t

$$\hat{\omega}_t = \hat{\omega}_{t-1} + g_t t^{-1} \epsilon_t \tag{52}$$

³⁷Recall that under rational expectations government debt has no effects on inflation under this Ricardian equilibrium.

where

$$\epsilon_t = z_t - (\hat{\omega}_{t-1} + \Phi^* z_{t-1})$$

is the prediction error. Evaluating expectations in the consumption decision rule and the government flow budget constraint permits writing the dynamic behavior of the economy as

$$\hat{\pi}_t = -T_{\pi\pi}\hat{\omega}_{t-1}^\pi - \frac{\phi_\pi^{-1}\delta\sigma\beta}{\phi_b(1-\beta)}\hat{\omega}_{t-1}^\tau - \frac{\sigma}{\phi_\pi}\hat{y}_t \quad (53)$$

$$\hat{\tau}_{t+1} = \frac{(1-\rho)\rho\beta}{1-\rho\beta}\phi_b\phi_\pi\hat{\omega}_{t-1}^\pi + \lambda_b\hat{\tau}_t - \phi_b(\beta^{-1} - (1-\rho)\phi_\pi)\hat{\pi}_t, \quad (54)$$

where $T_{\pi\pi}$ is a function of model structural parameters. Relation (53) shows tax beliefs ω_{t-1}^τ affect the evolution of inflation, formally establishing the departure from Ricardian equivalence. At the same time, relation (54) shows the estimated inflation drift affects the path of taxes, through the price of long-term bonds — see (50).

Consider two simple cases. First, if the wealth effects are relatively small, $\delta\sigma \approx 0$, then tax beliefs do not affect the dynamics of inflation. Dynamics under learning are then the same as in absence of debt: Eusepi and Preston (2013) show the E-Stability conditions are determined by the ODE (30) in section 4.3 and the Taylor principle applies. Second, if the government bonds have a duration of one period or they are all consol bonds (ρ takes the values of 0 or 1), then inflation beliefs do not affect the evolution of taxes and debt. For these extreme values of average debt duration, the *quantity* of outstanding debt (and therefore taxes) does not respond to interest-rate expectations. In this case the evolution of tax beliefs is not self-referential and the Taylor principle holds.³⁸

In the general case where $\delta\sigma > 0$ and $\rho \in (0, 1)$ the condition for E-Stability is

$$\phi_\pi > \max \left(1, \left[(2-\beta) - \delta\sigma\beta \cdot \frac{(1-\rho)\rho\beta}{1-\rho\beta} \right]^{-1} \right).$$

Not only is the average level of indebtedness a constraint on monetary policy, but also the average duration of debt. As a result the Taylor principle does not hold.

While the discussion above might suggest that it is safe to proceed without explicit treatment of fiscal variables when government debt is either of very short or very long maturity, this is not necessarily the case. Suppose monetary policy is instead given by the simple rule

$$i_t = \phi_\pi \hat{E}_{t-1} \pi_t$$

and that households *understand* this to be the case.³⁹ Finally analyze expectational stability in the neighborhood of the flexible-price equilibrium — formally $\alpha \rightarrow 0$. Then, even in

³⁸For more discussion on this point see Eusepi and Preston (2013). This result for $\rho = 0$ was first established by Evans and Honkapohja (2007) in a New Keynesian model with one-period ahead expectations and later extended by Eusepi and Preston (2012) to the anticipated utility framework, serving to extend **Result 1a** and **1b** to an explicit treatment of fiscal policy.

³⁹Absent knowledge of the policy rule **Result 2** continues to apply.

the case of where government debt is only of one period duration, the requirements for expectations stability are

$$1 < \phi_\tau < \frac{1 + \beta}{1 - \beta} \text{ and } \phi_\pi > \frac{1}{1 - \beta\delta\sigma} .$$

The Taylor principle is, again, no longer sufficient for stability. Fiscal policy again constrains the class of monetary policy rule consistent with stability. The higher the average level of indebtedness, the more aggressive must be monetary policy to stabilize inflation. In the hypothetical case $\delta = \sigma = 1$ recovers the necessary condition for stability identified by Preston (2006) and discussed in section 5.1. In this case, however, the policy rule is fully understood by the public! This highlights the self-referentiality of interest-rate policy and interest-rate beliefs is a fundamental source of instability and more important when fiscal policy is less responsible.⁴⁰

Result 12. *In economies with high government debt of intermediate duration wealth effects from government liabilities can reduce the effectiveness of monetary policy in controlling inflation.*

Fiscal policy can frustrate the pursuit of price stability. Eusepi and Preston (2013) develop this insight to quantify the importance of sound fiscal policy for macroeconomic stability in the US. They show using counterfactual simulations that had fiscal policy been less responsible, reflected in levels, and average duration, of debt of the kind commonly observed after the financial crisis, the great moderation would not have been observed — the average volatility of inflation and output would have been comparable to the 1960s and 1970s. Sinha (2013) demonstrates that identified debt shocks from simulated data from a closely related model explain 30 percent of the rise in short-term yields and 10 percent of the rise in long-term yields identified using a vector auto-regression. This signals potential policy challenges ahead for many advanced economies.

7.5 The Anticipated Effects of Fiscal Policy

Building on the insights of Preston (2006), Evans, Honkapohja and Mitra (2009, 2013, 2014) analyze a range of experiments exploring the anticipated effects of fiscal policy in a real business cycle model. Common to each paper is the use of the anticipated utility approach and the fact that agents know the government follows a balanced budget rule, so there is no public debt. Evans, Honkapohja, and Mitra (2009) analyze the consequences of an announced one-time change in level of government purchases. Mitra, Evans, and Honkapohja (2013) extend this analysis to compare model dynamics under surprise and announced permanent changes in the level of government purchases. Finally, Mitra, Evans, and Honkapohja (2014) explore the magnitude of fiscal multipliers from a fully credible temporary expansion in government purchases. In all cases, the basic predictions of the real

⁴⁰Interestingly, in absence of central bank communication of the policy rule, the stance of fiscal policy is irrelevant. The instability stemming from policy expectation being disconnected from the actual policy rule dominates.

business cycle model are altered, sometimes in surprising fashion. Both the quantitative implications in more fully articulated models, and also the consequences for monetary policy design, are unexplored areas of research.

7.6 Zero Lower Bound and global dynamics

The results discussed in the previous sections ignore a key constraint on monetary policy: the zero lower bound (ZLB) on the short-term nominal rate. The ZLB severely limits the power of monetary policy even under perfect information. While it is impossible to do justice to this substantial literature, there are two basic concerns for the discussion here. First, Eggertsson and Woodford (2003) show that large and persistent shocks that drive the economy to the ZLB for a protracted period of time can generate large output losses driven by a deflationary spiral. Second, Benhabib, Schmitt-Grohe, and Uribe (2001) demonstrate that commitment to policy rules of the form (20), generally delivers local determinacy but global indeterminacy: among possible equilibria, there exist a continuum of equilibrium paths converging to a deflationary steady state. These observations represent an important challenge to monetary policy design.

Putting aside the matter of global indeterminacy, policy rules that respond to the price level, and specifically induce a response to the lagged price level, have desirable properties under rational expectations. Eggertsson and Woodford (2003) show a price-level targeting rule (14) comes very close to implementing the optimal policy taking into account the ZLB. Reifschneider and Williams (2000) also adduce evidence that a Taylor-type rule with a high degree of interest smoothing and a policy of price-level targeting are not equivalent in the presence of ZLB. A policy rule with interest-smoothing prescribes an excessively tight policy stance because of its dependence of past interest rates.

Policy rules that respond to the price level displayed robustness to model uncertainty under learning — recall section 5.3. How do they perform when subject to the constraint of the ZLB? Williams (2010) considers a simple reduced-form New Keynesian model with learning where agents have to form multi-period forecasts of the output gap, inflation and the nominal interest rate. Using a simulation exercise similar those described in Section 6.1, the study evaluates the performance of policy rules incorporating a response to the price-level of the form

$$i_t = \max \left[r_t^n + \phi_p (\ln p_t - \ln p_t^*) + \phi_{\Delta x} (x_t - x_{t-1}) + \phi_x x_t, 0 \right]. \quad (55)$$

where $\ln p_t^* = \ln p_{t-1}^* + \pi^*$. Agents' knowledge of the policy rule is key to its effectiveness. In absence of central bank communication, or, equivalently, in the face of lack of credibility on the part of the central bank, the economy performs quite poorly under learning. The economy is frequently at the ZLB (five times more frequently than under rational expectations), which comes at the cost of sharp reductions in output, rare under the assumption of rational expectations. The frequency of these episodes is reduced substantially if the public is assumed to understand the policy rule and use it to form policy-consistent forecasts of nominal interest rates. In addition, the effectiveness of policy can be further enhanced by allowing the policy rule to be more aggressive in response to deviations of the price level from

target than is required under rational expectations. Each of these properties are desirable in absence of the ZLB constraint.

Of course, policy rules of the form (55) are not immune from global indeterminacy under rational expectations. Focusing purely on the local stability of rational expectations equilibria, it would be tempting to dismiss the practical relevance of a liquidity trap steady state (and the paths converging to it) as it is generally an equilibrium unstable under learning — see Evans, Guse, and Honkapohja (2008) and Eusepi (2007). However, a careful analysis of the global dynamics of the economy under learning reveals that, despite being unstable under learning, the liquidity trap equilibrium has a strong influence on the global behavior of the economic system. To anticipate some results, large shocks can push the economy into a prolonged period of low or negative inflation and low levels of output, very close to the ‘liquidity trap’ observed in Japan in the past decade. The perils of deflationary traps have also been frequently in policymakers minds in the aftermath of the recent global financial crisis.⁴¹

A number of studies analyze the global dynamics under Taylor-type policy rules in the simple New Keynesian model, under both finite-horizon and infinite-horizon decision rules.⁴² Regardless of which nonlinear decision rules are employed, these papers focus on a deterministic set up where agents believe the equilibrium is a possible changing noisy steady state, the object about which they learn. The economic system is described by the following true data-generating process for output, inflation and the nominal interest rate

$$z_t = \mathbb{H}(\omega_{t-1})$$

and the constant-gain rule

$$\omega_t = \omega_{t-1} + \bar{g} (\mathbb{G}(\mathbb{H}(\omega_{t-1})) - \omega_{t-1})$$

where ω_t is a vector including the estimated steady-state values and $\mathbb{H}(\cdot)$, $\mathbb{G}(\mathbb{H}(\cdot))$ are nonlinear functions — details on the analysis of such systems can be found in Evans and Honkapohja 2001. Following a different approach, Bullard and Cho (2005) consider a linear economy described by (31) and (32) where private agents learn with a constant-gain algorithm and the policymaker follows a simple Taylor rule satisfying the Taylor principle. Their economy fluctuates most of the time around the locally stable inflation target steady-state equilibrium. However, certain sequences of shocks can trigger the economy to ‘escape’ towards a period of persistently low interest rates and deflation, observational equivalent to a liquidity trap, before reverting back to fluctuating around the equilibrium.⁴³

⁴¹See for example Bullard (2010).

⁴²Evans and Honkapohja (2005), Evans, Guse, and Honkapohja (2008), Evans and Honkapohja (2009), Eusepi (2010) and Honkapohja and Mitra (2014). These models assume Rotemberg pricing, which has the same first-order implications as Calvo pricing but it is more convenient for the nonlinear analysis of the model.

⁴³The mechanism is the same as described in Sargent (1999) and discussed in section 6.4. One key assumption to obtain escapes in the model is that the inflation target set by the central bank is in fact the inflation target estimated by the private sector in real time, so that the nominal anchor of the system can slowly drift in response to shocks.

These studies show the existence of a ‘corridor of stability’: small shocks to expectations deliver convergence back to the inflation target.⁴⁴ In contrast, sufficiently large shocks induce a deflationary spiral preventing convergence back to equilibrium. Even within the corridor of stability, sufficiently large shocks can lead to a prolonged period of low inflation and output before convergence occurs. **Figure 9** illustrates possible paths for output and inflation in a simple New Keynesian where the policy rule is the Taylor rule.⁴⁵ The figure replicates the phase diagram that emerges in the model of Eusepi (2011). Agents make decisions according to the Euler equation approach. However, because of information delays, in absence of central bank communication they have to forecast one-step-ahead the current interest rate as well as output and inflation. Output is expressed in percentage deviations from its steady-state value (at the inflation target steady state), while inflation is expressed in annualized percentage terms. Models without informational delays or where decision rules imply forecasts over an infinite horizon show similar qualitative behavior of output and inflation — see, for example, Evans, Guse, and Honkapohja (2008), Evans and Honkapohja (2010) and Benhabib, Evans, and Honkapohja (2014) which are discussed below.

The steady state corresponding to the inflation target is a sink (implying local stability under learning) while the liquidity trap steady state is a saddle (unstable under learning). Interestingly the stable (dashed line) and unstable (solid line) manifolds associated to the liquidity trap steady-state ‘wrap’ the inflation target steady state, defining the corridor of stability in the economy. This corridor is better understood by considering three different initial conditions for inflation and output. If the economy suffers a small shock (point A), then, by the local properties induced by the Taylor principle, the policy rule induces convergence back to the steady state. A shock that is sufficiently large, but within the boundaries of the dashed line (point B), leads to a period of deflation, as the economy is attracted by the liquidity trap equilibrium. As the economy gets further away from the inflation target equilibrium, monetary policy becomes less effective because the policy rule violates the Taylor principle near the liquidity trap equilibrium. However, the liquidity trap equilibrium is unstable and the economy slowly reverts back to its steady state. What are the forces behind this recovery? After a prolonged period of deflation and slow output growth, the low interest rate ultimately stimulates spending and the economy reverts back towards the inflation target equilibrium.⁴⁶ Finally, a sufficiently large shock (point C) triggers a deflationary spiral with no return to equilibrium. In this case, the deflationary impetus in expectations is too strong to be offset by stimulative monetary policy, and the economy would eventually violate feasibility constraints. Along these deflationary paths either the private sector or policymakers would change their behavior. The most likely scenario involves a change in policy. However, when considering large shocks, the assumption of a time-invariant policy rule and a time-invariant learning algorithm becomes less realistic.

Result 13. *Under Taylor rules which satisfy locally the Taylor principle, large shocks can drive expectations and the economy in a prolonged period of deflation and low*

⁴⁴The term ‘corridor of stability’ dates back to Leijonhufvud (1973), which discusses the stabilizing effects of market forces in response to shocks.

⁴⁵Again, the Taylor rule satisfies the Taylor principle at the inflation target equilibrium.

⁴⁶Notice that the economy overshoots its steady state before convergence.

output.

As discussed in section 7.1, agents' knowledge of the policy rule has important implications for policy effectiveness. **Figure 10** shows the phase diagram of the model where agents understand the policy rule and therefore only have to forecast inflation and output gap. The stability corridor enlarges considerably under a regime of policy communication. All initial conditions lead to convergence to the inflation target. Honkapohja and Mitra (2014) discuss a similar result in the case of a policy rule that responds to the price level (or nominal output), such as (55). They show that without any guidance about the policy rule, the corridor of stability under a policy rule responding to the price level is considerably narrower than a rule responding to the inflation rate. Furthermore, the inflation target steady state is less robust to higher constant gains under price-level rules than under inflation-based policy rules. Conversely, Honkapohja and Mitra (2014) show that with some guidance about the policy regime the stability properties improve substantially. In particular, suppose agents forecast inflation using some information about the target path for the price level, so that

$$\hat{E}_{t-1}\pi_{t+1} = \left(\hat{E}_{t-1}\tilde{P}_{t+1} \times \pi^* \right) / \tilde{P}_{t-1}$$

where \tilde{P}_t measure the gap between the current price level and the target p_t/p_t^* . In turn \tilde{P}_t is estimated using an updating rule of the form (26).⁴⁷ Guidance induces a corridor of stability substantially wider than under a conventional Taylor rule.⁴⁸

Result 14. *Lack of communication increases the likelihood of entering a deflationary path. The stability corridor is smaller under a policy rule responding to the price level.*

Effective communication of policy does not eliminate the perils of Taylor rules. Although weaker, the influence of the liquidity trap equilibrium persists. For example, initial conditions in C continue to engender a period of persistent disinflation and low output. Section 7.2 discussed the interactions of monetary policy and government debt under learning. In the ZLB results discussed so far government liabilities play no direct role because either: i) household and government intertemporal budget constraints are not taken into account; or ii) agents in the economy fully understand that fiscal policy is Ricardian. Benhabib, Evans, and Honkapohja (2014) investigate whether wealth effects from government liabilities can prevent a deflationary outcome via the Pigou effect: falling prices increase perceived wealth and aggregate demand, boosting the economy out of the liquidity trap. Numerical examples are given where the wealth effects are strong enough to ensure convergence. An initial state of the economy that would lead to a deflationary path in absence of wealth effects on aggregate demand (for example, point C in **figure 9**) is in fact consistent with convergence to the inflation target steady state once wealth effects on aggregate demand are considered.⁴⁹

⁴⁷Notice that the private sector faces information delays when forming expectations.

⁴⁸However, even with some guidance about the policy rule, (55) is shown to induce local instability for relatively small values of the constant gain.

⁴⁹The result depends on fiscal policy being passive in the sense of Leeper (1991).

Results 15. *Under a passive fiscal regime, perceived wealth effects from government liabilities can significantly enlarge the stability corridor.*

Pigou effects, however, produce convergence involving overshooting of output and inflation, so that alternative fiscal and monetary measures might be required to further stabilize the economy. Evans and Honkapohja (2010) evaluate the effectiveness of a temporary switch from a standard Taylor rule to a near-zero constant interest rate when inflation crosses a threshold (above that implied by the liquidity trap steady state). Independently of the duration of the policy, the stability corridor of the economy is not significantly altered, even if the policy is fully understood by the public. However, coupling the temporary interest-rate peg with a commitment to increase government spending to whatever level needed to keep inflation from falling below the threshold can eliminate the influence of the liquidity trap equilibrium. This kind of policy, however, delivers a fairly volatile economic environment in the transition to the inflation target steady-state. The analysis also begs the question of the size of fiscal expansion that would be required to keep inflation from falling, in response to a negative shock similar to the recent financial crisis. Benhabib, Evans, and Honkapohja (2014) discuss the benefits of announcing a fiscal expansion (or, under certain conditions, a contraction) in response to a large negative shock to the economy. They show that provided the size and duration of the fiscal expansion is understood by the public, such policies can deliver stability in the presence of shocks that would drive the economy outside the stability corridor in absence of fiscal intervention. However designing such policies is difficult, as the required magnitude and duration depends on the size of the initial shock. They argue that the switching fiscal rules described above might be more effective.

Result 16. *A combination of expansionary fiscal and monetary policies that are well understood by the public can, if properly designed, eliminate deflationary equilibria.*

As for many topics discussed in this survey, a proper evaluation of this claim requires a considerably more quantitative and robustness analysis. Regardless, the results convey the general idea that when constrained by the ZLB, policy can steer expectations even in an environment where agents have imperfect information about the economic environment and update their view of the economy according to simple time-invariant updating algorithms. As in environments where the ZLB is not a constraint, inertial policy rules that are clearly communicated appear to have considerable merit.

8 Further directions

This survey reviews the basic principles of optimal policy in the New Keynesian model under imperfect information. The main challenge for further research is how are these principles modified in more realistic contexts. There are at least four dimensions where the literature could grow. Two dimensions are specific to the learning literature. Two others are common to the New Keynesian literature in general.

First, expectations formation depends on the choice of the gain sequence, g_t . In this survey, as in most of the underlying literature it reflects, we have taken the gain as an

exogenous parameter. However, this variable might well be an important choice variable for agents. The chosen gain could be a function of, among other factors, the policy regime in place and therefore subject to the Lucas critique — on this point see, for example, Evans and Ramey (2006). As such, it should be integral part of the policy optimization problem. A few papers in the literature treat the constant gain as a decision variable. In Evans and Honkapohja (1993) and Marcet and Nicolini (2003) the equilibrium gain is the gain that minimizes the forecast mean-square error of each individual agents: that is, no agent has an incentive to choose a different gain in equilibrium. Marcet and Nicolini (2003) discuss the emergence of hyperinflationary episodes in response to seigniorage needs, and show that a change in policy leads to a change in the equilibrium constant gain. It is therefore critical to evaluate the policies discussed above by letting the constant gain be an endogenous variable in the model. Finally, assuming either a constant gain or a decreasing gain is unnecessarily restrictive. A plausible learning algorithm could entail an endogenous switch between different gains, depending perhaps on the forecasting performance of the implied beliefs. Building on ideas first proposed by Brock and Hommes (1997), Marcet and Nicolini (2003), Evans, Honkapohja, Sargent, and Williams (2012) and Milani (2014) implement versions of such an algorithm.⁵⁰

The second dimension where the literature could and should expand is to abandon the assumption of homogeneous expectations. As documented by Branch (2004), Mankiw, Reis, and Wolfers (2004) and Andrade, Crump, Eusepi, and Moench (2013), professional forecasters disagree both in their short- and long-term forecasts of inflation, economic activity and the policy rate. In addition central bank forecasts are often not in agreement with the outlook of market participants. The efficacy of monetary policy might be compromised by heterogeneous expectations and might also introduce distributional considerations. A few papers have investigated the consequences of heterogeneous private beliefs for monetary policy at a theoretical level — Branch (2004), Branch and McGough (2009, 2010, 2011). Honkapohja and Mitra (2005) and Preston (2008) explore disagreement between private sector and central bank forecasts. In an interesting study, Assenza, Heemeijer, Hommes, and Massaro (2014) develop laboratory experiments designed to evaluate performance of Taylor-type rules in presence of expectational heterogeneity. More should be done to develop testable theoretical predictions that can be confronted with survey and other data on expectations.

Third, further quantitative assessment of learning for macroeconomic dynamics and policy design would be invaluable. There is a growing evidence that learning models can explain features of data that are deemed a puzzle when viewed through the lens of a rational expectations analysis. While most central banks use state of the art DSGE models of the kind proposed by Smets and Wouters (2007) for policy analysis, the large majority retains the assumption of rational expectations. More should be done to conduct policy evaluation in medium-scale New Keynesian models with learning. At the forefront of this effort are Milani (2004, 2008, 2011, 2012) and Sloboydan and Wouters (2012a, 2012b) which use state of the art Bayesian methods to estimate small- and medium-scale DSGE models. With the exception of Eusepi and Preston (2013), these models are evaluated under the Euler

⁵⁰See also Gaus (2014) and Kostyshyna (2012) for alternative time-varying gain algorithms.

equation approach, so that some of the aspects of the optimal policy problem discussed in this survey cannot be studied. Moreover, as in the case of forecast disagreement, more use should be done using survey-based forecasts to discipline the class of permitted learning algorithms employed in estimation — for some use of survey-data see, for example, Milani (2011), Eusepi and Preston (2011, 2013), Slobodyan and Wouters (2012b), Ormeno and Molnar (2013).

Lastly, the recent financial crises has stimulated efforts to introduce financial frictions and asset price dynamics in the baseline New Keynesian framework. It is easy to argue that such innovation could have important implications for the design of optimal monetary policy. These considerations are more compelling for models that incorporate learning, where asset prices, financial frictions and beliefs dynamics can deliver substantial variations from the rational expectations paradigm. Indeed, there has been a growing literature that attempts with a certain degree of success to explain asset prices with learning dynamics.⁵¹ One more challenge for the literature is to integrate these models in the standard New Keynesian model to study their implication for monetary policy.⁵²

9 Conclusions: Policy Design under Learning Dynamics

The main take from the survey is that the most of the main principles survive the introduction of imperfect information and learning but they get modified, in some cases substantially. Perhaps as one should expect, the art and science of monetary policy becomes more complex under imperfect knowledge, as learning can impose substantial limits to the effectiveness of monetary policy. Importantly central bank communication is shown to be one of the most important determinants of policy success, along with policy procedures that induce a dependence of current interest rates on the lagged level of prices. We then suggest re-writing the principles described in section 2 as follows

1. Optimal policy under learning is complicated by multiple intertemporal trade-offs that are absent under rational expectations. As a result, the Divine Coincidence does not generally hold.
2. In the neighborhood of rational expectations, optimal policy under learning is generally more aggressive towards inflation than under rational expectations. This is due both to the intertemporal trade-offs induced by the expectations formation mechanism and because of non-Ricardian wealth effects generated by the dynamics of government debt. When beliefs are sufficiently far from rational expectations equilibrium, optimal

⁵¹The long list of contributions includes, Adam, Beutel and Marcet (2013), Adam, Marcet, and Nicolini (2012), Carceles-Poveda and Giannitsarou (2007), Benhabib and Dave (2014), Branch and Evans (2010, 2011), Sinha (2014).

⁵²Examples of recent studies that consider from the interactions between monetary policy and asset pricing under learning. Airaudo, Nisticò, and Zanna (2014), Winkler (2015), Gelain, Lansing, and Mendicino (2013), Pintus and Suda (2014), Gelain, Lansing, and Natvik (2015), Dewachter, Iania, and Lyrio (2011), Milani (2008), Caputo, Medina, and Soto (2011).

policy is less aggressive responses to changing economic conditions than under rational expectations.

3. Optimal policy under learning induces history dependence which improves the short-run stabilization trade-off between inflation and the output gap. Such history dependence is however different in nature to the optimal commitment solution and depends on agents' learning rule.
4. Policy rules that respond to the price level or incorporate interest smoothing have good stabilization properties. When subject to the zero lower bound constraint the efficacy of policy depends on effective and credible communication of the policy rule.
5. Simple policy rules that incorporate some degree of price level targeting or a sufficient degree of interest smoothing show a high degree of robustness to model uncertainty — either reflecting mis-measured variables (natural rates) or different assumptions about the expectations formation mechanism of private agents.

The main conclusion: the body of evidence supports the adoption of some form of price level targeting. Provided such mechanism is credible, well communicated and understood by the public, policy rules consistent with PLT provide the desired aggressive stance toward inflation, and also history dependence with its benefits towards improving intertemporal trade-offs. Policy rules that incorporate some form of PLT also insure a better performance once the ZLB is taken into account by reducing the probability that the economy hits the ZLB, and better management of expectations when this constraint is binding. In other words such rules enlarge the corridor of stability of the economy, reducing the influence of the zero lower bound. Importantly, failure to properly communicate these rules imply poor performance.⁵³ An important lesson from this result is that a switch to some form of price level targeting is most desirable under economic circumstances when the policymaker has all the tools to establish credibility.⁵⁴ For example, switching to a PLT regime while a the zero lower bound might not have the desired impact on expectations and therefore might not deliver a faster exit to positive interest rates.

However, more needs to be done in the area of policy design, even in the simplest New-Keynesian models. In particular, what is missing is a proper quantitative evaluation of different policy rules incorporating either price-level targeting or interest smoothing and how they compare with the optimal policy under learning. Also, given that the ability to communicate depends on the form of the policy rule, it is still a rather open question how to directly incorporate policy communication in the design of optimal policies.

⁵³This resonates with Woodford (2010), which shows that price-level targeting is robust to uncertainty about expectation formation. Here, the deviation from rational expectation is modelled following the robust control literature.

⁵⁴On the costs of introducing price level targeting under imperfect credibiility see Krystov et al. (2008), Cateau et al (2009).

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LIST OF FIGURES

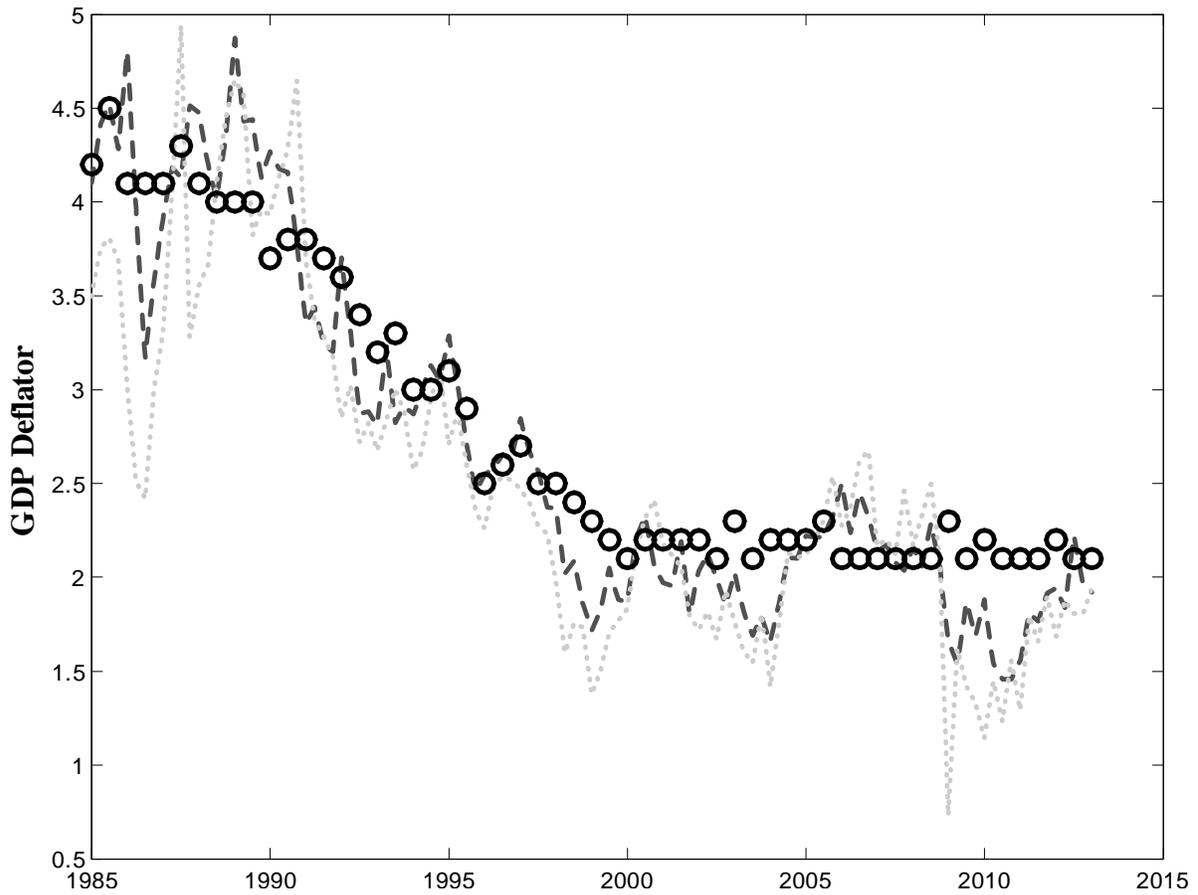


Figure 1: The figure shows the evolution of survey forecast for the GDP deflator. In particular, the light grey dotted (dark grey dashed) line shows 1-quarter (4-quarters) ahead consensus forecast from the Survey of Professional Forecasters. The black line with circles shows the 5-10 years ahead consensus forecast from Blue Chip Financial Forecasts survey.

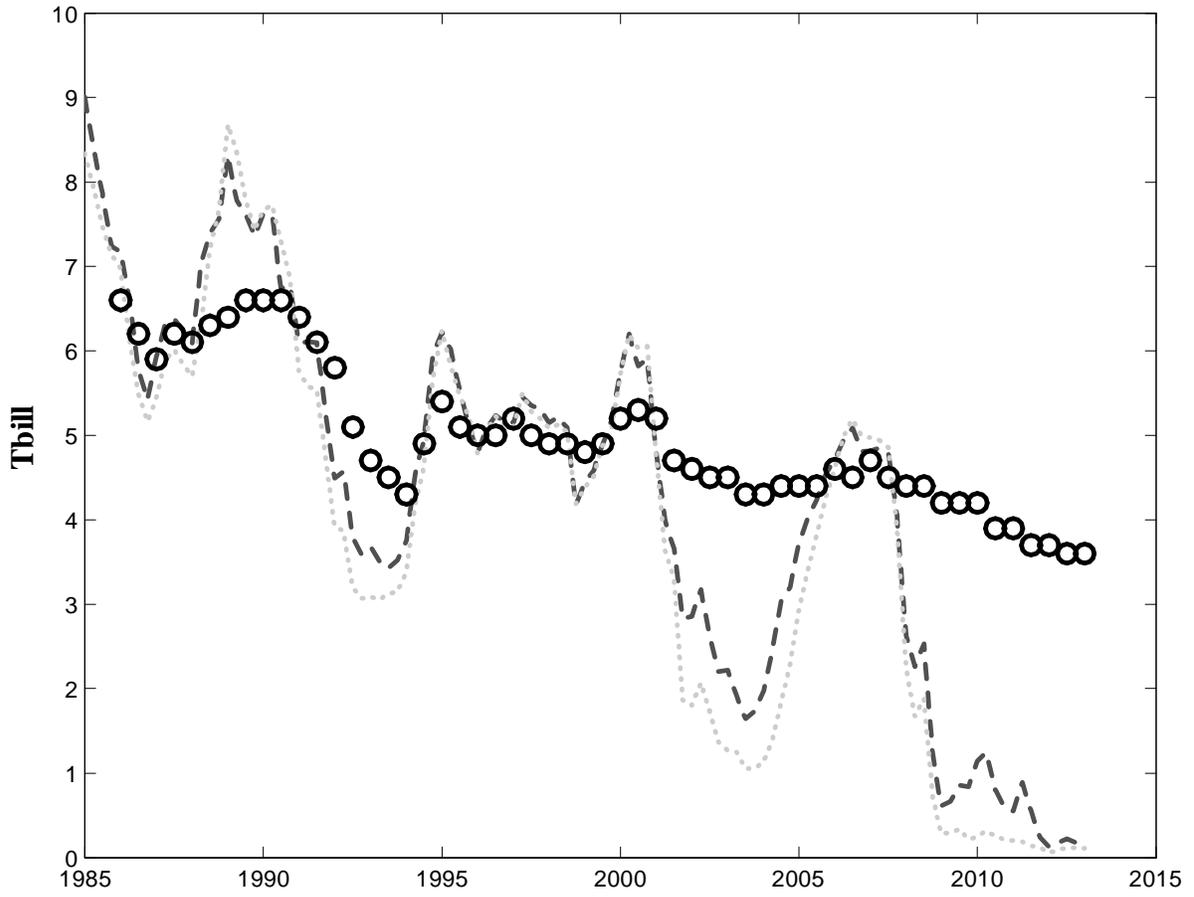


Figure 2: The figure shows the evolution of survey forecast for the 3-months T-bill interest rate. In particular, the light grey dotted (dark grey dashed) line shows 1-quarter (4-quarters) ahead consensus forecast from the Survey of Professional Forecasters. The black line with circles shows the 5-10 years ahead consensus forecast from Blue Chip Financial Forecasts survey.

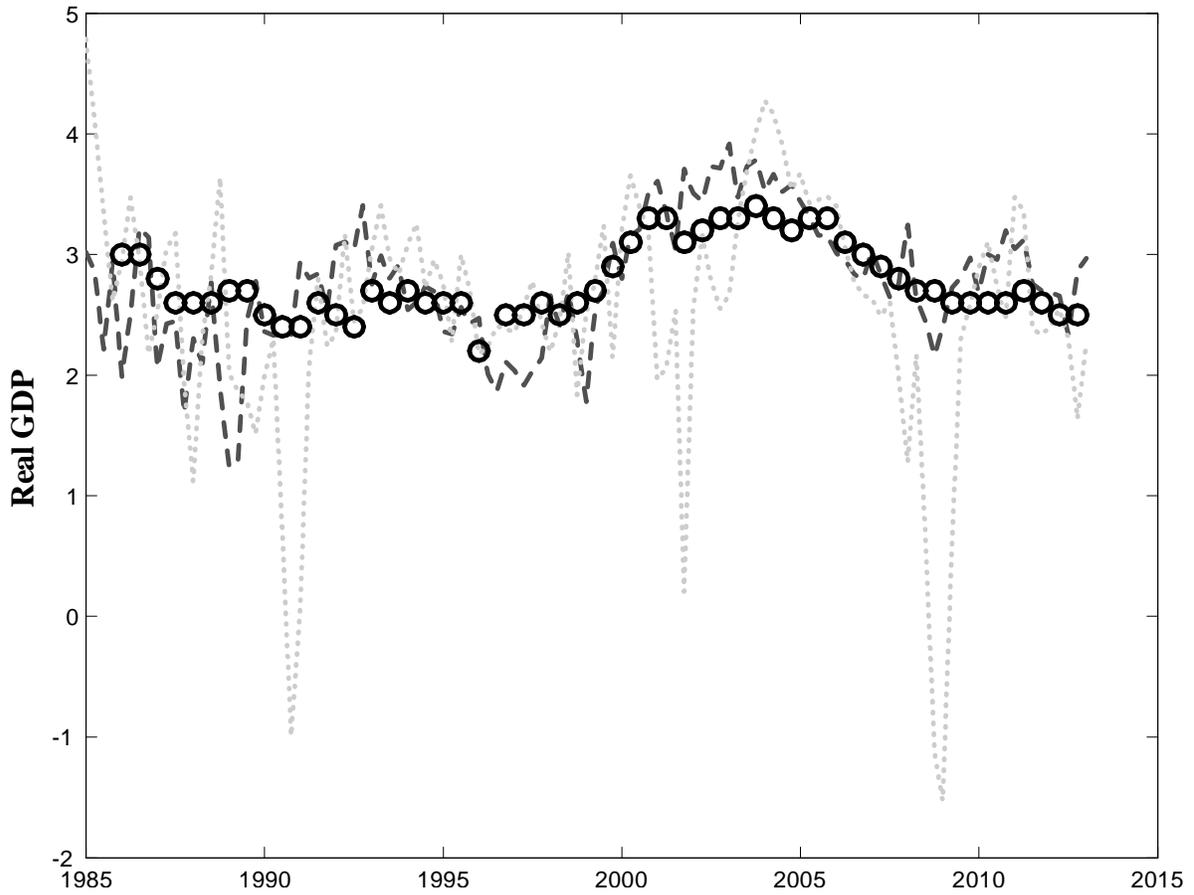


Figure 3: The figure shows the evolution of survey forecast for the real GDP growth. In particular, the light grey dotted (dark grey dashed) line shows 1-quarter (4-quarters) ahead consensus forecast from the Survey of Professional Forecasters. The black line with circles shows the 5-10 years ahead consensus forecast from Blue Chip Financial Forecasts survey.

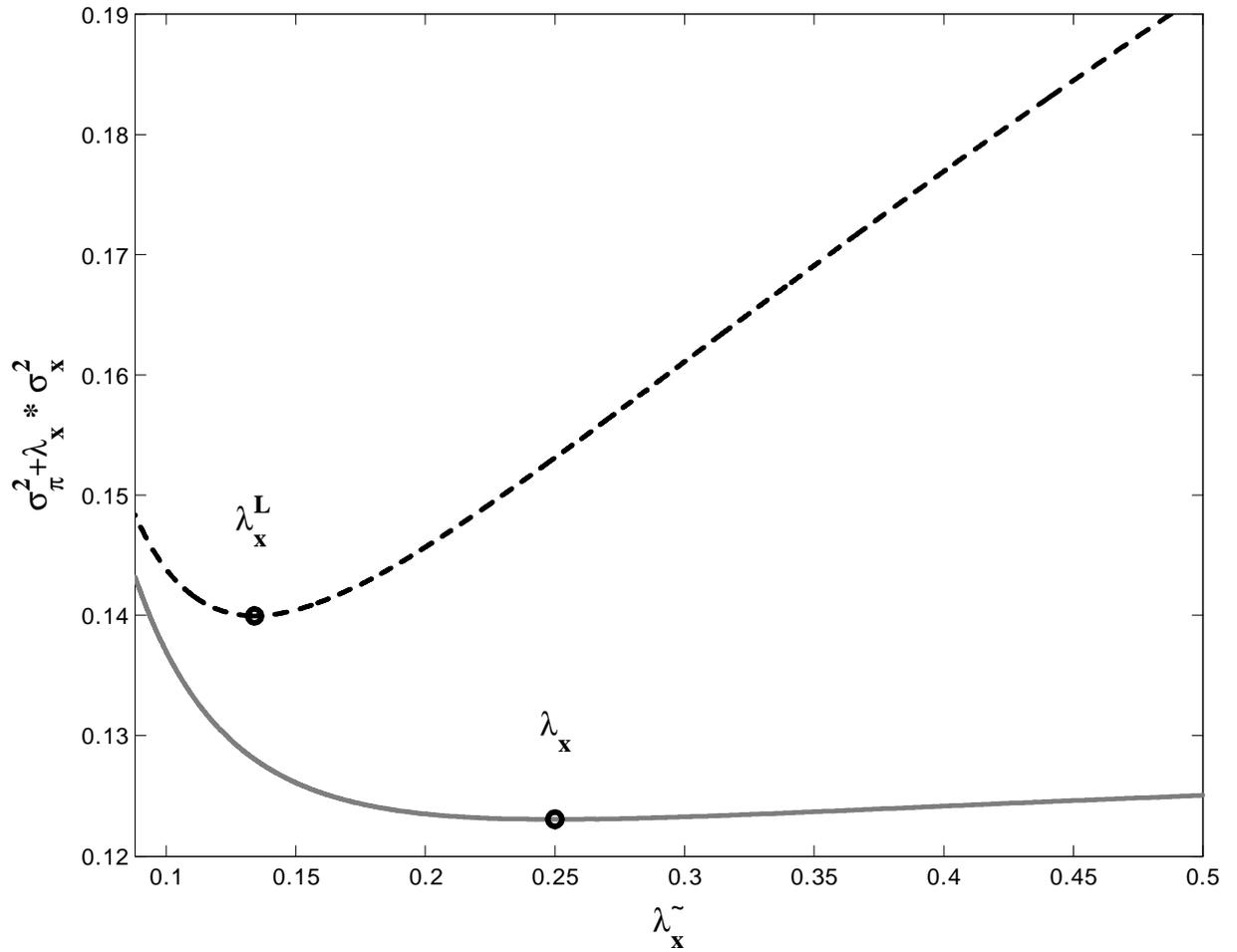


Figure 4: The figure shows the (weighted) volatilities out inflation and output gap associated to alternative targeting rules. The black dashed line corresponds to targeting the model with learning, while the grey solid line show pertains the model under rational expectations.

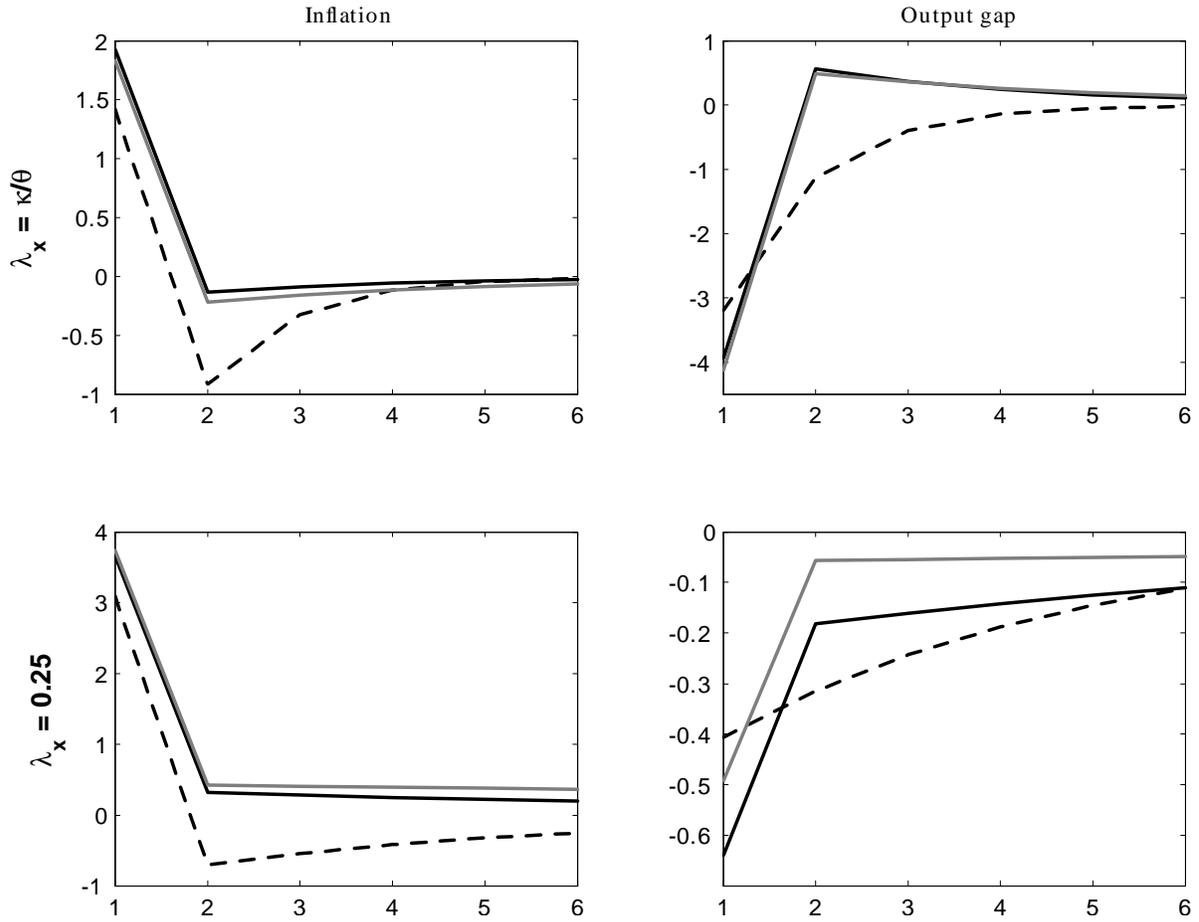


Figure 5: The figure shows the response to a 1-standard deviation positive cost push shock. In all panels, the dashed black line corresponds to optimal commitment, the solid black line shows optimal policy under learning and the solid grey line depict the response of the economy under the targeting rule discussed in section 6.1.

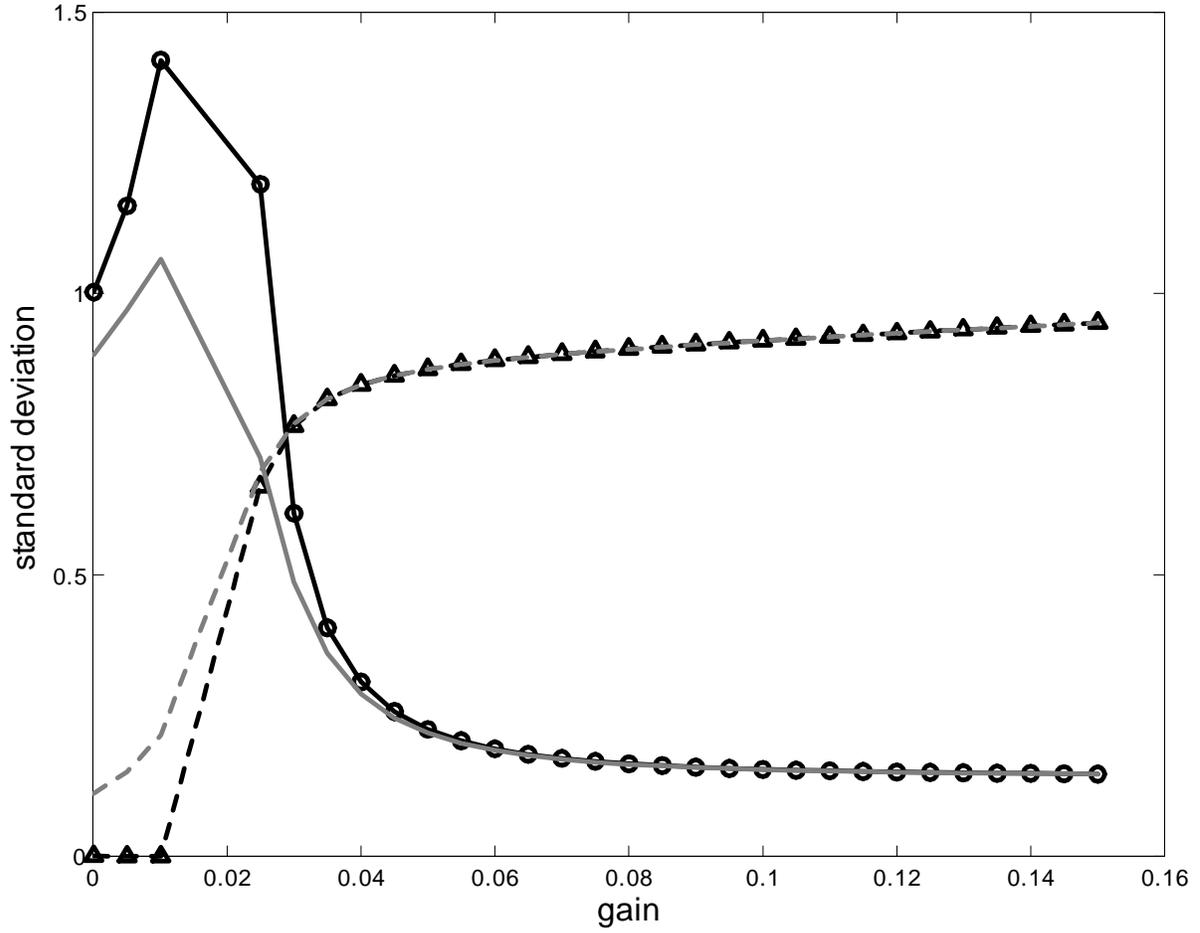


Figure 6: The figure shows the volatility of output and interest rate as a function of the constant gain \bar{g} . The black lines display the volatility output gap (triangles) and interest rate (circles) in the case where the central bank associates no cost to interest rate volatility. The grey dashed (solid) line show the volatility of output (interest rate) when the policymaker cares about interest rate volatility.

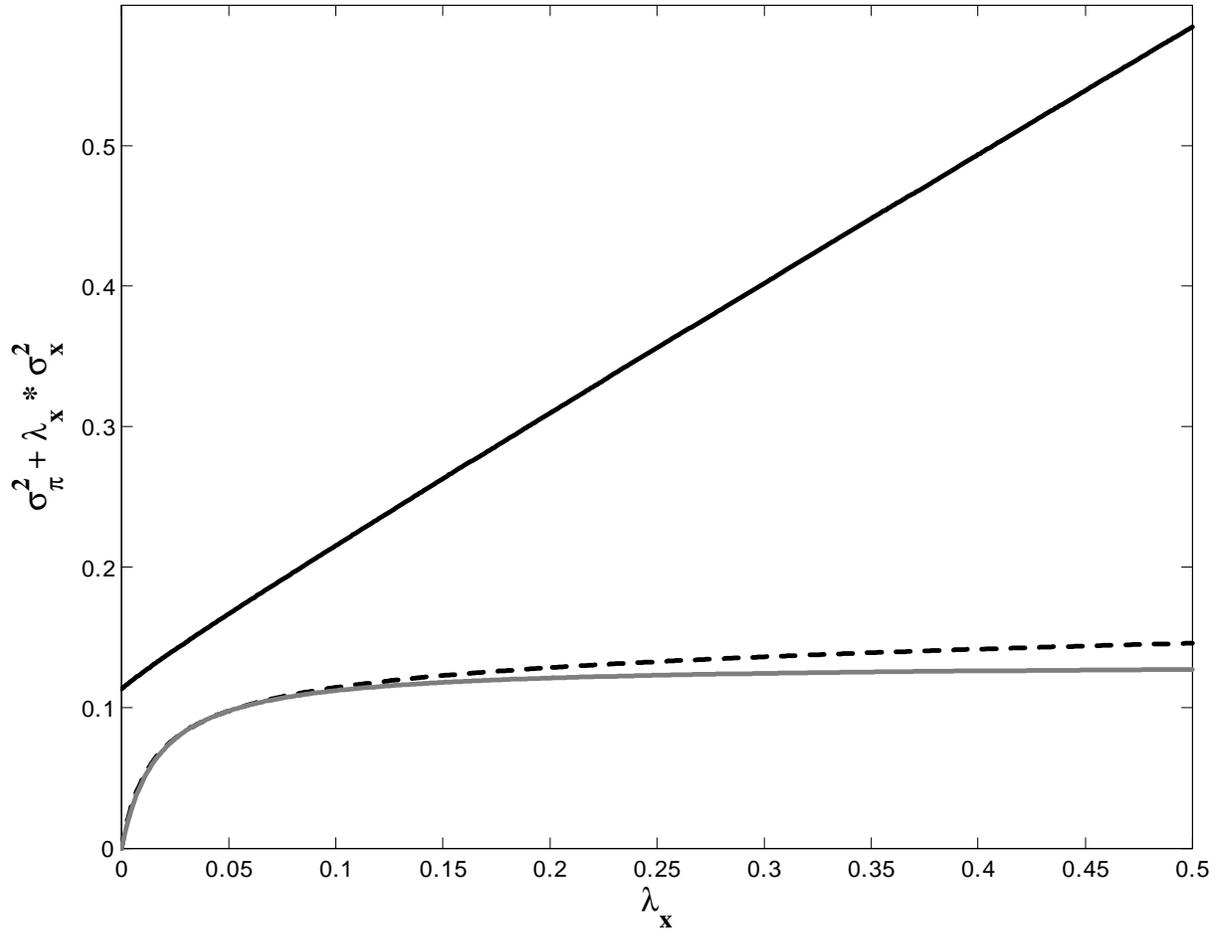


Figure 7: The figure shows the (weighted) volatilities of inflation and output gap associated to alternative policies as a function of λ_x . In particular, the black solid line shows the volatility under the optimal policy under learning. The dashed grey line shows the volatility for optimal policy under learning when the central bank is in full control of aggregate demand. Finally the solid grey line shows optimal discretion.

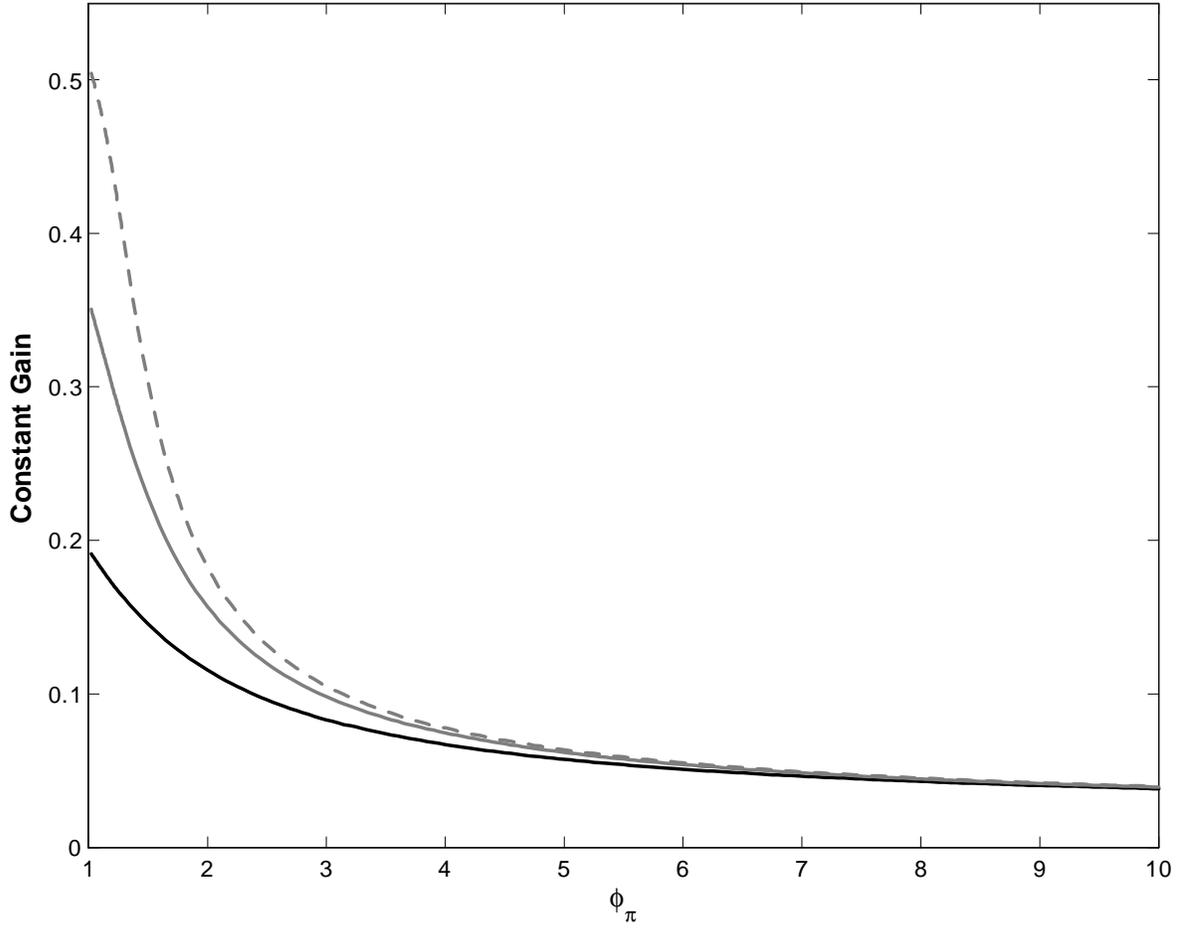


Figure 8: The figure shows stability frontiers corresponding to alternative Taylor rules. In particular (\bar{g}, ϕ_π) pairs above the frontier correspond to locally unstable equilibria under constant gain learning. The black solid line corresponds to the standard Taylor specification with $\phi_x^* = 0.5/4$. The solid (dashed) grey line corresponds to $\phi_x = \phi_x^*/2$ ($\phi_x = \phi_x^*/3$).

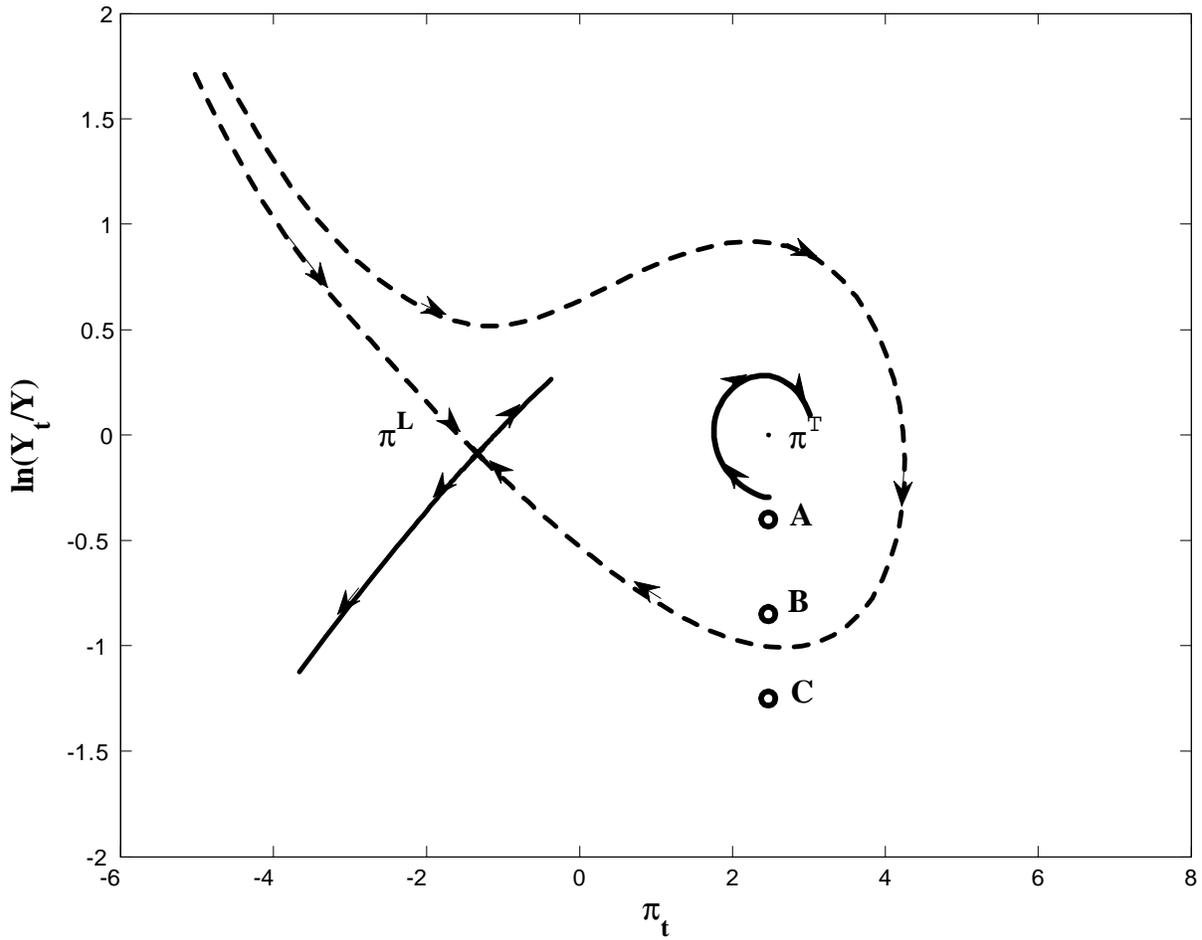


Figure 9: The figure shows the phase diagram for inflation and the output gap in the model where the monetary policy rule is not communicated to market participants.

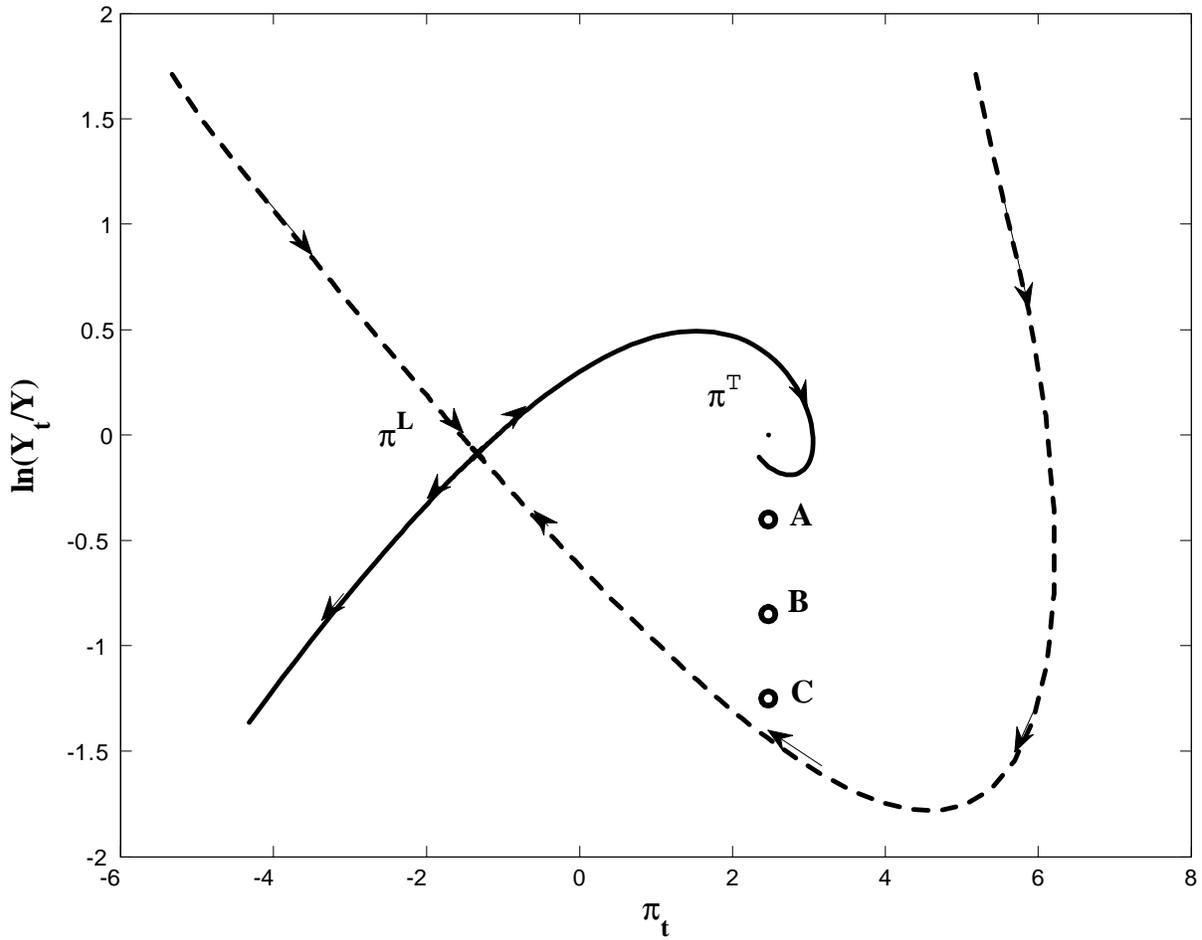


Figure 10: The figure shows the phase diagram for inflation and the output gap in the model where agents know the monetary policy rule.