

MA'20
EB 12

Algoritmos de Estimación de Distribuciones
para la Selección Simultánea de Instancias y
Atributos

MAEB 2012 – Albacete

8-10 Febrero

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Resumen

- 1. Pre-procesamiento de bases de datos**
- 2. IFS - Propuestas**
- 3. Experimentos**
- 4. Conclusiones y Trabajo Futuro**

1. Pre-procesamiento de bases de datos

- Las técnicas de pre-procesamiento mejoran la calidad de los datos con los que se pretende construir modelos predictivos:

| Instance ID | X_1 | X_2 | ... | X_n | C |
|-------------|----------|----------|-----|----------|-------|
| 1 | x_{11} | x_{12} | ... | x_{1n} | c_1 |
| 2 | x_{21} | x_{22} | ... | x_{2n} | c_2 |
| 3 | x_{31} | x_{32} | ... | x_{3n} | c_3 |
| 4 | x_{41} | x_{42} | ... | x_{4n} | c_4 |
| ... | ... | ... | ... | ... | ... |
| N | x_{N1} | x_{N2} | ... | x_{Nn} | c_N |

- Cuando n es del orden de miles, hablamos de bases de datos de **alta dimensionalidad**. Si N es muy grande, bases de datos masivas.
- Otro problema común: *imbalanceado*.

1. Pre-procesamiento de bases de datos

- Las técnicas de pre-procesamiento mejoran la calidad de los datos con los que se pretende construir modelos predictivos:

Selección de atributos(FS)

| Instance ID | X_1 | X_2 | ... | X_n | C |
|-------------|----------|----------|-----|----------|-------|
| 1 | x_{11} | x_{12} | ... | x_{1n} | c_1 |
| 2 | x_{21} | x_{22} | ... | x_{2n} | c_2 |
| 3 | x_{31} | x_{32} | ... | x_{3n} | c_3 |
| 4 | x_{41} | x_{42} | ... | x_{4n} | c_4 |
| ... | ... | ... | ... | ... | ... |
| N | x_{N1} | x_{N2} | ... | x_{Nn} | c_N |

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1. Pre-procesamiento de bases de datos

- Las técnicas de pre-procesamiento mejoran la calidad de los datos con los que se pretende construir modelos predictivos:

Selección de atributos(FS)

Construcción de Atributos

| Instance ID | X_1 | X_2 | ... | X_n | C | X_{n+1} |
|-------------|----------|----------|-----|----------|-------|-----------|
| 1 | x_{11} | x_{12} | ... | x_{1n} | c_1 | ... |
| 2 | x_{21} | x_{22} | ... | x_{2n} | c_2 | ... |
| 3 | x_{31} | x_{32} | ... | x_{3n} | c_3 | ... |
| 4 | x_{41} | x_{42} | ... | x_{4n} | c_4 | ... |
| ... | ... | ... | ... | ... | ... | ... |
| N | x_{N1} | x_{N2} | ... | x_{Nn} | c_N | ... |

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1. Pre-procesamiento de bases de datos

- Las técnicas de pre-procesamiento mejoran la calidad de los datos con los que se pretende construir modelos predictivos:

Selección de atributos(FS)

Construcción de Atributos

Muestrear instancias

| Instance ID | X_1 | X_2 | ... | X_n | C | X_{n+1} |
|-------------|----------|----------|-----|----------|-------|-----------|
| 1 | x_{11} | x_{12} | ... | x_{1n} | c_1 | ... |
| 2 | x_{21} | x_{22} | ... | x_{2n} | c_2 | ... |
| 3 | x_{31} | x_{32} | ... | x_{3n} | c_3 | ... |
| 4 | x_{41} | x_{42} | ... | x_{4n} | c_4 | ... |
| ... | ... | ... | ... | ... | ... | ... |
| N | x_{N1} | x_{N2} | ... | x_{Nn} | c_N | ... |
| N+1 | ... | ... | ... | ... | ... | ... |

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1. Pre-procesamiento de bases de datos

- Las técnicas de pre-procesamiento mejoran la calidad de los datos con los que se pretende construir modelos predictivos:

Selección de atributos (FS)
Muestrear instancias

Construcción de Atributos
Seleccionar Instancias (IS)

| Instance ID | X_1 | X_2 | ... | X_n | C | X_{n+1} |
|-------------|----------|----------|-----|----------|-------|-----------|
| 1 | x_{11} | x_{12} | ... | x_{1n} | c_1 | ... |
| 2 | x_{21} | x_{22} | ... | x_{2n} | c_2 | ... |
| 3 | x_{31} | x_{32} | ... | x_{3n} | c_3 | ... |
| 4 | x_{41} | x_{42} | ... | x_{4n} | c_4 | ... |
| ... | ... | ... | ... | ... | ... | ... |
| N | x_{N1} | x_{N2} | ... | x_{Nn} | c_N | ... |
| N+1 | ... | ... | ... | ... | ... | ... |

- Cuando n es del orden de miles, hablamos de bases de datos de **alta dimensionalidad**. Si N es muy grande, bases de datos masivas.
- Otro problema común: *imbalanceado*.

1. Pre-procesamiento de bases de datos

- **FS (Selección de atributos):**
 - Reduce la anchura de la base de datos: ligereza, mejores modelos, más entendibles.
 - Las métricas utilizadas para seleccionar un atributo suelen calcularse **a partir de las instancias disponibles.**
- **IS (Selección de instancias):**
 - Reduce la longitud de la base de datos: ligereza, clusters mejor definidos, gran mejora para clasificadores perezosos.
 - Las métricas utilizadas para seleccionar una instancia suelen calcularse **a partir de los atributos disponibles.**

FS influye en IS

IS influye en FS

¿Cuál realizar antes? → Selección Simultánea (IFS)

2. IFS

- **IFS-CHC**: algoritmo evolutivo adaptativo CHC.
- **IGA**: algoritmo genético inteligente con operador de cruce ortogonal.
- **HGA**: algoritmo genético híbrido: técnicas de búsqueda local+AG.
- Una de las propuestas más recientes y exitosas es **IFS-CoCo**:
 - Co-evolución genética de 3 poblaciones
 - 1 población para FS
 - 1 población para IS
 - 1 población para IFS
 - Resultados muy buenos
 - Wrapper: caro computacionalmente

EDAs

- Algoritmos evolutivos que trabajan sobre conjuntos de poblaciones de soluciones candidatas.

Algoritmo 1 Algoritmo de estimación de distribuciones (EDA).

```
1   $D_0 \leftarrow$  Generar la población inicial ( $m$  individuos)
2  Evaluar la población  $D_0$ 
3   $l = 1$ 
4  Repeat until condición de parada
5      $D_{l-1}^{Se} \leftarrow$  Seleccionar  $s \leq m$  individuos de  $D_{l-1}$ 
6     Estimar un modelo probabilístico  $\mathcal{M}$  a partir de
        $D_{l-1}^{Se}$ 
7      $D_{l-1}^m \leftarrow$  Muestrear  $m$  individuos a partir de  $\mathcal{M}$ 
8     Evaluar  $D_{l-1}^m$ 
9      $D_l \leftarrow$  Seleccionar  $m$  individuos de  $D_{l-1} \cup D_{l-1}^m$ 
10     $l = l + 1$ 
11  end
```

EDAs

- **Ventajas** (frente a los AGs):
 - Menor número de parámetros a ajustar.
 - Mayor expresividad y transparencia del modelo probabilístico que guía el proceso de búsqueda.
- Existen multitud de EDAs:
 - Sin dependencias: **UMDA**.
 - Distribución de probabilidad conjunta a partir de las distribuciones univariadas independientes.
 - Dependencias bivariadas.
 - Dependencias múltiples.

2. IFS

- Proponemos 2 nuevos métodos para realizar IFS, ambos basados en evolución de EDAs (UMDA), y con evaluación principalmente filter:
 - **IFS-EDAig**
 - **IFS-EDAcfs**
 - En ambas búsquedas, las poblaciones se inicializan dando la probabilidad a cada instancia inversamente proporcional a la cardinalidad de su clase, para intentar sesgar el resultado a una base de datos balanceada → IFS + balanceado.

2. IFS

- IFS-EDAig:

- Fase filter (UMDA): repetida n veces
 - Un individuo representa explícitamente las instancias seleccionadas
 - Los atributos seleccionados se representan implícitamente con un ranking de los k mejores atributos por IG
 - La suma de estos k atributos es la bondad de un individuo
- Fase wrapper: comparación del mejor individuo de cada $UMDA_k$

Algoritmo IFS-EDAig.

In Base de datos \mathcal{T} , n° atributos n , n° instancias l , tamaño población m , n° generaciones x , tamaño población aprendizaje s , clasificador \mathcal{C}

Out Base de datos reducida $\mathcal{R}_{\mathcal{T}}$

```
1 for  $k \leftarrow 1$  to  $n$ 
  //fase filter
2 mejorInd  $\leftarrow$   $UMDA_{ig}(k, l, m, s, x, \mathcal{T})$   $\rightarrow$ 
  // fase wrapper
3  $\mathbf{T}'^{\downarrow k} \leftarrow$  proyectar( $\mathcal{T}'$ , mejorInd)  $\rightarrow$  K mejores atributos: ranking por IG
4 tasaAciertos  $\leftarrow$  crossValidate( $\mathbf{T}'^{\downarrow k}$ ,  $\mathcal{C}$ )
5 if (tasaAciertos > mejorTasaAc)
6   mejorTasaAc  $\leftarrow$  tasaAciertos
7   mejor $\mathcal{T} \leftarrow$   $\mathbf{T}'^{\downarrow k}$ 
8 end
9 return mejor $\mathcal{T}$ 
```

$$f(c[]) = \sum_{i=1}^k IG_{T_{c[]}}(x_i)$$

2. IFS

- **IFS-EDAcfs:** filter puro: 1 sola búsqueda UMDA
 - Un individuo representa explícitamente las instancias seleccionadas.
 - Los atributos seleccionados se representan implícitamente con una búsqueda voraz con métrica CFS (correlation-based FS).
 - La bondad de un individuo es la devuelta por dicha búsqueda.

Algoritmo IFS-EDAcfs.

In Base de datos \mathcal{T} , n° instancias l ,
tamaño población m , n° generaciones x ,
tamaño población aprendizaje s

Out Base de datos reducida $\mathcal{R}_{\mathcal{T}}$
//fase filter

- 1 mejorInd \leftarrow UMDA_{cfs}(l, m, s, x, \mathcal{T})
- 2 return $\mathbf{T}'^{\downarrow k} \leftarrow$ proyectar($\mathcal{T}',$ mejorInd)

3. Experimentos

- Utilizamos el siguiente corpus para la evaluación de nuestras propuestas y comparación con otros métodos:

| Nombre | Instancias | Atributos | Clases |
|-----------------|------------|-----------|--------|
| Automobile | 205 | 25 | 6 |
| Balance | 625 | 4 | 3 |
| Bupa | 345 | 6 | 2 |
| Car | 1728 | 6 | 4 |
| Cleveland | 303 | 13 | 5 |
| Dermat | 366 | 34 | 6 |
| German | 1000 | 20 | 2 |
| Glass | 214 | 9 | 7 |
| Housevotes | 435 | 16 | 2 |
| Iris | 150 | 4 | 3 |
| Mammograph | 961 | 5 | 2 |
| Pima | 768 | 8 | 2 |
| Sonar | 208 | 60 | 2 |
| Spectfheart | 267 | 44 | 2 |
| Tic-tac-toe | 958 | 9 | 2 |
| Vehicle | 846 | 18 | 4 |
| Wisconsin | 699 | 9 | 2 |
| Zoo | 101 | 16 | 7 |
| Chess | 3196 | 36 | 2 |
| Movement-libras | 360 | 90 | 15 |
| Satimage | 6435 | 36 | 7 |
| Spambase | 4597 | 57 | 2 |
| Splice | 3190 | 60 | 3 |
| Texture | 5500 | 40 | 11 |

3. Experimentos

- Hemos evaluado nuestras propuestas mediante una **3x10cv**, y los resultados devueltos son la media los 3 valores devueltos por la media de cada 10cv.
 - Nº generaciones = 50
 - Tamaño población = 20
 - Tamaño población aprendizaje (cada generación) = 10
- **1NN** como algoritmo base de clasificación.
- Atenderemos a los siguientes criterios para comparar nuestras propuestas con otras existentes:
 - Tasa de aciertos (TA)
 - Kappa
 - Tiempo de ejecución
 - % Reducción de atributos

} Test de Wilcoxon

3. Experimentos

IFS-EDAig

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|---------------|
| Automobile | 65.85 | 0.55 | 53.34 | 69.60 | 22.21 |
| Balance | 79.10 | 0.63 | 51.59 | 1.67 | 5.33 |
| Bupa | 58.56 | 0.15 | 52.93 | 57.22 | 5.17 |
| Car | 90.53 | 0.80 | 55.85 | 16.67 | 51.04 |
| Cleveland | 53.33 | 0.26 | 54.79 | 60.51 | 9.86 |
| Dermat | 93.17 | 0.91 | 54.28 | 20.59 | 24.66 |
| German | 71.70 | 0.30 | 51.95 | 80.17 | 52.10 |
| Glass | 67.14 | 0.55 | 53.59 | 35.93 | 8.31 |
| Housevotes | 95.49 | 0.91 | 52.33 | 92.71 | 11.75 |
| Iris | 94.67 | 0.92 | 51.28 | 68.33 | 1.10 |
| Mammograph | 82.13 | 0.64 | 51.43 | 63.33 | 6.88 |
| Pima | 70.62 | 0.35 | 52.51 | 54.58 | 38.65 |
| Sonar | 74.86 | 0.49 | 58.31 | 68.44 | 159.43 |
| Spectfheart | 67.78 | 0.27 | 63.24 | 74.39 | 109.63 |
| Tic-tac-toe | 92.63 | 0.83 | 52.66 | 0.00 | 22.23 |
| Vehicle | 67.97 | 0.57 | 50.25 | 28.89 | 74.75 |
| Wisconsin | 96.37 | 0.92 | 50.85 | 26.67 | 13.62 |
| Zoo | 92.03 | 0.90 | 54.64 | 29.38 | 2.73 |
| Ches | 95.25 | 0.90 | 50.57 | 58.70 | 765.57 |
| Movement_libras | 71.48 | 0.69 | 50.61 | 17.44 | 1836.38 |
| Satimage | 89.17 | 0.87 | 49.67 | 15.09 | 3062.14 |
| Spambase | 88.70 | 0.76 | 50.69 | 63.98 | 4969.81 |
| Splice | 88.45 | 0.82 | 48.97 | 93.11 | 847.90 |
| Texture | 98.08 | 0.98 | 49.89 | 15.17 | 6375.14 |
| Media | 81.04 | 0.67 | 52.76 | 46.36 | 769.85 |

IFS-EDAcfs

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|--------------|
| Automobile | 67.92 | 0.58 | 56.49 | 75.87 | 1.29 |
| Balance | 79.53 | 0.64 | 53.35 | 1.67 | 0.85 |
| Bupa | 55.58 | 0.09 | 53.25 | 70.56 | 0.60 |
| Car | 77.62 | 0.56 | 50.32 | 66.67 | 2.51 |
| Cleveland | 54.91 | 0.28 | 55.52 | 54.10 | 0.98 |
| Dermat | 94.45 | 0.93 | 54.32 | 59.22 | 2.48 |
| German | 68.40 | 0.24 | 50.97 | 80.50 | 2.43 |
| Glass | 67.42 | 0.56 | 55.36 | 43.70 | 0.87 |
| Housevotes | 95.64 | 0.91 | 51.82 | 93.75 | 0.51 |
| Iris | 92.89 | 0.89 | 29.58 | 75.00 | 0.29 |
| Mammograph | 80.92 | 0.62 | 51.34 | 42.00 | 1.49 |
| Pima | 69.88 | 0.34 | 52.66 | 63.75 | 1.86 |
| Sonar | 74.37 | 0.48 | 58.23 | 89.44 | 5.31 |
| Spectfheart | 72.90 | 0.34 | 58.17 | 71.29 | 3.97 |
| Tic-tac-toe | 69.93 | 0.34 | 51.72 | 88.89 | 1.16 |
| Vehicle | 60.68 | 0.48 | 52.14 | 61.85 | 5.97 |
| Wisconsin | 95.80 | 0.91 | 52.25 | 32.22 | 1.53 |
| Zoo | 90.39 | 0.87 | 55.15 | 55.00 | 0.31 |
| Ches | 90.43 | 0.81 | 49.89 | 91.67 | 15.06 |
| Movement_libras | 66.02 | 0.64 | 54.02 | 76.59 | 40.70 |
| Satimage | 88.68 | 0.86 | 50.31 | 36.94 | 163.46 |
| Spambase | 89.07 | 0.77 | 50.09 | 81.35 | 94.98 |
| Splice | 88.04 | 0.81 | 50.32 | 90.00 | 87.89 |
| Texture | 96.65 | 0.96 | 50.37 | 74.83 | 163.43 |
| Media | 78.67 | 0.62 | 51.99 | 65.70 | 25.00 |

3. Experimentos

IFS-EDAig

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|---------------|
| Automobile | 65.85 | 0.55 | 53.34 | 69.60 | 22.21 |
| Balance | 79.10 | 0.63 | 51.59 | 1.67 | 5.33 |
| Bupa | 58.56 | 0.15 | 52.93 | 57.22 | 5.17 |
| Car | 90.53 | 0.80 | 55.85 | 16.67 | 51.04 |
| Cleveland | 53.33 | 0.26 | 54.79 | 60.51 | 9.86 |
| Dermat | 93.17 | 0.91 | 54.28 | 20.59 | 24.66 |
| German | 71.70 | 0.30 | 51.95 | 80.17 | 52.10 |
| Glass | 67.14 | 0.55 | 53.59 | 35.93 | 8.31 |
| Housevotes | 95.49 | 0.91 | 52.33 | 92.71 | 11.75 |
| Iris | 94.67 | 0.92 | 51.28 | 68.33 | 1.10 |
| Mammograph | 82.13 | 0.64 | 51.43 | 63.33 | 6.88 |
| Pima | 70.62 | 0.35 | 52.51 | 54.58 | 38.65 |
| Sonar | 74.86 | 0.49 | 58.31 | 68.44 | 159.43 |
| Spectfheart | 67.78 | 0.27 | 63.24 | 74.39 | 109.63 |
| Tic-tac-toe | 92.63 | 0.83 | 52.66 | 0.00 | 22.23 |
| Vehicle | 67.97 | 0.57 | 50.25 | 28.89 | 74.75 |
| Wisconsin | 96.37 | 0.92 | 50.85 | 26.67 | 13.62 |
| Zoo | 92.03 | 0.90 | 54.64 | 29.38 | 2.73 |
| Ches | 95.25 | 0.90 | 50.57 | 58.70 | 765.57 |
| Movement_libras | 71.48 | 0.69 | 50.61 | 17.44 | 1836.38 |
| Satimage | 89.17 | 0.87 | 49.67 | 15.09 | 3062.14 |
| Spambase | 88.70 | 0.76 | 50.69 | 63.98 | 4969.81 |
| Splice | 88.45 | 0.82 | 48.97 | 93.11 | 847.90 |
| Texture | 98.08 | 0.98 | 49.89 | 15.17 | 6375.14 |
| <i>Media</i> | 81.04 | 0.67 | 52.76 | 46.36 | 769.85 |

IFS-EDAcfs

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|--------------|
| Automobile | 67.92 | 0.58 | 56.49 | 75.87 | 1.29 |
| Balance | 79.53 | 0.64 | 53.35 | 1.67 | 0.85 |
| Bupa | 55.58 | 0.09 | 53.25 | 70.56 | 0.60 |
| Car | 77.62 | 0.56 | 50.32 | 66.67 | 2.51 |
| Cleveland | 54.91 | 0.28 | 55.52 | 54.10 | 0.98 |
| Dermat | 94.45 | 0.93 | 54.32 | 59.22 | 2.48 |
| German | 68.40 | 0.24 | 50.97 | 80.50 | 2.43 |
| Glass | 67.42 | 0.56 | 55.36 | 43.70 | 0.87 |
| Housevotes | 95.64 | 0.91 | 51.82 | 93.75 | 0.51 |
| Iris | 92.89 | 0.89 | 29.58 | 75.00 | 0.29 |
| Mammograph | 80.92 | 0.62 | 51.34 | 42.00 | 1.49 |
| Pima | 69.88 | 0.34 | 52.66 | 63.75 | 1.86 |
| Sonar | 74.37 | 0.48 | 58.23 | 89.44 | 5.31 |
| Spectfheart | 72.90 | 0.34 | 58.17 | 71.29 | 3.97 |
| Tic-tac-toe | 69.93 | 0.34 | 51.72 | 88.89 | 1.16 |
| Vehicle | 60.68 | 0.48 | 52.14 | 61.85 | 5.97 |
| Wisconsin | 95.80 | 0.91 | 52.25 | 32.22 | 1.53 |
| Zoo | 90.39 | 0.87 | 55.15 | 55.00 | 0.31 |
| Ches | 90.43 | 0.81 | 49.89 | 91.67 | 15.06 |
| Movement_libras | 66.02 | 0.64 | 54.02 | 76.59 | 40.70 |
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| Texture | 96.65 | 0.96 | 50.37 | 74.83 | 163.43 |
| <i>Media</i> | 78.67 | 0.62 | 51.99 | 65.70 | 25.00 |

3. Experimentos

IFS-EDAig

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|-------|-------|---------|
| Automobile | 65.85 | 0.55 | 53.34 | 69.60 | 22.21 |
| Balance | 79.10 | 0.63 | 51.59 | 1.67 | 5.33 |
| Bupa | 58.56 | 0.15 | 52.93 | 57.22 | 5.17 |
| Car | 90.53 | 0.80 | 55.85 | 16.67 | 51.04 |
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| Pima | 70.62 | 0.35 | 52.51 | 54.58 | 38.65 |
| Sonar | 74.86 | 0.49 | 58.31 | 68.44 | 159.43 |
| Spectfheart | 67.78 | 0.27 | 63.24 | 74.39 | 109.63 |
| Tic-tac-toe | 92.63 | 0.83 | 52.66 | 0.00 | 22.23 |
| Vehicle | 67.97 | 0.57 | 50.25 | 28.89 | 74.75 |
| Wisconsin | 96.37 | 0.92 | 50.85 | 26.67 | 13.62 |
| Zoo | 92.03 | 0.90 | 54.64 | 29.38 | 2.73 |
| Ches | 95.25 | 0.90 | 50.57 | 58.70 | 765.57 |
| Movement_libras | 71.48 | 0.69 | 50.61 | 17.44 | 1836.38 |
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| Dermat | 94.45 | 0.93 | 54.32 | 59.22 | 2.48 |
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| Glass | 67.42 | 0.56 | 55.36 | 43.70 | 0.87 |
| Housevotes | 95.64 | 0.91 | 51.82 | 93.75 | 0.51 |
| Iris | 92.89 | 0.89 | 29.58 | 75.00 | 0.29 |
| Mammograph | 80.92 | 0.62 | 51.34 | 42.00 | 1.49 |
| Pima | 69.88 | 0.34 | 52.66 | 63.75 | 1.86 |
| Sonar | 74.37 | 0.48 | 58.23 | 89.44 | 5.31 |
| Spectfheart | 72.90 | 0.34 | 58.17 | 71.29 | 3.97 |
| Tic-tac-toe | 69.93 | 0.34 | 51.72 | 88.89 | 1.16 |
| Vehicle | 60.68 | 0.48 | 52.14 | 61.85 | 5.97 |
| Wisconsin | 95.80 | 0.91 | 52.25 | 32.22 | 1.53 |
| Zoo | 90.39 | 0.87 | 55.15 | 55.00 | 0.31 |
| Ches | 90.43 | 0.81 | 49.89 | 91.67 | 15.06 |
| Movement_libras | 66.02 | 0.64 | 54.02 | 76.59 | 40.70 |
| Satimage | 88.68 | 0.86 | 50.31 | 36.94 | 163.46 |
| Spambase | 89.07 | 0.77 | 50.09 | 81.35 | 94.98 |
| Splice | 88.04 | 0.81 | 50.32 | 90.00 | 87.89 |
| Texture | 96.65 | 0.96 | 50.37 | 74.83 | 163.43 |
| <i>Media</i> | 78.67 | 0.62 | 51.99 | 65.70 | 25.00 |

3. Experimentos

IFS-EDAig

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|-------|---------|
| Automobile | 65.85 | 0.55 | 53.34 | 69.60 | 22.21 |
| Balance | 79.10 | 0.63 | 51.59 | 1.67 | 5.33 |
| Bupa | 58.56 | 0.15 | 52.93 | 57.22 | 5.17 |
| Car | 90.53 | 0.80 | 55.85 | 16.67 | 51.04 |
| Cleveland | 53.33 | 0.26 | 54.79 | 60.51 | 9.86 |
| Dermat | 93.17 | 0.91 | 54.28 | 20.59 | 24.66 |
| German | 71.70 | 0.30 | 51.95 | 80.17 | 52.10 |
| Glass | 67.14 | 0.55 | 53.59 | 35.93 | 8.31 |
| Housevotes | 95.49 | 0.91 | 52.33 | 92.71 | 11.75 |
| Iris | 94.67 | 0.92 | 51.28 | 68.33 | 1.10 |
| Mammograph | 82.13 | 0.64 | 51.43 | 63.33 | 6.88 |
| Pima | 70.62 | 0.35 | 52.51 | 54.58 | 38.65 |
| Sonar | 74.86 | 0.49 | 58.31 | 68.44 | 159.43 |
| Spectfheart | 67.78 | 0.27 | 63.24 | 74.39 | 109.63 |
| Tic-tac-toe | 92.63 | 0.83 | 52.66 | 0.00 | 22.23 |
| Vehicle | 67.97 | 0.57 | 50.25 | 28.89 | 74.75 |
| Wisconsin | 96.37 | 0.92 | 50.85 | 26.67 | 13.62 |
| Zoo | 92.03 | 0.90 | 54.64 | 29.38 | 2.73 |
| Ches | 95.25 | 0.90 | 50.57 | 58.70 | 765.57 |
| Movement_libras | 71.48 | 0.69 | 50.61 | 17.44 | 1836.38 |
| Satimage | 89.17 | 0.87 | 49.67 | 15.09 | 3062.14 |
| Spambase | 88.70 | 0.76 | 50.69 | 63.98 | 4969.81 |
| Splice | 88.45 | 0.82 | 48.97 | 93.11 | 847.90 |
| Texture | 98.08 | 0.98 | 49.89 | 15.17 | 6375.14 |
| <i>Media</i> | 81.04 | 0.67 | 52.76 | 46.36 | 769.85 |

IFS-EDAcfs

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|-------|--------|
| Automobile | 67.92 | 0.58 | 56.49 | 75.87 | 1.29 |
| Balance | 79.53 | 0.64 | 53.35 | 1.67 | 0.85 |
| Bupa | 55.58 | 0.09 | 53.25 | 70.56 | 0.60 |
| Car | 77.62 | 0.56 | 50.32 | 66.67 | 2.51 |
| Cleveland | 54.91 | 0.28 | 55.52 | 54.10 | 0.98 |
| Dermat | 94.45 | 0.93 | 54.32 | 59.22 | 2.48 |
| German | 68.40 | 0.24 | 50.97 | 80.50 | 2.43 |
| Glass | 67.42 | 0.56 | 55.36 | 43.70 | 0.87 |
| Housevotes | 95.64 | 0.91 | 51.82 | 93.75 | 0.51 |
| Iris | 92.89 | 0.89 | 29.58 | 75.00 | 0.29 |
| Mammograph | 80.92 | 0.62 | 51.34 | 42.00 | 1.49 |
| Pima | 69.88 | 0.34 | 52.66 | 63.75 | 1.86 |
| Sonar | 74.37 | 0.48 | 58.23 | 89.44 | 5.31 |
| Spectfheart | 72.90 | 0.34 | 58.17 | 71.29 | 3.97 |
| Tic-tac-toe | 69.93 | 0.34 | 51.72 | 88.89 | 1.16 |
| Vehicle | 60.68 | 0.48 | 52.14 | 61.85 | 5.97 |
| Wisconsin | 95.80 | 0.91 | 52.25 | 32.22 | 1.53 |
| Zoo | 90.39 | 0.87 | 55.15 | 55.00 | 0.31 |
| Ches | 90.43 | 0.81 | 49.89 | 91.67 | 15.06 |
| Movement_libras | 66.02 | 0.64 | 54.02 | 76.59 | 40.70 |
| Satimage | 88.68 | 0.86 | 50.31 | 36.94 | 163.46 |
| Spambase | 89.07 | 0.77 | 50.09 | 81.35 | 94.98 |
| Splice | 88.04 | 0.81 | 50.32 | 90.00 | 87.89 |
| Texture | 96.65 | 0.96 | 50.37 | 74.83 | 163.43 |
| <i>Media</i> | 78.67 | 0.62 | 51.99 | 65.70 | 25.00 |

3. Experimentos

IFS-EDAig

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|---------|
| Automobile | 65.85 | 0.55 | 53.34 | 69.60 | 22.21 |
| Balance | 79.10 | 0.63 | 51.59 | 1.67 | 5.33 |
| Bupa | 58.56 | 0.15 | 52.93 | 57.22 | 5.17 |
| Car | 90.53 | 0.80 | 55.85 | 16.67 | 51.04 |
| Cleveland | 53.33 | 0.26 | 54.79 | 60.51 | 9.86 |
| Dermat | 93.17 | 0.91 | 54.28 | 20.59 | 24.66 |
| German | 71.70 | 0.30 | 51.95 | 80.17 | 52.10 |
| Glass | 67.14 | 0.55 | 53.59 | 35.93 | 8.31 |
| Housevotes | 95.49 | 0.91 | 52.33 | 92.71 | 11.75 |
| Iris | 94.67 | 0.92 | 51.28 | 68.33 | 1.10 |
| Mammograph | 82.13 | 0.64 | 51.43 | 63.33 | 6.88 |
| Pima | 70.62 | 0.35 | 52.51 | 54.58 | 38.65 |
| Sonar | 74.86 | 0.49 | 58.31 | 68.44 | 159.43 |
| Spectfheart | 67.78 | 0.27 | 63.24 | 74.39 | 109.63 |
| Tic-tac-toe | 92.63 | 0.83 | 52.66 | 0.00 | 22.23 |
| Vehicle | 67.97 | 0.57 | 50.25 | 28.89 | 74.75 |
| Wisconsin | 96.37 | 0.92 | 50.85 | 26.67 | 13.62 |
| Zoo | 92.03 | 0.90 | 54.64 | 29.38 | 2.73 |
| Ches | 95.25 | 0.90 | 50.57 | 58.70 | 765.57 |
| Movement_libras | 71.48 | 0.69 | 50.61 | 17.44 | 1836.38 |
| Satimage | 89.17 | 0.87 | 49.67 | 15.09 | 3062.14 |
| Spambase | 88.70 | 0.76 | 50.69 | 63.98 | 4969.81 |
| Splice | 88.45 | 0.82 | 48.97 | 93.11 | 847.90 |
| Texture | 98.08 | 0.98 | 49.89 | 15.17 | 6375.14 |
| <i>Media</i> | 81.04 | 0.67 | 52.76 | 46.36 | 769.85 |

IFS-EDAcfs

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|--------|
| Automobile | 67.92 | 0.58 | 56.49 | 75.87 | 1.29 |
| Balance | 79.53 | 0.64 | 53.35 | 1.67 | 0.85 |
| Bupa | 55.58 | 0.09 | 53.25 | 70.56 | 0.60 |
| Car | 77.62 | 0.56 | 50.32 | 66.67 | 2.51 |
| Cleveland | 54.91 | 0.28 | 55.52 | 54.10 | 0.98 |
| Dermat | 94.45 | 0.93 | 54.32 | 59.22 | 2.48 |
| German | 68.40 | 0.24 | 50.97 | 80.50 | 2.43 |
| Glass | 67.42 | 0.56 | 55.36 | 43.70 | 0.87 |
| Housevotes | 95.64 | 0.91 | 51.82 | 93.75 | 0.51 |
| Iris | 92.89 | 0.89 | 29.58 | 75.00 | 0.29 |
| Mammograph | 80.92 | 0.62 | 51.34 | 42.00 | 1.49 |
| Pima | 69.88 | 0.34 | 52.66 | 63.75 | 1.86 |
| Sonar | 74.37 | 0.48 | 58.23 | 89.44 | 5.31 |
| Spectfheart | 72.90 | 0.34 | 58.17 | 71.29 | 3.97 |
| Tic-tac-toe | 69.93 | 0.34 | 51.72 | 88.89 | 1.16 |
| Vehicle | 60.68 | 0.48 | 52.14 | 61.85 | 5.97 |
| Wisconsin | 95.80 | 0.91 | 52.25 | 32.22 | 1.53 |
| Zoo | 90.39 | 0.87 | 55.15 | 55.00 | 0.31 |
| Ches | 90.43 | 0.81 | 49.89 | 91.67 | 15.06 |
| Movement_libras | 66.02 | 0.64 | 54.02 | 76.59 | 40.70 |
| Satimage | 88.68 | 0.86 | 50.31 | 36.94 | 163.46 |
| Spambase | 89.07 | 0.77 | 50.09 | 81.35 | 94.98 |
| Splice | 88.04 | 0.81 | 50.32 | 90.00 | 87.89 |
| Texture | 96.65 | 0.96 | 50.37 | 74.83 | 163.43 |
| <i>Media</i> | 78.67 | 0.62 | 51.99 | 65.70 | 25.00 |

3. Experimentos

IFS-EDAig

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|---------------|
| Automobile | 65.85 | 0.55 | 53.34 | 69.60 | 22.21 |
| Balance | 79.10 | 0.63 | 51.59 | 1.67 | 5.33 |
| Bupa | 58.56 | 0.15 | 52.93 | 57.22 | 5.17 |
| Car | 90.53 | 0.80 | 55.85 | 16.67 | 51.04 |
| Cleveland | 53.33 | 0.26 | 54.79 | 60.51 | 9.86 |
| Dermat | 93.17 | 0.91 | 54.28 | 20.59 | 24.66 |
| German | 71.70 | 0.30 | 51.95 | 80.17 | 52.10 |
| Glass | 67.14 | 0.55 | 53.59 | 35.93 | 8.31 |
| Housevotes | 95.49 | 0.91 | 52.33 | 92.71 | 11.75 |
| Iris | 94.67 | 0.92 | 51.28 | 68.33 | 1.10 |
| Mammograph | 82.13 | 0.64 | 51.43 | 63.33 | 6.88 |
| Pima | 70.62 | 0.35 | 52.51 | 54.58 | 38.65 |
| Sonar | 74.86 | 0.49 | 58.31 | 68.44 | 159.43 |
| Spectfheart | 67.78 | 0.27 | 63.24 | 74.39 | 109.63 |
| Tic-tac-toe | 92.63 | 0.83 | 52.66 | 0.00 | 22.23 |
| Vehicle | 67.97 | 0.57 | 50.25 | 28.89 | 74.75 |
| Wisconsin | 96.37 | 0.92 | 50.85 | 26.67 | 13.62 |
| Zoo | 92.03 | 0.90 | 54.64 | 29.38 | 2.73 |
| Ches | 95.25 | 0.90 | 50.57 | 58.70 | 765.57 |
| Movement_libras | 71.48 | 0.69 | 50.61 | 17.44 | 1836.38 |
| Satimage | 89.17 | 0.87 | 49.67 | 15.09 | 3062.14 |
| Spambase | 88.70 | 0.76 | 50.69 | 63.98 | 4969.81 |
| Splice | 88.45 | 0.82 | 48.97 | 93.11 | 847.90 |
| Texture | 98.08 | 0.98 | 49.89 | 15.17 | 6375.14 |
| <i>Media</i> | 81.04 | 0.67 | 52.76 | 46.36 | 769.85 |

IFS-EDAcfs

| Nombre | TA | Kappa | ISR | FSR | Tiempo |
|-----------------|--------------|-------------|--------------|--------------|--------------|
| Automobile | 67.92 | 0.58 | 56.49 | 75.87 | 1.29 |
| Balance | 79.53 | 0.64 | 53.35 | 1.67 | 0.85 |
| Bupa | 55.58 | 0.09 | 53.25 | 70.56 | 0.60 |
| Car | 77.62 | 0.56 | 50.32 | 66.67 | 2.51 |
| Cleveland | 54.91 | 0.28 | 55.52 | 54.10 | 0.98 |
| Dermat | 94.45 | 0.93 | 54.32 | 59.22 | 2.48 |
| German | 68.40 | 0.24 | 50.97 | 80.50 | 2.43 |
| Glass | 67.42 | 0.56 | 55.36 | 43.70 | 0.87 |
| Housevotes | 95.64 | 0.91 | 51.82 | 93.75 | 0.51 |
| Iris | 92.89 | 0.89 | 29.58 | 75.00 | 0.29 |
| Mammograph | 80.92 | 0.62 | 51.34 | 42.00 | 1.49 |
| Pima | 69.88 | 0.34 | 52.66 | 63.75 | 1.86 |
| Sonar | 74.37 | 0.48 | 58.23 | 89.44 | 5.31 |
| Spectfheart | 72.90 | 0.34 | 58.17 | 71.29 | 3.97 |
| Tic-tac-toe | 69.93 | 0.34 | 51.72 | 88.89 | 1.16 |
| Vehicle | 60.68 | 0.48 | 52.14 | 61.85 | 5.97 |
| Wisconsin | 95.80 | 0.91 | 52.25 | 32.22 | 1.53 |
| Zoo | 90.39 | 0.87 | 55.15 | 55.00 | 0.31 |
| Ches | 90.43 | 0.81 | 49.89 | 91.67 | 15.06 |
| Movement_libras | 66.02 | 0.64 | 54.02 | 76.59 | 40.70 |
| Satimage | 88.68 | 0.86 | 50.31 | 36.94 | 163.46 |
| Spambase | 89.07 | 0.77 | 50.09 | 81.35 | 94.98 |
| Splice | 88.04 | 0.81 | 50.32 | 90.00 | 87.89 |
| Texture | 96.65 | 0.96 | 50.37 | 74.83 | 163.43 |
| <i>Media</i> | 78.67 | 0.62 | 51.99 | 65.70 | 25.00 |

3. Experimentos

| Medida | IFS-EDAig | IFS-EDAcs | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|--------|-----------|-----------|------------|----------|-----------|-----------|--------------|
| TA | 81.0446 | 78.6722 | 84.2963 | 81.3458 | 71.9675 | 81.5233 | 83.1881 |
| Kappa | 0.6669 | 0.6215 | 0.6963 | 0.6107 | 0.6097 | 0.6482 | 0.6289 |
| Tiempo | 769.8488 | 24.9978 | 10356.8192 | 374.1075 | 5723.7379 | 5092.3096 | - |
| ISR | 52.7599 | 51.9850 | 94.5667 | - | - | - | - |
| FSR | 46.3572 | 65.7023 | 53.1729 | - | - | - | - |

3. Experimentos

| Medida | IFS-EDAig | IFS-EDAcs | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|--------|-----------|-----------|------------|----------|-----------|-----------|--------------|
| TA | 81.0446 | 78.6722 | 84.2963 | 81.3458 | 71.9675 | 81.5233 | 83.1881 |
| Kappa | 0.6669 | 0.6215 | 0.6963 | 0.6107 | 0.6097 | 0.6482 | 0.6289 |
| Tiempo | 769.8488 | 24.9978 | 10356.8192 | 374.1075 | 5723.7379 | 5092.3096 | - |
| ISR | 52.7599 | 51.9850 | 94.5667 | - | - | - | - |
| FSR | 46.3572 | 65.7023 | 53.1729 | - | - | - | - |

3. Experimentos

| Medida | IFS-EDAig | IFS-EDAcfS | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|--------|-----------|------------|------------|----------|-----------|-----------|--------------|
| TA | 81.0446 | 78.6722 | 84.2963 | 81.3458 | 71.9675 | 81.5233 | 83.1881 |
| Kappa | 0.6669 | 0.6215 | 0.6963 | 0.6107 | 0.6097 | 0.6482 | 0.6289 |
| Tiempo | 769.8488 | 24.9978 | 10356.8192 | 374.1075 | 5723.7379 | 5092.3096 | - |
| ISR | 52.7599 | 51.9850 | 94.5667 | - | - | - | - |
| FSR | 46.3572 | 65.7023 | 53.1729 | - | - | - | - |

3. Experimentos

| Medida | IFS-EDAig | IFS-EDAcfS | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|--------|-----------|------------|------------|----------|-----------|-----------|--------------|
| TA | 81.0446 | 78.6722 | 84.2963 | 81.3458 | 71.9675 | 81.5233 | 83.1881 |
| Kappa | 0.6669 | 0.6215 | 0.6963 | 0.6107 | 0.6097 | 0.6482 | 0.6289 |
| Tiempo | 769.8488 | 24.9978 | 10356.8192 | 374.1075 | 5723.7379 | 5092.3096 | - |
| ISR | 52.7599 | 51.9850 | 94.5667 | - | - | - | - |
| FSR | 46.3572 | 65.7023 | 53.1729 | - | - | - | - |

3. Experimentos

| Medida | IFS-EDAig | IFS-EDAcfS | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|--------|-----------|------------|------------|----------|-----------|-----------|--------------|
| TA | 81.0446 | 78.6722 | 84.2963 | 81.3458 | 71.9675 | 81.5233 | 83.1881 |
| Kappa | 0.6669 | 0.6215 | 0.6963 | 0.6107 | 0.6097 | 0.6482 | 0.6289 |
| Tiempo | 769.8488 | 24.9978 | 10356.8192 | 374.1075 | 5723.7379 | 5092.3096 | - |
| ISR | 52.7599 | 51.9850 | 94.5667 | - | - | - | - |
| FSR | 46.3572 | 65.7023 | 53.1729 | - | - | - | - |

3. Experimentos

| Medida | IFS-EDAig | IFS-EDAcfS | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|--------|-----------|------------|------------|----------|-----------|-----------|--------------|
| TA | 81.0446 | 78.6722 | 84.2963 | 81.3458 | 71.9675 | 81.5233 | 83.1881 |
| Kappa | 0.6669 | 0.6215 | 0.6963 | 0.6107 | 0.6097 | 0.6482 | 0.6289 |
| Tiempo | 769.8488 | 24.9978 | 10356.8192 | 374.1075 | 5723.7379 | 5092.3096 | - |
| ISR | 52.7599 | 51.9850 | 94.5667 | - | - | - | - |
| FSR | 46.3572 | 65.7023 | 53.1729 | - | - | - | - |

3. Experimentos

| Medida | IFS-EDAig | IFS-EDAcs | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|--------|-----------|-----------|------------|----------|-----------|-----------|--------------|
| TA | 81.0446 | 78.6722 | 84.2963 | 81.3458 | 71.9675 | 81.5233 | 83.1881 |
| Kappa | 0.6669 | 0.6215 | 0.6963 | 0.6107 | 0.6097 | 0.6482 | 0.6289 |
| Tiempo | 769.8488 | 24.9978 | 10356.8192 | 374.1075 | 5723.7379 | 5092.3096 | - |
| ISR | 52.7599 | 51.9850 | 94.5667 | - | - | - | - |
| FSR | 46.3572 | 65.7023 | 53.1729 | - | - | - | - |

3. Experimentos

- IFS-EDA mejor que el resto

Negrita: diferencia estadística

TASA DE ACIERTO

| | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|------------|---------------|---------------|----------------|---------------|---------------|
| IFS-EDAig | 0.0010 | 0.4387 | 0.0003● | 0.4073 | 0.0060 |
| IFS-EDAcfs | 0.0000 | 0.0036 | 0.0035● | 0.0022 | 0.0060 |

KAPPA

| | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|------------|---------------|----------------|----------------|----------------|----------------|
| IFS-EDAig | 0.0278 | 0.0108● | 0.0297● | 0.3216● | 0.3115● |
| IFS-EDAcfs | 0.0003 | 0.3658 ● | 0.4058 ● | 0.8982● | 0.7805 |

Resultados comparables con IFS-CoCo al tomar sólo bdd discretas

3. Experimentos

- IFS-EDA mejor que el resto

Negrita: diferencia estadística

TASA DE ACIERTO

| | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|------------|---------------|---------------|----------------|---------------|---------------|
| IFS-EDAig | 0.0010 | 0.4387 | 0.0003● | 0.4073 | 0.0060 |
| IFS-EDAcfs | 0.0000 | 0.0036 | 0.0035● | 0.0022 | 0.0060 |

KAPPA

| | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|------------|---------------|----------------|----------------|---------|--------------|
| IFS-EDAig | 0.0278 | 0.0108● | 0.0297● | 0.3216● | 0.3115● |
| IFS-EDAcfs | 0.0003 | 0.3658 ● | 0.4058 ● | 0.8982● | 0.7805 |

Resultados comparables con IFS-CoCo al tomar sólo bdd discretas

3. Experimentos

- IFS-EDA mejor que el resto

Negrita: diferencia estadística

TASA DE ACIERTO

| | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|------------|---------------|---------------|----------------|---------------|---------------|
| IFS-EDAig | 0.0010 | 0.4387 | 0.0003● | 0.4073 | 0.0060 |
| IFS-EDAcfs | 0.0000 | 0.0036 | 0.0035● | 0.0022 | 0.0060 |

KAPPA

| | IFS-CoCo | IFS-CHC | IGA | HGA | BDD original |
|------------|---------------|----------------|----------------|---------|----------------|
| IFS-EDAig | 0.0278 | 0.0108● | 0.0297● | 0.3216● | 0.3115● |
| IFS-EDAcfs | 0.0003 | 0.3658 ● | 0.4058 ● | 0.8982● | 0.7805 |

Resultados comparables con IFS-CoCo al tomar sólo bdd discretas

4. Conclusiones

- Propuesta de dos algoritmos basados en EDAs para la IFS:
 - **IFS-EDAig**: UMDA para un nº creciente de atributos evaluados con IG. Validación cruzada de 1NN para seleccionar nº atributos final en función de instancias.
 - **IFS-EDAcfs**: más sencillo. Un único UMDA con selección de atributos mediante métrica cfs.
- **Ventajas** a nivel de kappa con el resto de técnicas excepto IFS-CoCo, a quien aventaja en coste computacional.
- Otras ventajas:
 - Necesidad de ajustar un nº menor de parámetros .
 - Posibilidad de recurrir a la paralelización.
 - Las bases de datos resultantes están balanceadas.
 - Porcentaje de reducción en cuanto al número de atributos es mayor.

Trabajo futuro

- Hacer extensibles los algoritmos a bases de datos con atributos numéricos para evitar el uso de técnicas de discretización .
 - Medidas filter que manejen los **valores numéricos directamente**.
- Explotar formas alternativas de inicializar la población para **aumentar el porcentaje de reducción de instancias**.
- Probar diferentes **EDAs bivariados**, o incluso multivariados, para manejar las relaciones entre las variables.
- Interesante: adaptar las propuestas HGA e IFS-CoCo para la utilización de EDAs.

Gracias!

