

Stable

Ergodicity

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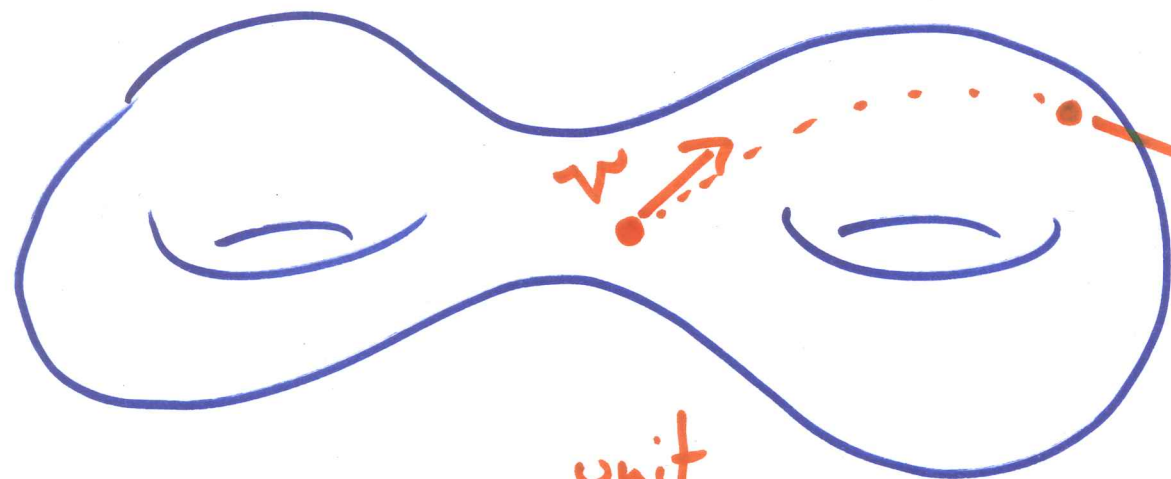


Monash University

Hopf (1939):

The geodesic flow on a  
negatively curved manifold  
is ergodic.

S



unit  
vector

$\phi_t(v)$

$$M = \underbrace{T^1 S}_{\text{unit vectors}}$$

$$\psi_t : M \rightarrow M \quad \text{flow}$$

The Hopf Argument

for the cat map

$$A : \mathbb{T}^2 \rightarrow \mathbb{T}^2$$

$$A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}.$$

Say  $\phi : \mathbb{T}^2 \rightarrow \mathbb{R}$  is (uniformly) continuous.

We want to show the forward Birkhoff average

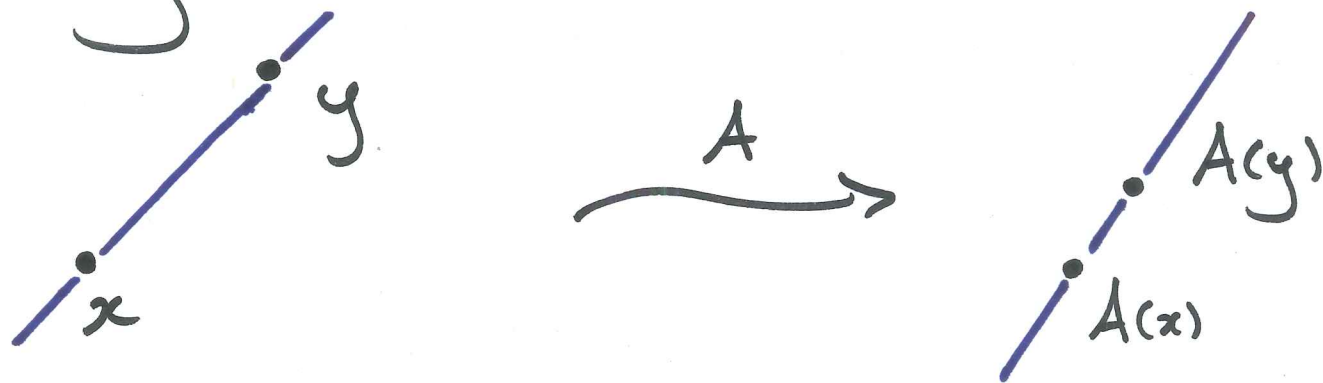
$$\phi^+(x) = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^N \phi(A^k(x)) \quad \text{is constant a.e.}$$

$A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$  has eigs  $\lambda^{-1} < 1 < \lambda$

and a splitting  $TM = E^s \oplus E^u$  given by the eigenspaces.

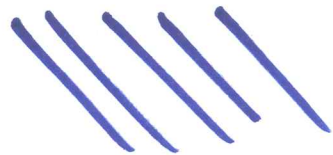
If  $x$  and  $y$  are on the same stable leaf,

then

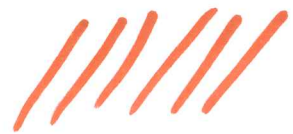


$$d(A^k x, A^k y) \rightarrow 0 \Rightarrow |\phi(A^k x) - \phi(A^k y)| \rightarrow 0 \Rightarrow \phi^+(x) = \phi^+(y)$$

$\phi^+$  is constant on stable leaves



$\phi^+$  is constant on unstable leaves

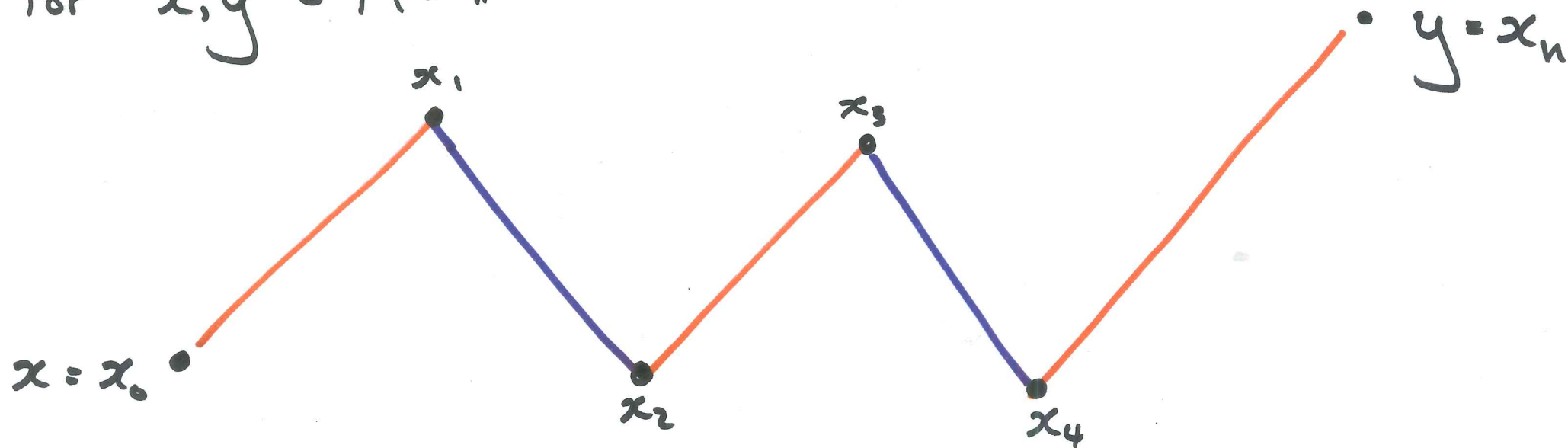


and  $\phi^+ = \phi^-$  almost everywhere.

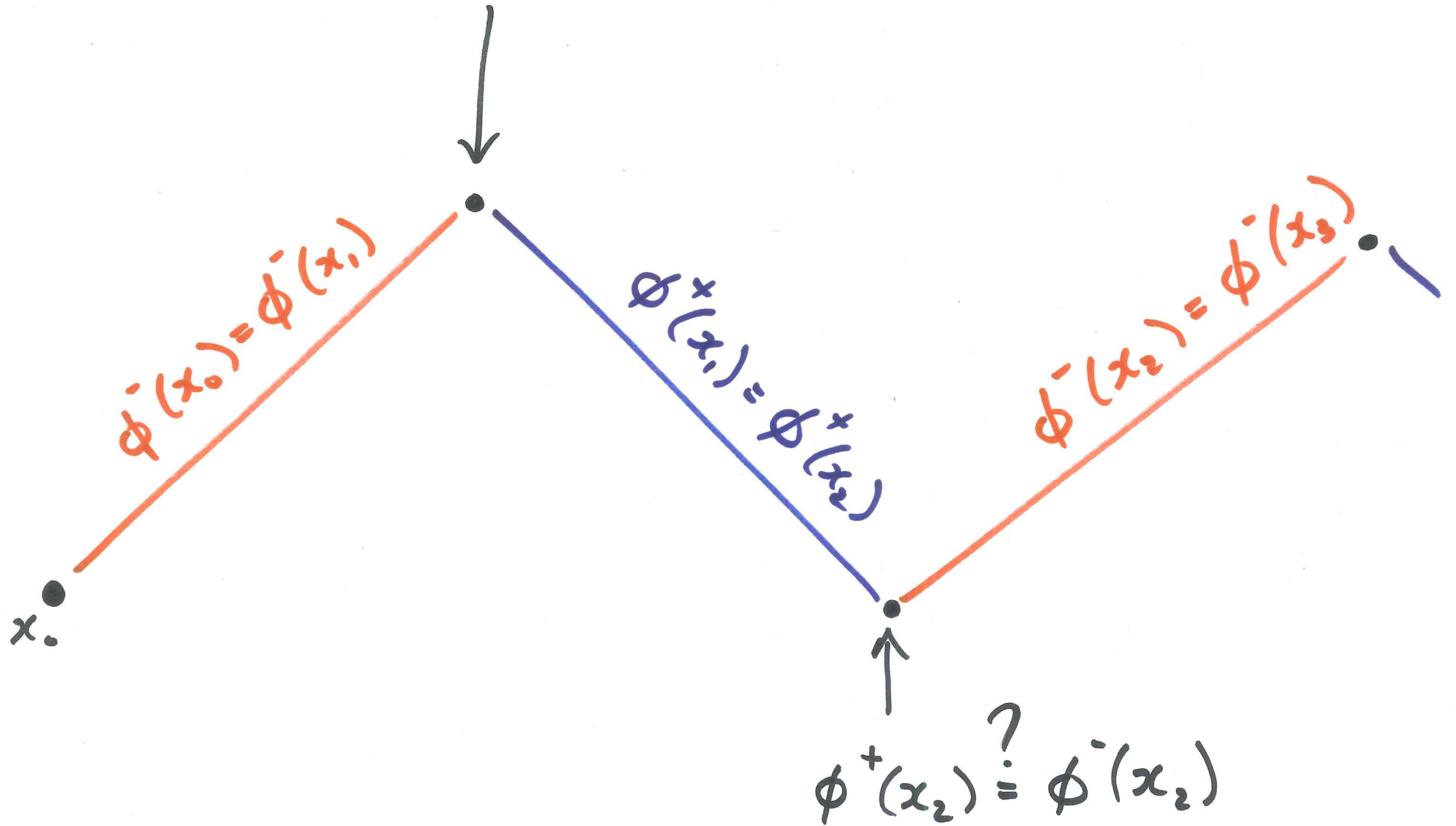
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First, a non-proof that  $\phi^+$  is constant a.e.

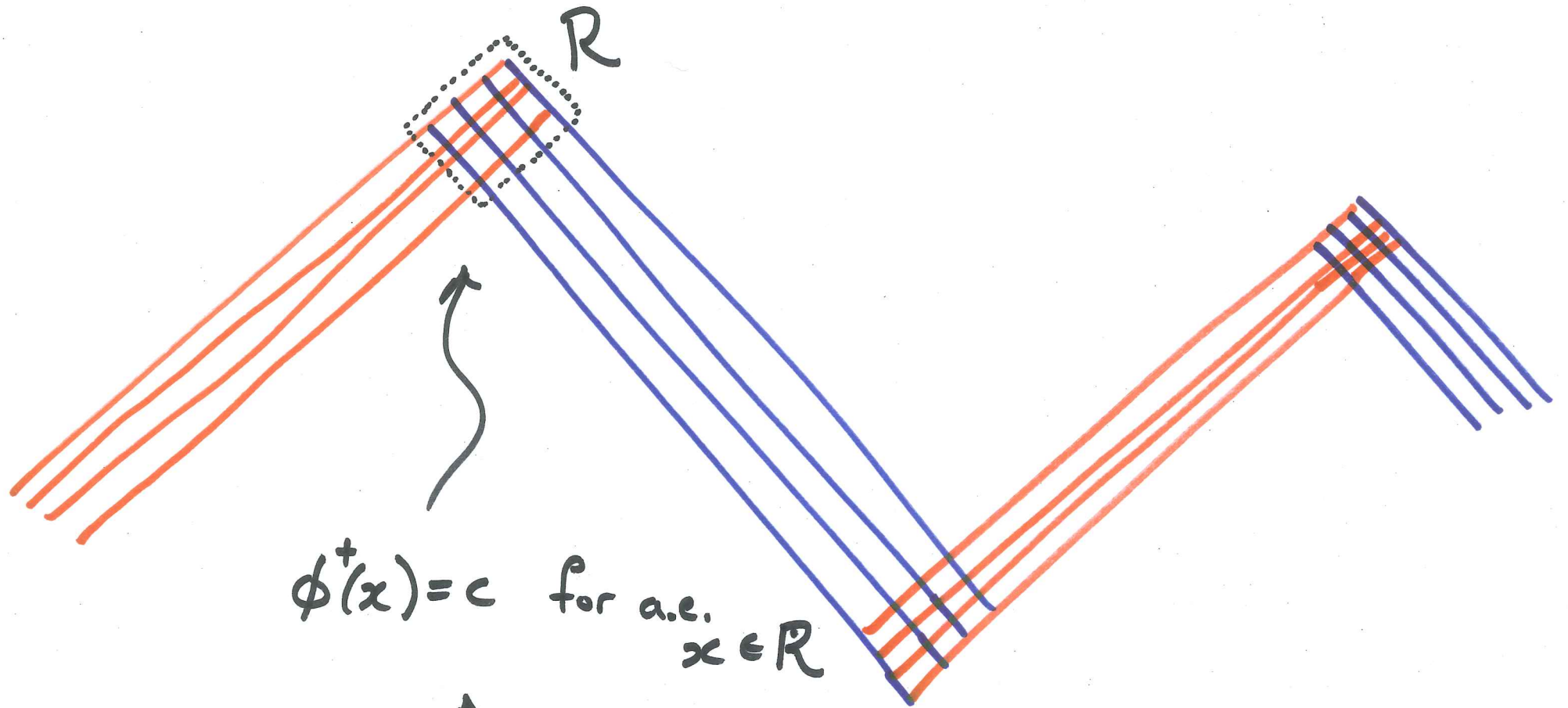
For  $x, y \in M = \mathbb{T}^2$



$$\phi^-(x_1) \stackrel{?}{=} \phi^+(x_1)$$



Use Fubini's Theorem



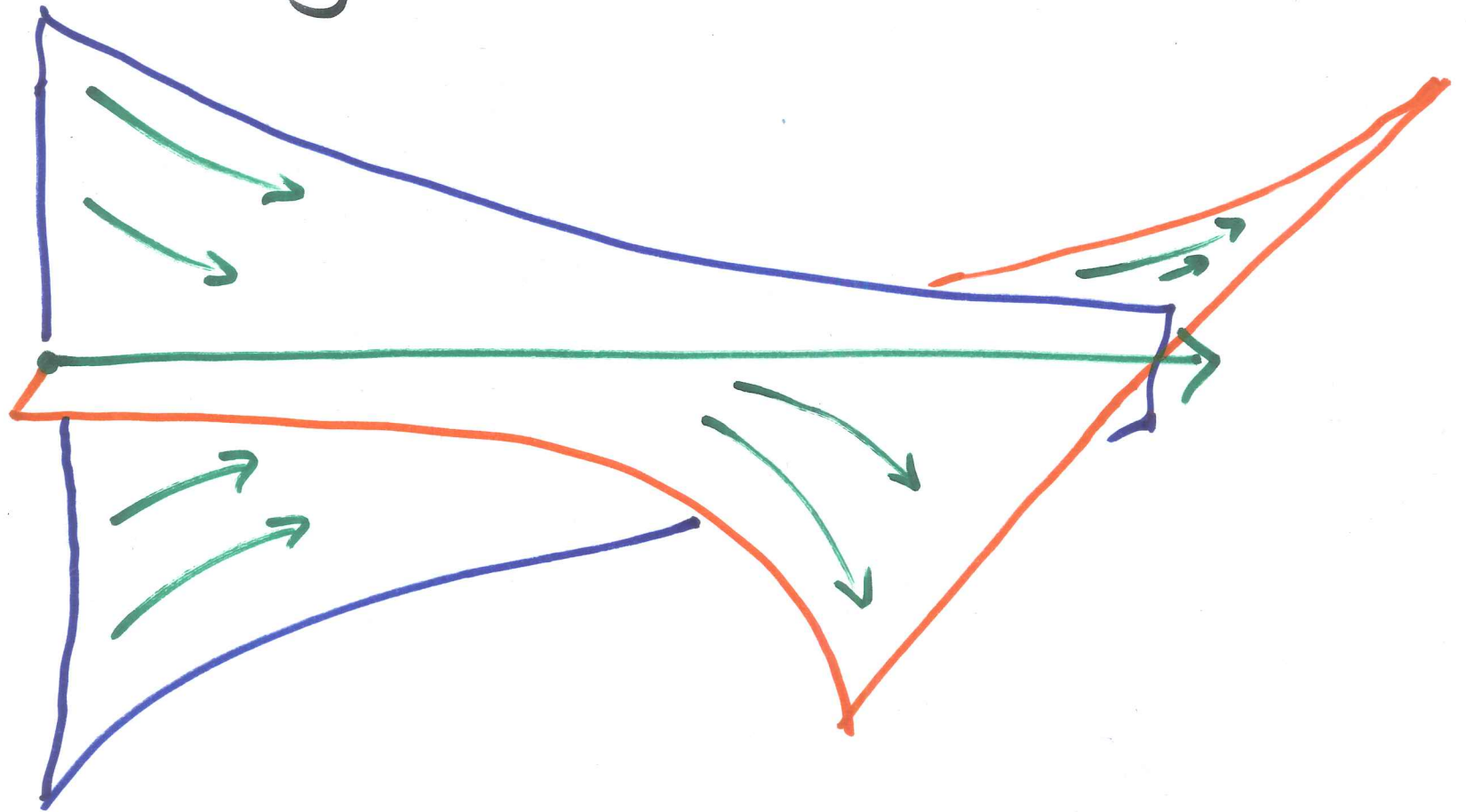
$$\phi^+(x) = c \text{ for a.e. } x \in \mathbb{R}$$



$$\phi^-(x) = c \text{ for a.e. } x \in \mathbb{R}$$



A similar argument ~~is~~ works  
for geodesic flows.



Smale (1961):

Is the cat map

stably ergodic?

Anosov (1962, 1963): Yes!

Def A diffeo  $f: M \rightarrow M$  is Anosov

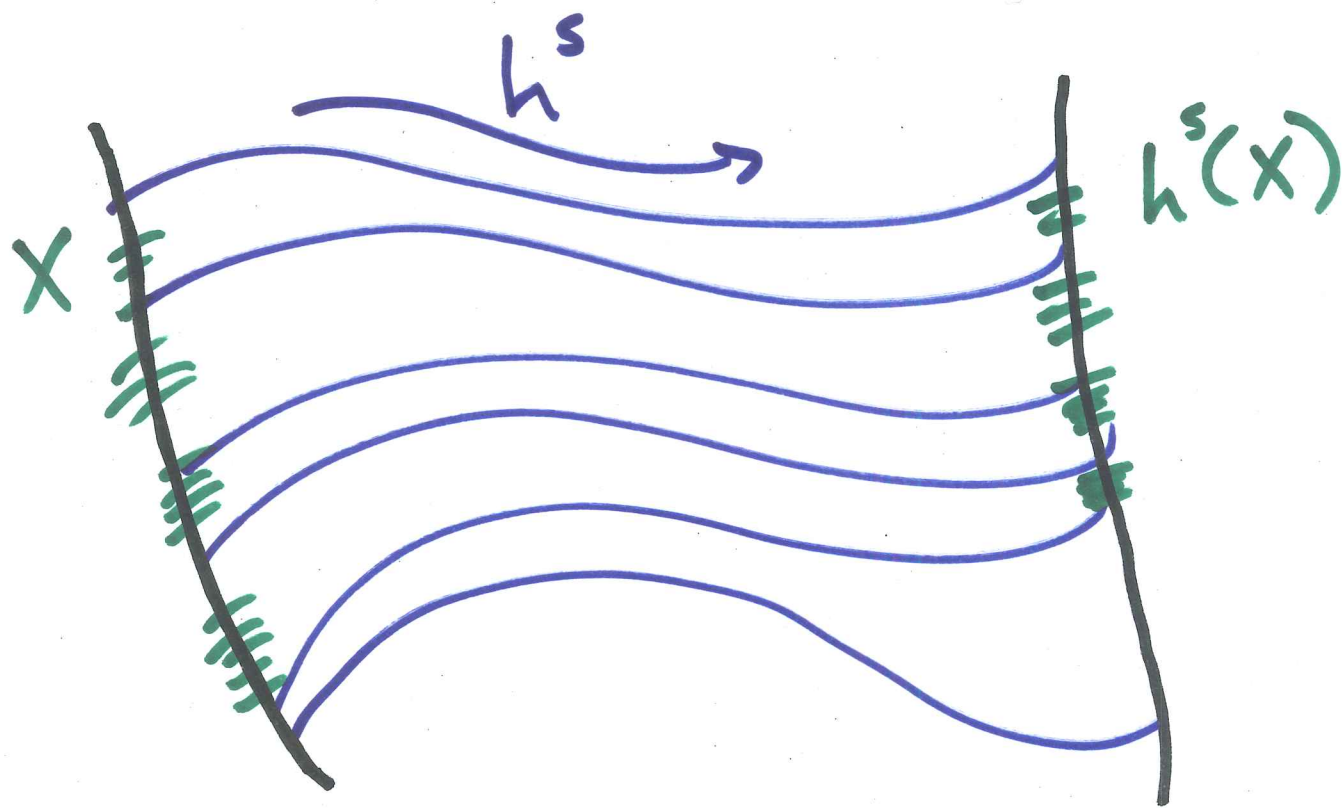
if  $\exists$  an inv't splitting

$$TM = E^s \oplus E^u$$

┌──────────┐      ┌──────────┐  
contracting      expanding

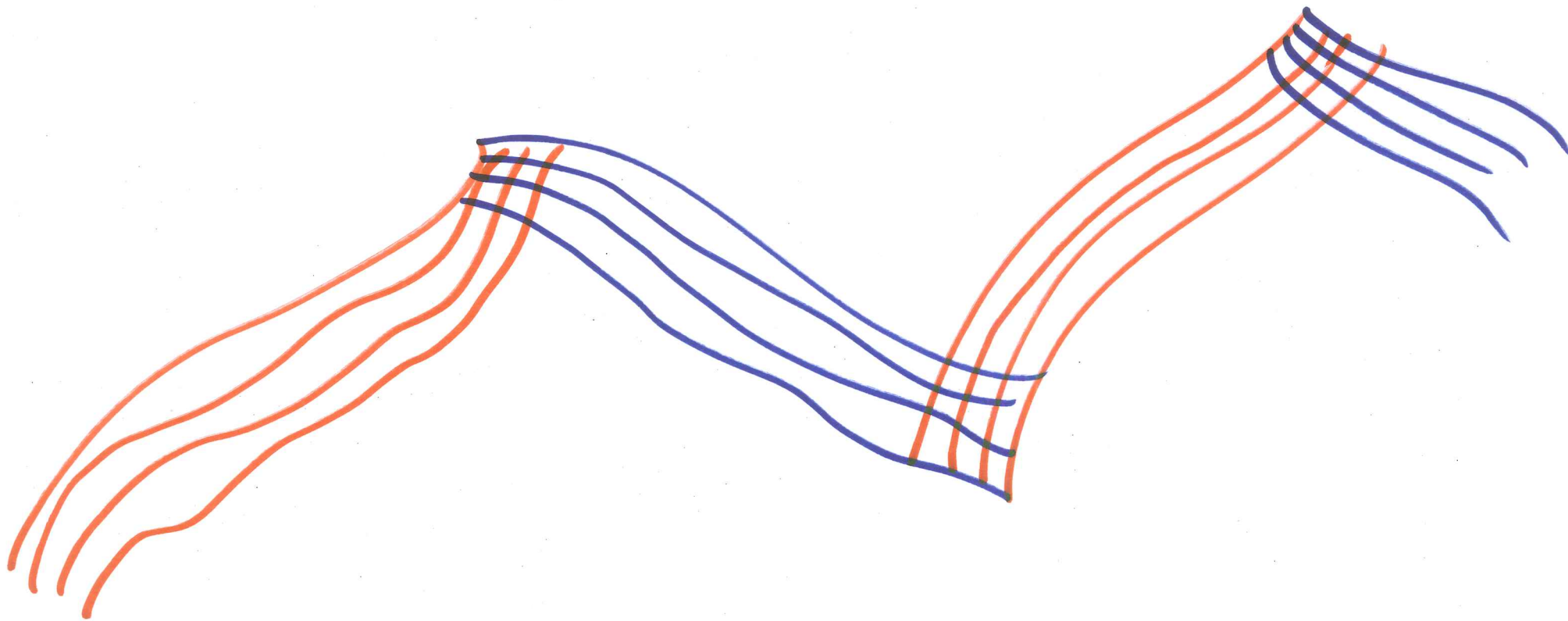
$$\exists \sigma < 1 \text{ s.t. } \begin{aligned} \|Df v\| &\leq \sigma \|v\| && \text{for } v \in E^s \\ \|Df^{-1} v\| &\leq \sigma \|v\| && \text{for } v \in E^u \end{aligned}$$

Thm (Anosov) For a  $C^2$  Anosov diffeo or flow,  
the stable and unstable foliations  
have absolutely continuous holonomies.



$X$  has meas zero  $\iff h^s(X)$  has meas zero

Thm (Anosov) A volume preserving  $C^2$   
Anosov system is ergodic.



Fact: Every vol. pres.  $C^2$  diffeo  
which is  $C^1$ -close to the cat map  
is ergodic.

OPEN QUESTION: If a vol. pres.  $\underline{\underline{C^1}}$  diffeo  
is  $C^1$ -close to the cat map,  
is it ergodic?

For the rest of the talk,

a vol. pres.  $C^2$  diffeo is

stably ergodic

if every vol. pres.  $C^2$  diffeo in  
a  $C^1$ -neighbourhood is ergodic.

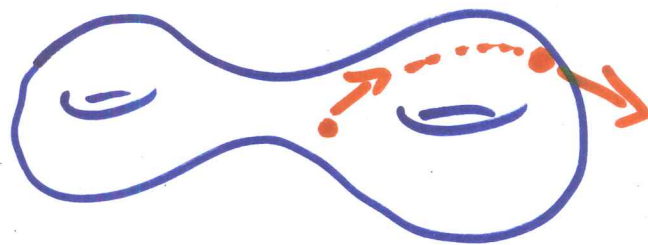
From 1963 to 1994,

Anosov systems were the only  
known stably ergodic systems.



Grayson-Pugh-Shub 1994:

Let  $\psi_t: M \rightarrow M$  be the geodesic flow  
of a surface of curvature  $\kappa = -1$



The time-1 map  $f = \psi_1: M \rightarrow M$

is stably ergodic as a diffeo.

Two key concepts in the proof:

1) A diffeo  $f: M \rightarrow M$  is partially hyperbolic if there is an invariant splitting

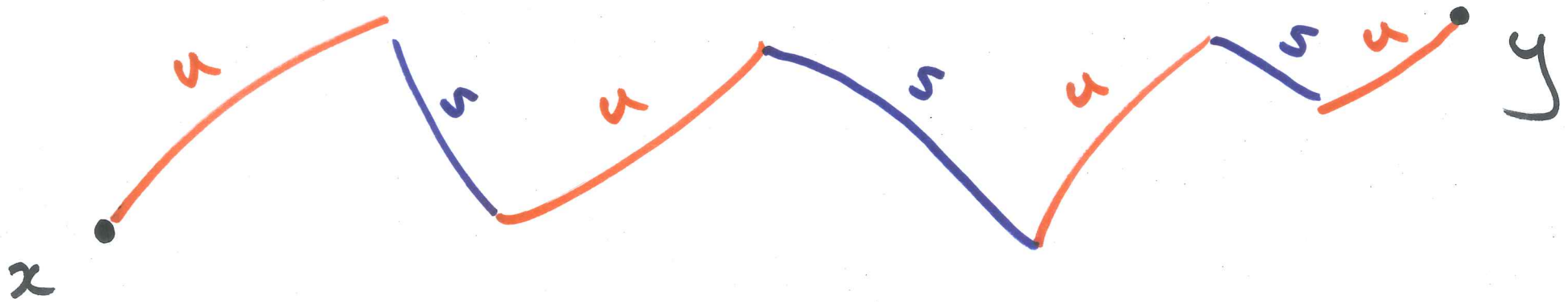
$$TM = E^s \oplus E^c \oplus E^u$$

.....  
strongly contracting                      no strong contraction or expansion                      strongly expanding

Example: the time-1 map of an Anosov flow

Two key concepts in the proof:

2) A partially hyperbolic diffeo is accessible  
if for any  $x, y \in M$   
there is a path



Grayson-Pugh-Shub showed that any  $f: M \rightarrow M$   
near the time-1 map is both  
partially hyperbolic and accessible.

Then did lots of analysis to show  $f$  is ergodic.

This work lead to the Pugh-Shub  
conjectures.

# Pugh-Shub Conjectures

In the space of vol. pres. partially hyperbolic  
 $C^r$  diffeos ( $r \geq 2$ ):

- 1) ergodicity  $\stackrel{?}{\Leftrightarrow}$   $C^r$ -open and  $C^r$ -dense
- 2) accessibility  $\stackrel{?}{\Leftrightarrow}$   $C^r$ -open and  $C^r$ -dense
- 3) accessibility implies ergodicity

For  $C^2$  vol. pres. partially hyperbolic systems:

Rodriguez Hertz - Rodriguez Hertz - Ures 2008:

if  $\dim E^c = 1$ , then ergodicity is  $C^1$ -open  
and  $C^r$ -dense ( $r \geq 2$ )

Burns - Wilkinson 2010:

accessibility & center bunching  $\Rightarrow$  ergodicity

Avila - Crovisier - Wilkinson, preprint in 2014:

ergodicity is  $C^1$ -open and  $C^1$ -dense

# Converse Results

(based on work of Arbieto-Matheus)

For diffeos:

In dim 2

(Mañé-Bochi)  
stably ergodic  $\iff$  Anosov

In dim 3

stably ergodic  $\implies$  (weakly) partially hyperbolic  
(Díaz - Pujals - Ures)

In dim  $\geq 4$

stably ergodic  $\implies$  volume partially hyperbolic  
(Bonatti - Díaz - Pujals)

Questions:

What types of partially hyperbolic systems exist?

What are the non-ergodic ones?

What are their ergodic decompositions?



Consider linear maps on the 3-torus  $\mathbb{T}^3$

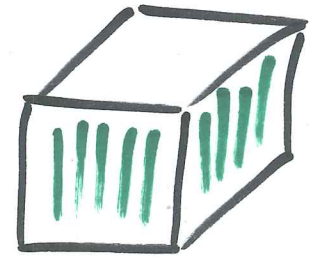
Example:

$$\begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

eigs

$\lambda^{-1}$	1	$\lambda$
s	c	u

$A \times \text{id}$  on  $\mathbb{T}^2 \times S^1$



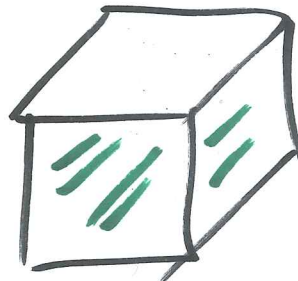
$\uparrow E^c$

Example:

$$\begin{pmatrix} 2 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

eigs

0.198	1.55	3.24
s	c	u



$\uparrow E^c$  has irrat slope

Thm (H, 2009)

Every partially hyperbolic diffeo on  $\mathbb{T}^3$   
is leaf conjugate to a linear map.

(After a  $C^0$  change of coordinates on  $\mathbb{T}^3$ ,  
 $f$  is given by a ~~leaf~~ linear map  
composed with some sliding along the  
 $E^c$  direction.)

Thm (H-Ures, 2013)

If  $f: \mathbb{T}^3 \rightarrow \mathbb{T}^3$  is vol pres, partially hyperbolic  
and homotopic to an Anosov diffeo  $A$ ,

then either

1)  $f$  is ergodic, or

2)  $f$  is non-ergodic and topologically  
conjugate to  $A$  ( $\exists h$  so that  
 $f = h^{-1} A h$ )

We don't know if case 2 exists.

## Thm (H-Potrie, 2014)

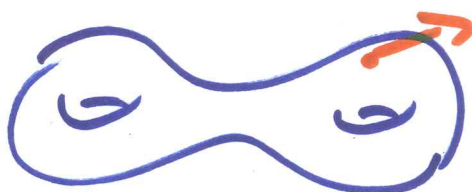
Every partially hyperbolic diffeo on a 3-mfld with solvable fundamental group is leaf conjugate to

- 1) an Anosor diffeo on  $\mathbb{T}^3$ ,
- 2) a skew product, or
- 3) the time-1 map of an Anosor flow.

This allowed me to give a classification of all of the accessibility classes of these diffeos.

Except for the open question on  $\mathbb{T}^3$ , these accessibility classes coincide with the ergodic decomposition of the system.

In recent work with  
Bonatti, Gogolev, & Potrie,  
we've found new stably ergodic  
partially hyperbolic systems on unit  
tangent bundles



which are not homotopic to the  
time-1 maps of Anosov flows.