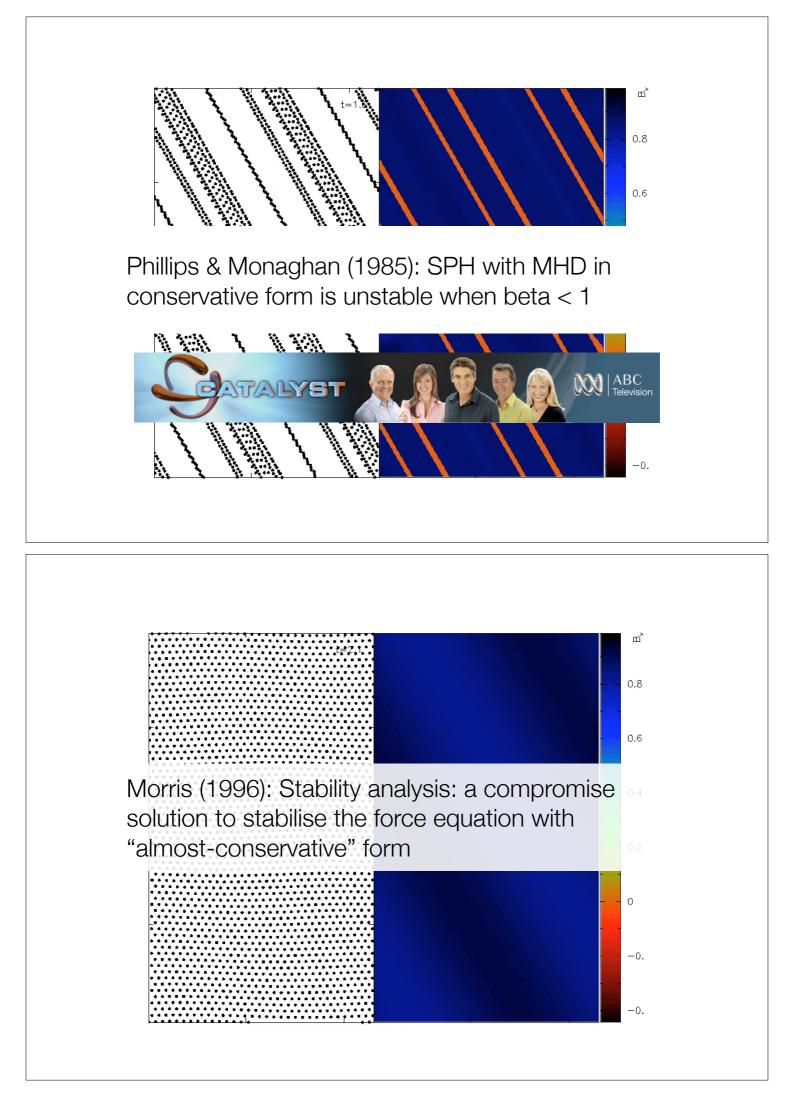
SPH +/- MHD

The state of the art in the dark arts

Daniel Price Monash University Melbourne, Australia



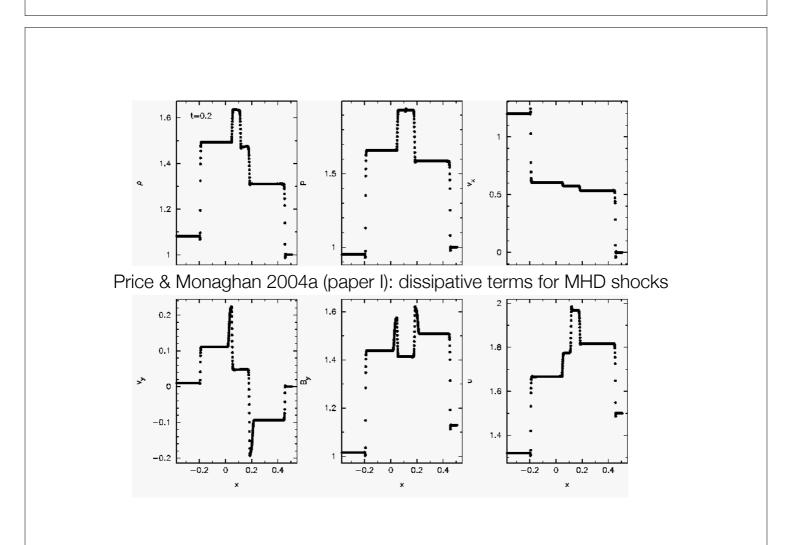
Gingold & Monaghan (1977): Magnetic polytropes with SPH

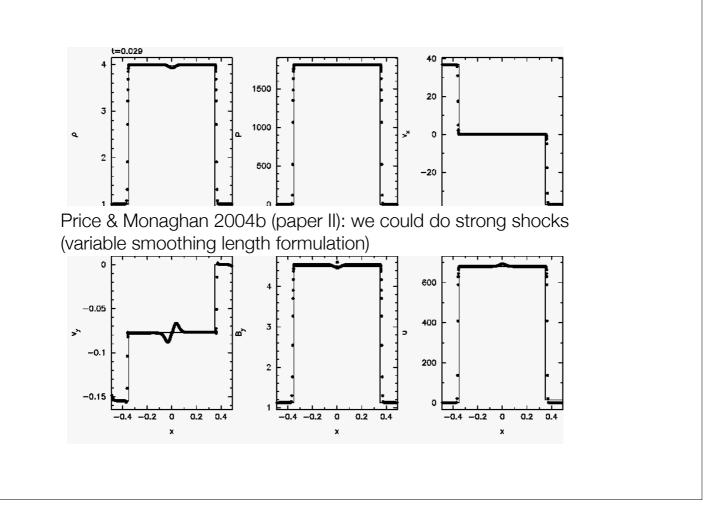


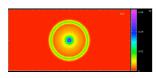
The "Middle Years"

Dolag, Bartelmann & Lesch (1999): SPH+MHD applied to galaxy clusters (beta >> 1)

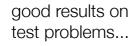




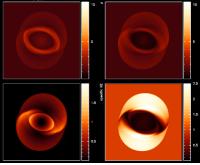




advection of a current loop (Gardiner & Stone 2006, Rosswog & Price 2007)





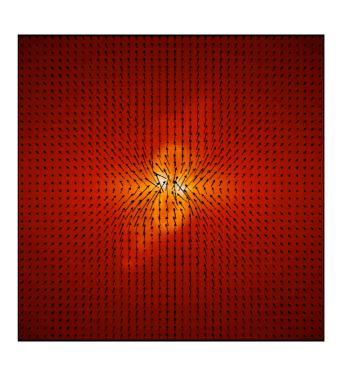


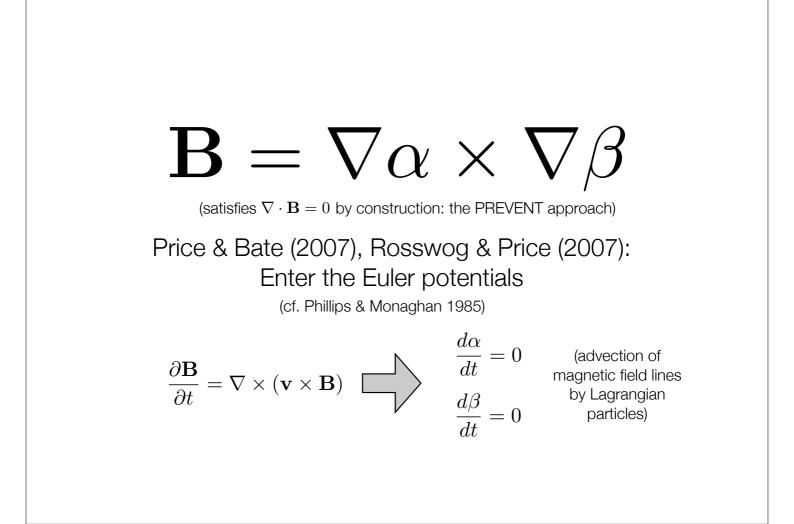
Orszag-Tang vortex problem (PM05, Rosswog & Price 2007) Magnetic rotor problem (PM05)

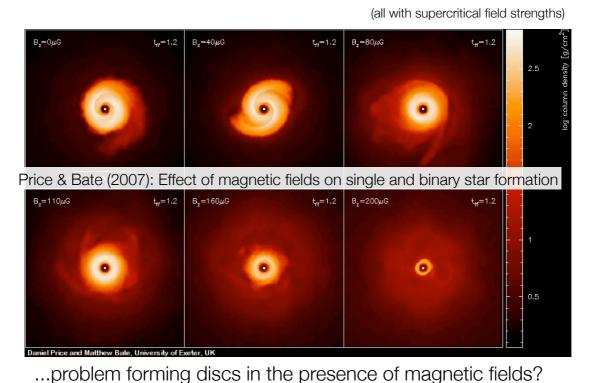
Price & Monaghan 2005 (paper III): How to handle the divergence constraint (using IGNORE or CLEAN approach)

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B}) \qquad \nabla \cdot \mathbf{B} = 0$$

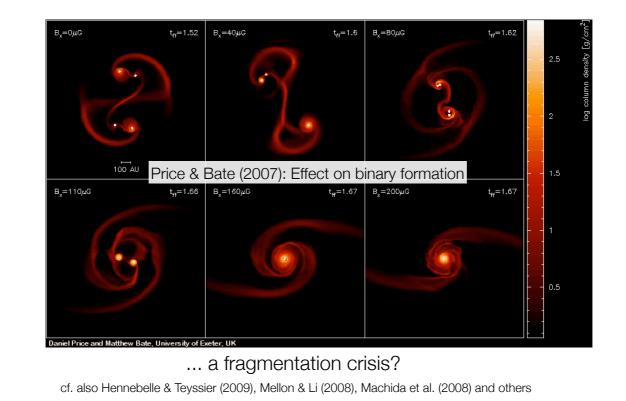
...but didn't work so well for star formation

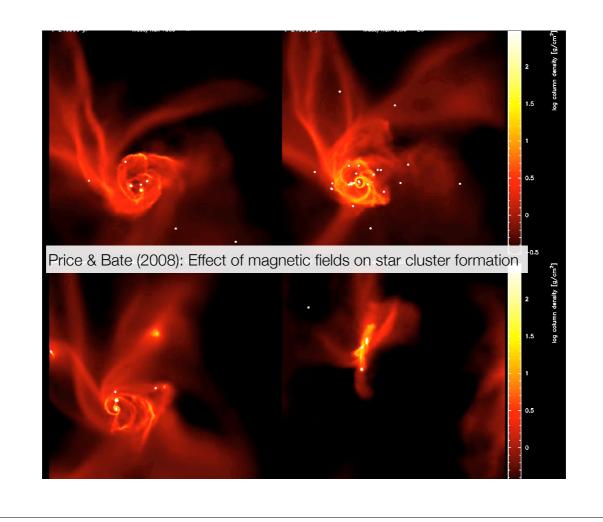


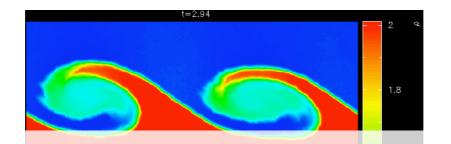




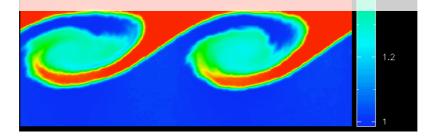
see also Hennebelle & Fromang (2008), Hennebelle & Ciardi (2009), Mellon & Li (2009), Duffin & Pudritz (2009)

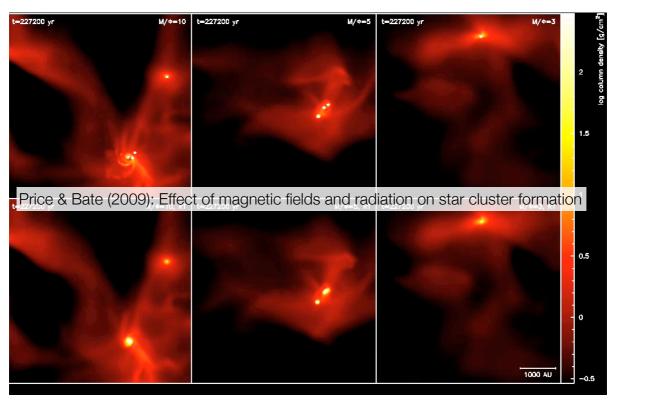






Price (2008): We got unhelpfully distracted by a discussion on Kelvin-Helmholtz instabilities...





net effect is a very much reduced star formation rate / efficiency per t_ff

Dolag & Stasyszyn (2009): SPH+MHD makes it's way into GADGET

application to galaxy clusters, magnetic field evolution and dynamics in spiral galaxies (Kotarba et al. 2009, Stasyszyn et al. 2010)

Limitations of the Euler potentials approach

(Rosswog & Price 2007, Price & Bate 2008, Brandenburg 2010)

$$\mathbf{B} = \nabla \alpha \times \nabla \beta \qquad \qquad \frac{d\alpha}{dt} = 0$$
$$\frac{d\beta}{dt} = 0$$

• advection of magnetic fields: no change in topology (A.B = 0)

- does not follow wind-up of magnetic fields
- difficult to model resistive effects -- reconnection processes not treated correctly

Axel Brandenburg (at KITP 2007): "Why don't you just use the vector potential?"

is $\mathbf{B} = \nabla \times \mathbf{A}$ a better approach?

$$\frac{\partial \mathbf{A}}{\partial t} = \mathbf{v} \times \mathbf{B} + \nabla \phi \quad \square \qquad \frac{d \mathbf{A}}{dt} = -A_i \nabla v^i$$

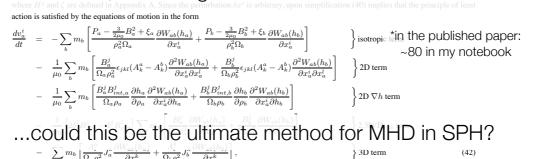
2.4.4 Equations of motion

Putting the perturbations (31) and (33) [the second term of which has been expanded into (38) and (39)] into (13) we have

 $\int \left\{ -m_a \frac{dv_a^i}{dt} - \sum_b \frac{m_b}{\Omega_b} \left[\frac{P_b}{\rho_b^2} - \frac{3}{2\mu_0} \left(\frac{B_b}{\rho_b} \right)^2 + \frac{\xi_b}{\rho_b^2} \right] \sum_c m_c \frac{\partial W_{bc}(h_b)}{\partial x_b^i} (\delta_{ba} - \delta_{ca})$ $- \frac{1}{\mu_0} \sum_b \frac{m_b}{\Omega_b} \frac{B_b^j}{\rho_b^2} \epsilon_{jkl} \sum_c m_c (A_k^b - A_k^c) \frac{\partial^2 W_{bc}(h_b)}{\partial x_b^i \partial x_b^i} (\delta_{ba} - \delta_{ca})$

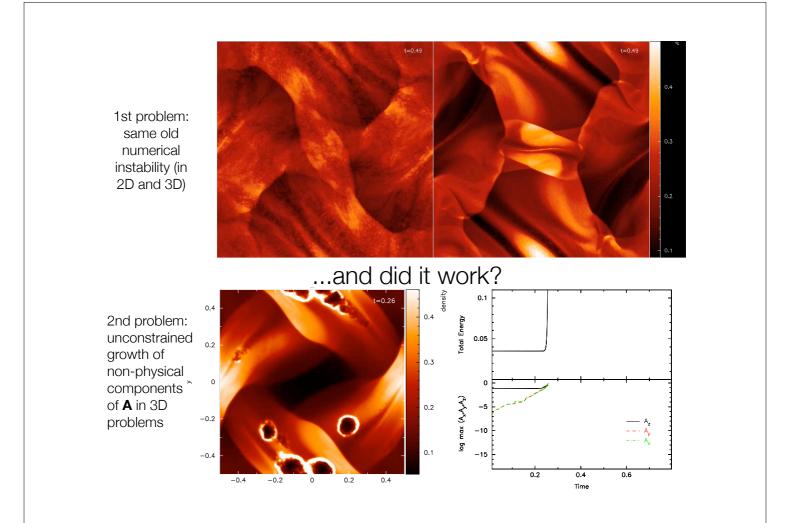
Price 2010 (paper IV): 25 pages* of pain later, we had derived the ultimate vector potential formulation in SPH...

...it was beautiful, derived elegantly from a Lagrangian variational principle, the method was exactly conservative, novel, the divergence was constrained...



 $-\sum_{b} m_{b} \left[\frac{\Delta + \omega_{c}}{\Omega_{a} \rho_{a}^{2}} J_{a}^{a} \frac{\partial u_{a} \psi(a_{a})}{\partial x_{a}^{k}} + \frac{\Delta + \omega_{c}}{\Omega_{b} \rho_{b}^{2}} J_{b}^{a} \frac{\partial w_{a} \psi(b_{c})}{\partial x_{a}^{k}} \right],$ where the current J^{k} is defined according to

Eniour (c) piour (c)]



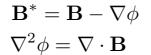


Current directions on SPH+MHD

• generalised Euler potentials method

$$\begin{split} \mathbf{B} &= \nabla \alpha_1 \times \nabla \beta_1 + \nabla \alpha_2 \times \nabla \beta_2 + \nabla \alpha_3 \times \nabla \beta_3 \\ \mathbf{B} &= \nabla \alpha_1 \times \nabla X_0 + \nabla \alpha_2 \times \nabla Y_0 + \nabla \alpha_3 \times \nabla Z_0 \\ \text{Allows remapping procedure} \quad \alpha_1^* &= \alpha_1 \nabla \beta_1 \quad \alpha_2^* = \alpha_2 \nabla \beta_2 \\ \text{(reconnection "by hand"):} \quad [\beta_1^*, \beta_2^*, \beta_3^*] &= [X_i, Y_i, Z_i] \end{split}$$

• exact implementation of projection method for div B



was tried by PM05, but with only approximate solution. With exact method might be better

• two fluid implementation (ions/neutrals)

completely independent of the ideal MHD implementation

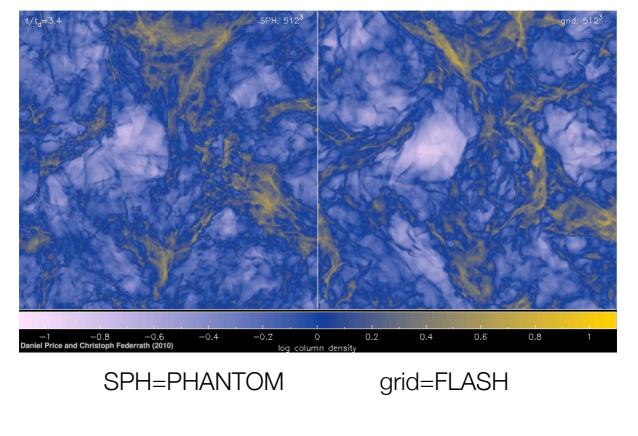
why haven't we finished all this yet?

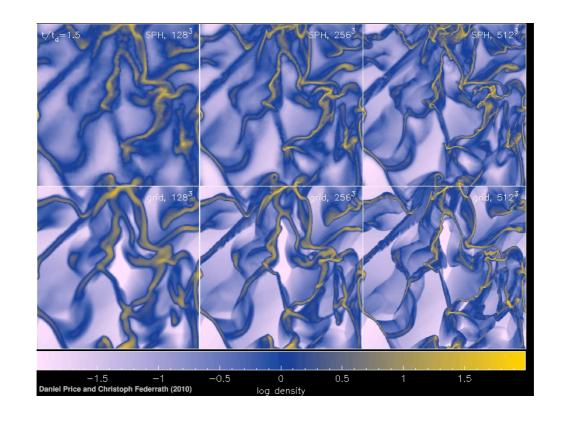
Padoan et al. (2007):

"Numerical simulations can ... account for ... turbulence in ... star formation only if they can generate an inertial range of turbulence, which requires both low numerical diffusivity and large numerical resolution. Furthermore... the magnetic field cannot be neglected"

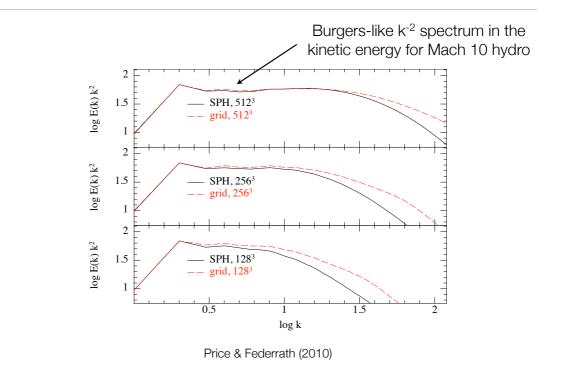
"SPH simulations of large scale star formation to date fail in all three fronts: numerical diffusivity, numerical resolution, and presence of magnetic fields. This should cast serious doubts on the value of comparing predictions based on SPH simulations with observational data (see also Agertz et al. 2006)."

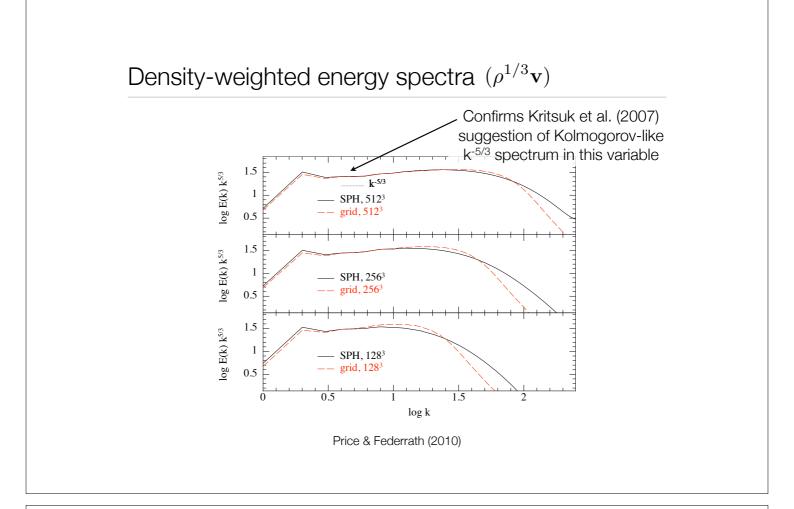
Comparison of Mach 10, hydro turbulence



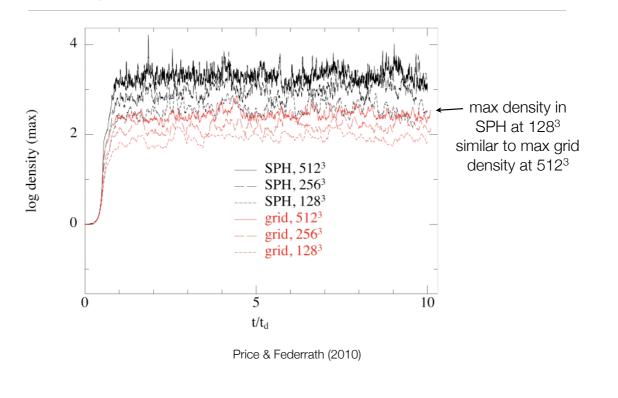


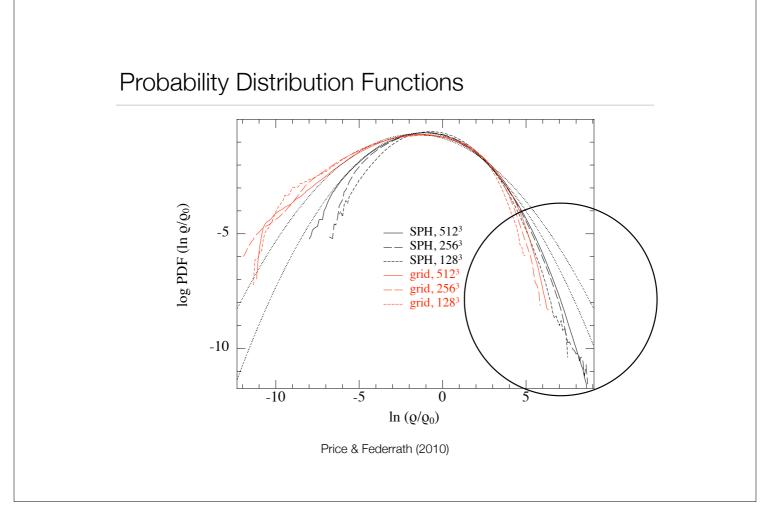
Kinetic energy spectra

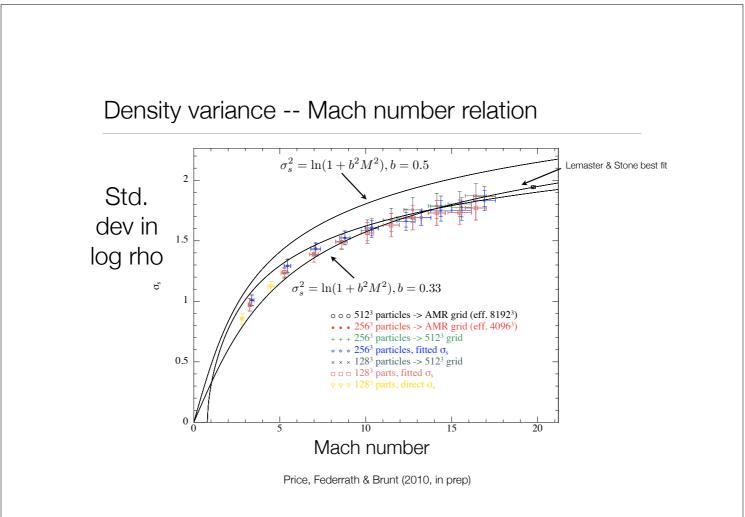


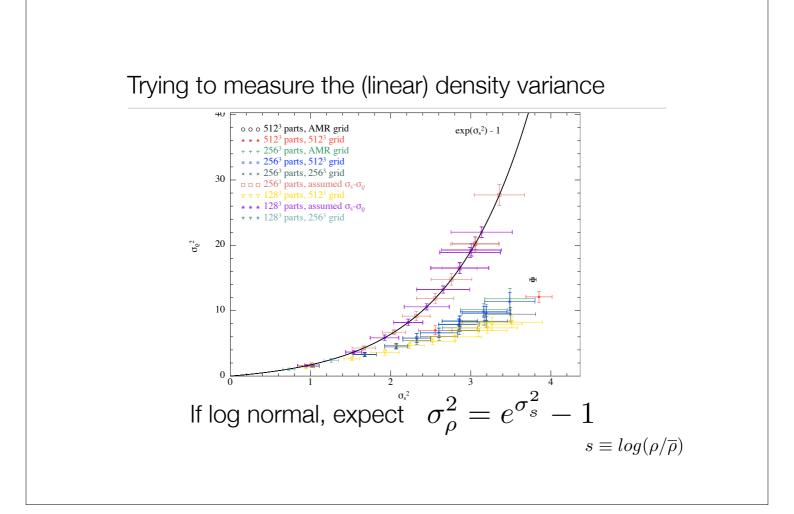


Density resolution

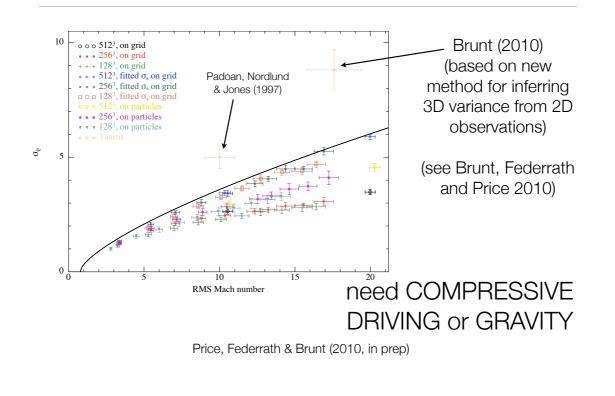








Comparison to observations



Conclusions

- being a television presenter is easier than getting MHD in SPH to work
- MHD in SPH would work if people stopped making unsubstantiated swipes* at SPH
- Magnetic fields can significantly change star formation even at supercritical field strengths, so we need MHD in SPH
- SPH and grid codes agree very well on the statistics of turbulence when the resolutions are comparable: nparts = ncells to get similar spectra, but SPH much better at resolving dense structures.
- The standard-deviation-- Mach number relation in supersonic turbulence seems robust up to Mach 20, but observed density variances are much higher than can be produced with solenoidally-driven turbulence alone

*defined as any paper where the criticism is based purely on a citation to Agertz et al. (2006)